

4

~~ERRATA~~ ERRATA:

p.12 $(SAT)_{\alpha \dots \alpha} = \dots \sum_{\alpha} S_{[\alpha \dots T \dots \alpha]}$ (obvious from index conventions)
↑ should be β 's

p.16 line 1 p -forms \rightarrow $(n-p)$ -forms

p.28 $\pi(1, \dots, n) = (\pi^{-1}(1), \dots, \pi^{-1}(n))$

$(1, 2, 3, 4) \rightarrow (4, 3, 2, 1) = (\pi^{-1}(1), \pi^{-1}(2), \pi^{-1}(3), \pi^{-1}(4))$
 $= (\pi(4), \pi(3), \pi(2), \pi(1))$

$4 = \pi(1), \quad 1 = \pi^{-1}(4)$

thanks John Bruno.

SO THIS WEEK WE FINISH OFF LINEAR ALGEBRA (for now)

all we need to remember about " \wedge ": $\omega^{\alpha_1 \dots \alpha_p} \wedge \omega^{\alpha_{p+1} \dots \alpha_{p+q}} = \omega^{\alpha_1 \dots \alpha_{p+q}}$

Then: p -form $S = \frac{1}{p!} S_{\alpha_1 \dots \alpha_p} \omega^{\alpha_1 \dots \alpha_p} = S_{|\alpha_1 \dots \alpha_p|} \omega^{\alpha_1 \dots \alpha_p}$

q -form $T = \frac{1}{q!} T_{\alpha_1 \dots \alpha_q} \omega^{\alpha_1 \dots \alpha_q} = T_{|\alpha_1 \dots \alpha_q|} \omega^{\alpha_1 \dots \alpha_q}$

$(p+q)$ -form $S \wedge T = \frac{1}{p!q!} S_{\alpha_1 \dots \alpha_p} T_{\alpha_{p+1} \dots \alpha_{p+q}} \underbrace{\omega^{\alpha_1 \dots \alpha_p} \wedge \omega^{\alpha_{p+1} \dots \alpha_{p+q}}}_{= \omega^{\alpha_1 \dots \alpha_{p+q}}}$

$= \frac{1}{p!q!} S_{[\alpha_1 \dots \alpha_p T_{\alpha_{p+1} \dots \alpha_{p+q}}]} \omega^{\alpha_1 \dots \alpha_{p+q}}$
 $+ \sum_{\beta_1 \dots \beta_{p+q}} \frac{1}{(p+q)!} S_{\beta_1 \dots \beta_p} T_{\beta_{p+1} \dots \beta_{p+q}}$

$= \frac{1}{p!q!} \sum_{|\alpha_1 \dots \alpha_{p+q}|} S_{\beta_1 \dots \beta_p} T_{\beta_{p+1} \dots \beta_{p+q}} \omega^{\alpha_1 \dots \alpha_{p+q}}$

$= \sum_{|\alpha_1 \dots \alpha_{p+q}|} S_{|\beta_1 \dots \beta_p|} T_{|\beta_{p+1} \dots \beta_{p+q}|} \omega^{\alpha_1 \dots \alpha_{p+q}}$

$[SAT]_{|\alpha_1 \dots \alpha_{p+q}|}$

$\left(= \frac{(p+q)!}{p!q!} S_{[\alpha_1 \dots \alpha_p T_{\alpha_{p+1} \dots \alpha_{p+q}}]} \right)$

So let's do some examples.

oops, not much room here.

$$\underline{n=3} : \dim \Lambda^1(V^*) = 3 \quad \dim \Lambda^2(V^*) = 3 \quad \dim \Lambda^3(V^*) = 1 \quad (V = E^3)$$

$$(p,q) = (1,1)$$

$$\begin{aligned} B \wedge C &= (B_i \omega^i) \wedge (C_j \omega^j) = B_i C_j \omega^{ij} = 2 B_{[ij]} \omega^{[ij]} \\ &= (B_2 C_3 - B_3 C_2) \omega^{23} + (B_3 C_1 - B_1 C_3) \omega^{31} + (B_1 C_2 - B_2 C_1) \omega^{12} \\ &\quad \text{"}\epsilon_{1ij} B_i C_j\text{"} \quad \text{"}\epsilon_{2ij} B_i C_j\text{"} \quad \text{"}\epsilon_{3ij} B_i C_j\text{"} \\ &= (B \times C)_1 \omega^{23} + (B \times C)_2 \omega^{31} + (B \times C)_3 \omega^{12} \end{aligned}$$

$$\begin{aligned} \text{"}B \times C\text{"} &= (*B \wedge C) \equiv \delta_{ik} \epsilon^{ljk} B_j C_k \omega^i && \text{"}\epsilon_{ijk} B_i C_j C_k\text{"} \\ * \omega^i &= \frac{1}{2} \delta^{ij} \epsilon_{jke} \omega^{ke} && (*B \wedge C)_i * \omega^i \end{aligned}$$

$$\begin{aligned} p,q = (1,2) \quad A \wedge J &= (A_i \omega^i) \wedge \left(\frac{1}{2} J_{jk} \omega^{jk} \right) = \left(A_1 \underbrace{J_{23}}_{(*J)^1} + A_2 \underbrace{J_{31}}_{(*J)^2} + A_3 \underbrace{J_{12}}_{(*J)^3} \right) \omega^{123} \\ &= A_i (*J)^i \omega^{123} \\ *J^i &= \frac{1}{2} \epsilon^{ijk} J_{jk} \end{aligned}$$

Now A, B, C 1-forms ($J = B \wedge C$):

$$\begin{aligned} A \wedge (B \wedge C) &= [A_1 (B_2 C_3 - B_3 C_2) + \dots] \omega^{123} = \underbrace{A_i (*B \wedge C)^i}_{\text{"}A \cdot (B \times C)\text{"}} \omega^{123} \\ &= \begin{vmatrix} A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \\ C_1 & C_2 & C_3 \end{vmatrix} \omega^{123} \end{aligned}$$

You see the star operator is forced on us if we want to represent our results in the simplest way.

$$\underline{n=4} : \dim \Lambda^1(V^*) = 4, \quad \dim \Lambda^2(V^*) = 6, \quad \dim \Lambda^3(V^*) = 4, \quad \dim \Lambda^4(V^*) = 1$$

$V = M^4$ (Minkowski spacetime) $\alpha = 0, 1, 2, 3$ and $i = 1, 2, 3$.

$$\begin{aligned} (p,q) = (1,1) \quad B \wedge C &= (B_0 \omega^0 + B_i \omega^i) \wedge (C_0 \omega^0 + C_j \omega^j) \\ &= (B_i C_0 - C_i C_0) \omega^{i0} + \underbrace{B_{[ij]} C_{j]}_{\frac{1}{2} (B \times C)_{ij}} \omega^{ij} \end{aligned}$$

$$(p, a) = (1, 2) \quad A \wedge F = (A_0 \omega^0 + A_i \omega^i) \wedge \left(\underbrace{F_{i0}}_{E_i} \omega^{i0} + \frac{1}{2} \underbrace{F_{ij}}_{\epsilon_{ijk} B^k} \omega^{ij} \right)$$

$$= A_0 B^i \left(\frac{1}{2} \epsilon_{ijk} \omega^{ijk} \right) + A_i E_j \omega^{ij0} + (A_1 F_{23} + A_2 F_{31} + A_3 F_{12}) \omega^{123}$$

$$\underbrace{\left(-\frac{1}{2} \epsilon_{0ijk} \omega^{0ijk} \right)}_{* \omega^i}$$

$$= [A_0 B^i + \epsilon^{ijk} A_j E_k] \frac{1}{2} \epsilon_{imn} \omega^{imn} + A_i B^i \omega^{123}$$

$$(p, a) = (2, 2)$$

$$F = E_i \omega^{i0} + \frac{1}{2} B^i \epsilon_{ijk} \omega^{ijk}, \quad G = D_i \omega^{i0} + \frac{1}{2} H^i \epsilon_{ijk} \omega^{ijk}$$

$$F \wedge G = \frac{1}{2} E_i H^e \underbrace{\left(\begin{array}{c} \epsilon_{emn} \omega^{iomn} \\ -\omega^{oimn} \\ \epsilon^{imn} \omega^{0123} \end{array} \right)}_{2 \delta^e_i} + \frac{1}{2} D_i B^e \underbrace{\left(\begin{array}{c} \epsilon_{emn} \omega^{mnio} \\ -\omega^{oimn} \end{array} \right)}$$

$$= - (E_i H^i + D_i B^i) \omega^{0123}$$

$$G = *F \equiv -B_i \omega^{i0} + \frac{1}{2} E^i \epsilon_{ijk} \omega^{ijk}$$

$$F \wedge *F = - (E_i E^i - B_i B^i) \omega^{0123}$$

$$\text{or } F \wedge F = -2 E_i B^i \omega^{0123}$$

$$= \frac{1}{2} F^{\alpha\beta} F_{\alpha\beta} \omega^{0123}$$

$$= \frac{1}{2} F^{\alpha\beta} *F_{\alpha\beta} \omega^{0123}$$

$E^2 - B^2$ and $E \cdot B$ are the only 2 invariants of the EM field under Lorentz transformations.

These examples show the utility of introducing the star operation as done on pp 16-17.

The star operation has 2 parts.

One uses the epsilon-indicators to go from a p-form to an (n-p)-vector (or p-vector to an (n-p)-form)

$$T_{\alpha_1 \dots \alpha_p} \rightarrow *T^{\alpha_{p+1} \dots \alpha_n} = \frac{1}{p!} T_{\alpha_1 \dots \alpha_p} \epsilon^{\alpha_1 \dots \alpha_p \alpha_{p+1} \dots \alpha_n} \quad (\text{natural dual})$$

This we can do without a metric. But one needs a metric to get back to a form, which can be obtained in this case by lowering all the indices. BUT we get into trouble if we raise and lower indices on the ϵ -indicators because they are "not the components of tensors."

So we have to use the η -tensors instead:

$$T_{\alpha_1 \dots \alpha_p} \rightarrow *T^{\alpha_{p+1} \dots \alpha_n} = \frac{1}{p!} T_{\alpha_1 \dots \alpha_p} \eta^{\alpha_1 \dots \alpha_p \alpha_{p+1} \dots \alpha_n} \quad (\text{metric dual})$$

$$*T^{\alpha_{p+1} \dots \alpha_n} = \frac{1}{p!} T_{\alpha_1 \dots \alpha_p} \eta^{\alpha_1 \dots \alpha_p \alpha_{p+1} \dots \alpha_n}$$

* is a linear operation so

$$*T = * \left(\frac{1}{p!} T_{\alpha_1 \dots \alpha_p} \omega^{\alpha_1 \dots \alpha_p} \right) = \frac{1}{p!} T_{\alpha_1 \dots \alpha_p} * \omega^{\alpha_1 \dots \alpha_p}$$

$$\text{but } *T = \frac{1}{(n-p)!} *T^{\alpha_{p+1} \dots \alpha_n} \omega^{\alpha_{p+1} \dots \alpha_n} = \frac{1}{p!} T_{\alpha_1 \dots \alpha_p} \frac{1}{(n-p)!} \eta^{\alpha_1 \dots \alpha_p \alpha_{p+1} \dots \alpha_n} \omega^{\alpha_{p+1} \dots \alpha_n}$$

$$\therefore * \omega^{\alpha_1 \dots \alpha_p} = \frac{1}{(n-p)!} \eta^{\alpha_1 \dots \alpha_p \alpha_{p+1} \dots \alpha_n} \omega^{\alpha_{p+1} \dots \alpha_n} \equiv \eta^{\alpha_1 \dots \alpha_p}$$

$$*T = \frac{1}{p!} T_{\alpha_1 \dots \alpha_p} \eta^{\alpha_1 \dots \alpha_p}$$

$$p=0, \text{ T function} \quad *T = T *1 = \frac{1}{n!} T \eta_{\alpha_1 \dots \alpha_n} \omega^{\alpha_1 \dots \alpha_n}$$

$$= T \eta \quad \text{ie}$$

$$\begin{aligned} *1 &= \eta \\ * \eta &= 1 \end{aligned}$$

$$p=n, \quad *T = \frac{1}{n!} T_{\alpha_1 \dots \alpha_n} \eta^{\alpha_1 \dots \alpha_n}$$

$$* \eta = \frac{1}{n!} \eta_{\alpha_1 \dots \alpha_n} \eta^{\alpha_1 \dots \alpha_n} = 1$$

Now what is $**T$?

$$\begin{aligned}
 *(*T)_{\beta_1 \dots \beta_p} &= \frac{1}{(n-p)!} \underbrace{(*T_{\alpha_1 \dots \alpha_{n-p}})}_{\frac{1}{p!} T_{\gamma_1 \dots \gamma_p} \eta^{\delta_1 \dots \delta_p}_{\alpha_1 \dots \alpha_{n-p}}} \eta^{\alpha_1 \dots \alpha_{n-p}}_{\beta_1 \dots \beta_p} \\
 &= \frac{1}{p!(n-p)!} T_{\gamma_1 \dots \gamma_p} \eta^{\delta_1 \dots \delta_p}_{\alpha_1 \dots \alpha_{n-p}} \underbrace{\eta_{\alpha_1 \dots \alpha_{n-p}}}_{\eta_{\beta_1 \dots \beta_p} \alpha_1 \dots \alpha_{n-p}} \underbrace{\eta_{\beta_1 \dots \beta_p}}_{(-1)^{p(n-p)}} \\
 &= (-1)^{\frac{n-s}{2}} |\det g|^{-1/2} |\det g|^{1/2} \underbrace{\delta_{\beta_1 \dots \beta_p \alpha_1 \dots \alpha_{n-p}}}_{\delta_{\beta_1 \dots \beta_p} \alpha_1 \dots \alpha_{n-p}} \underbrace{p! T_{\beta_1 \dots \beta_p}}_{(n-p)! \delta_{\beta_1 \dots \beta_p}^{\delta_1 \dots \delta_p}} \\
 &= (-1)^{\frac{n-s}{2}} (-1)^{p(n-p)} T_{\beta_1 \dots \beta_p}
 \end{aligned}$$

$** = (-1)^{\frac{n-s}{2}} (-1)^{p(n-p)} \text{id}$

S, T p -forms: $S \wedge *T = (?) \eta$

$$\begin{aligned}
 S \wedge *T &= \left(\frac{1}{p!} S_{\alpha_1 \dots \alpha_p} \omega^{\alpha_1 \dots \alpha_p} \right) \wedge \left(\frac{1}{p!} T_{\beta_1 \dots \beta_p} \eta^{\beta_1 \dots \beta_p} \right) \\
 &= \frac{1}{(p!)^2} S_{\alpha_1 \dots \alpha_p} T_{\beta_1 \dots \beta_p} \underbrace{\omega^{\alpha_1 \dots \alpha_p} \wedge \eta_{\beta_1 \dots \beta_p}}_{\frac{1}{(n-p)!} \underbrace{\eta_{\beta_1 \dots \beta_p} \beta_{p+1} \dots \beta_n}} \underbrace{\omega^{\alpha_1 \dots \alpha_p \beta_{p+1} \dots \beta_n}}_{\in \alpha_1 \dots \alpha_p \beta_{p+1} \dots \beta_n} \\
 &= \frac{1}{(p!)^2} S_{\alpha_1 \dots \alpha_p} T_{\beta_1 \dots \beta_p} \underbrace{\eta_{\beta_1 \dots \beta_p} \beta_{p+1} \dots \beta_n}_{(n-p)! \delta_{\beta_1 \dots \beta_p}^{\alpha_1 \dots \alpha_p}} \omega^{\alpha_1 \dots \alpha_p \beta_{p+1} \dots \beta_n} \\
 &= \delta_{\beta_1 \dots \beta_p}^{\alpha_1 \dots \alpha_p} \eta \\
 &= \left(\frac{1}{p!} S_{\alpha_1 \dots \alpha_p} T^{\alpha_1 \dots \alpha_p} \right) \eta \\
 &\equiv \langle S, T \rangle
 \end{aligned}$$

$S \wedge *T = \langle S, T \rangle \eta$

$$n=3, V=E, g_{ij}=\delta_{ij}$$

$$p=1 \quad * \omega^i = \frac{1}{2} \epsilon^{ijk} \omega^{jk}$$

$$* \omega^1 = \omega^{23}$$

$$* \omega^2 = \omega^{31}$$

$$* \omega^3 = \omega^{12}$$

$$p=2 \quad * \omega^{ij} = \epsilon^{ijk} \omega_k$$

$$* \omega^{23} = \omega^1$$

$$* \omega^{31} = \omega^2$$

$$* \omega^{12} = \omega^3$$

$$** = 1 \quad \left(\begin{matrix} n=3 \\ s=n \end{matrix} \right)$$

$$\text{vectors: } *[(B^i e_i) \wedge (C^j e_j)] = \epsilon^{ijk} B_j C_k e_i$$

$$*(B \wedge C) = B \times C$$

$$n=4, V=M^4, g_{ij}=\eta_{ij} \quad (-+++)$$

$$g_{00}=-1, g_{ij}=\delta_{ij}$$

$$\eta_{0123} = 1$$

$$\eta^{0123} = -1$$

$$\eta_{0ijk} = \epsilon_{ijk} \quad \eta^{0ijk} = -\epsilon^{ijk}$$

$$p=1 \quad * \omega^\alpha = \eta^{\alpha\beta\gamma\delta} \omega_{\beta\gamma\delta}$$

$$* \omega^0 = \eta^{0123} \omega_{123} = -\omega^{123}$$

$$* \omega^i = \underbrace{\eta^{i0jk}}_{-\eta^{0ijk}} \omega_{0jkl} = -\frac{1}{2} \epsilon^{ijk} \omega^0_{jk}$$

$$* \omega^1 = -\omega^{023}$$

$$* \omega^2 = -\omega^{031}$$

$$* \omega^3 = -\omega^{012}$$

$$p=2 \quad * \omega^{\alpha\beta} = \eta^{\alpha\beta\gamma\delta} \omega_{\gamma\delta}$$

$$* \omega^{i0} = \underbrace{\eta^{i0jk}}_{\epsilon^{ijk}} \omega_{ijkl}$$

$$* \omega^{10} = \omega^{23}$$

$$* \omega^{20} = \omega^{31}$$

$$* \omega^{30} = \omega^{12}$$

$$p=3 \quad * \omega^{\alpha\beta\gamma} = \eta^{\alpha\beta\gamma\delta} \omega_\delta$$

$$* \omega^{123} = \frac{\eta^{1230} \omega_0}{-\eta^{0123} \omega^0} = -\omega^0$$

$$* \omega^{0ij} = \eta^{0ijk} \omega_k = -\epsilon^{ijk} \omega_k$$

$$* \omega^{023} = -\omega^1$$

$$* \omega^{031} = -\omega^2$$

$$* \omega^{012} = -\omega^3$$

Final remarks : "Densities" = "nontensor components of tensors"

Suppose $T = \frac{1}{n!} T_{\alpha_1 \dots \alpha_n} \omega^{\alpha_1 \dots \alpha_n} = T_{1 \dots n} \omega^{1 \dots n}$ is an n -form.

Under a change of basis $e'_\alpha = e_\beta A^{-1\beta}_\alpha$, the component of T in the induced basis of $\Lambda^n(V^*)$ transforms as follows:

$$\tau = T_{1' \dots n'} = (\det A^{-1}) T_{1 \dots n} \quad \text{"scalar density of weight 1"}$$

On the other hand $*T$ is a "scalar", independent of basis

$$*T = T_{1 \dots n} * \omega^{1 \dots n} = T_{1 \dots n} \eta^{1 \dots n} = T_{1 \dots n} (-1)^{\frac{n-1}{2}} g^{-1/2} \underbrace{\epsilon^{1 \dots n}}_1 \operatorname{sgn}(\text{orientation of } e)$$

$$\text{or } \tau = (-1)^{\frac{n-1}{2}} \operatorname{sgn}(\text{orientation}) g^{1/2} \underbrace{(*T)}_{\text{scalar}}$$

this provides the sign to make τ a weight-1 scalar density

"oriented density of weight 1"

$$g'_{..} = A^{-T} g_{..} A^{-1}$$

$$\det g'_{..} = (\det A^{-1})^2 \det g_{..}$$

$$g'^{1/2} \equiv |\det g'_{..}|^{1/2} = |\det A^{-1}| g^{1/2}$$

doesn't change sign with $\det A^{-1}$

can make other densities:

$$\tau_W \equiv (g^{1/2})^W *T$$

"oriented scalar density of weight W "

$$\tau_W' = |\det A^{-1}|^W \tau_W$$

This can also be done with other rank tensors.

For example the "natural dual" of a 2-form on E^3 produces a "vector density"

$$B^i = \frac{1}{2} \epsilon^{ijk} F_{jk}$$

↑
since not a tensor