

Show all work, including mental steps, in a clearly organized way that speaks for itself. Use proper mathematical notation, identifying expressions by their proper symbols (introducing them if necessary), and use arrows and equal signs when appropriate. Always simplify expressions. BOX final short answers. LABEL parts of problem. Keep answers EXACT (but give decimal approximations for interpretation). Indicate where technology is used and what type (Maple, GC).

[You may use technology for row reductions, backsubstitutions and determinants although these may easily be done by hand.]

$$1. v1 = \langle 1, 0, 1, 0 \rangle, v2 = \langle 0, 1, 0, 1 \rangle, v3 = \langle 1, -1, 1, -1 \rangle, v4 = \langle 1, 2, 1, 2 \rangle, \\ v5 = \langle 2, 1, 2, 1 \rangle.$$

a) Express $v5$ as a linear combination of the remaining 4 vectors. [Final answer: $v5 = \dots$]

b) Check that this linear combination that you find actually evaluates to $v5$.

b) Find the independent linear relationships among these 4 vectors. Write out these relationships.

2. Demonstrate that the following vectors are linearly independent: (OPTIONAL)

$$u1 = \langle 1, -1, 0, 0 \rangle, u2 = \langle 1, 1, -1, -1 \rangle, u3 = \langle 0, 0, 1, 1 \rangle, u4 = \langle 1, -1, 1, -1 \rangle.$$

► solution

$$1. a) x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3 + x_4 \vec{v}_4 = \vec{v}_5$$

$$\begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & 2 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 2 \\ 1 \end{bmatrix} \xrightarrow{\text{augment}} \begin{bmatrix} 1 & 0 & 1 & 1 & 2 \\ 0 & 1 & -1 & 2 & 1 \\ 1 & 0 & 1 & 1 & 2 \\ 0 & 1 & -1 & 2 & 1 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - R_1} \begin{bmatrix} 1 & 0 & 1 & 1 & 2 \\ 0 & 1 & -1 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 2 & 1 \end{bmatrix} \xrightarrow{R_4 \rightarrow R_4 - R_2} \begin{bmatrix} 1 & 0 & 1 & 1 & 2 \\ 0 & 1 & -1 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{aligned} x_3 &= t_1 & x_1 + t_1 + t_2 &= 2 \\ x_4 &= t_2 & x_2 - t_1 - 2t_2 &= 1 \\ 0 &= 0 & 0 &= 0 \\ 0 &= 0 & 0 &= 0 \end{aligned}$$

$$\begin{aligned} x_1 &= 2 - t_1 - t_2 \\ x_2 &= 1 + t_1 - 2t_2 \\ x_3 &= t_1 \\ x_4 &= t_2 \end{aligned} \quad \text{or} \quad \vec{x} = \begin{bmatrix} 2 - t_1 - t_2 \\ 1 + t_1 - 2t_2 \\ t_1 \\ t_2 \end{bmatrix}$$

setting $t_1 = 0 = t_2$
would have given
you one particular
way of doing this

$$\text{so } \vec{v}_5 = (2 - t_1 - t_2) \vec{v}_1 + (1 + t_1 - 2t_2) \vec{v}_2 + t_1 \vec{v}_3 + t_2 \vec{v}_4$$

$$b) = (2 - t_1 - t_2) \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + (1 + t_1 - 2t_2) \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} + t_1 \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix} + t_2 \begin{bmatrix} 1 \\ 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} (2 - t_1 - t_2) + t_1 + t_2 \\ 0 + (1 + t_1 - 2t_2) - t_1 + 2t_2 \\ (2 - t_1 - t_2) + t_1 + t_2 \\ 0 + (1 + t_1 - 2t_2) - t_1 + 2t_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 2 \\ 1 \end{bmatrix} \checkmark$$

c) Solve homogeneous linear system instead:

$$x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3 + x_4 \vec{v}_4 = 0 \rightarrow \vec{x} = \begin{bmatrix} -t_1 - t_2 \\ t_1 - 2t_2 \\ t_1 \\ t_2 \end{bmatrix} = t_1 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 0 \end{bmatrix} + t_2 \begin{bmatrix} -1 \\ -2 \\ 1 \\ 1 \end{bmatrix}$$

$$\boxed{\begin{aligned} -\vec{v}_1 + \vec{v}_2 + \vec{v}_3 &= 0 \\ -\vec{v}_1 - 2\vec{v}_2 + \vec{v}_4 &= 0 \end{aligned}} \quad \left(\begin{array}{l} \text{check: } -\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1+1 \\ 0 \\ 1-1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \checkmark \\ -\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} - 2\begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1+1 \\ -2+2 \\ 1+1 \\ -1+1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \checkmark \end{array} \right) \quad \text{coeffs of 2 independent relationships}$$

$$2. \frac{U}{U} = \langle u_1, u_2, u_3, u_4 \rangle = \begin{bmatrix} 1 & 1 & 0 & 1 \\ 1 & 1 & 0 & -1 \\ 0 & -1 & 1 & 1 \\ 0 & -1 & 1 & 1 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 + R_1} \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 2 & 0 & 0 \\ 0 & -1 & 1 & 1 \\ 0 & -1 & 1 & 1 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 + \frac{1}{2}R_2} \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \xrightarrow{R_4 \rightarrow R_4 + \frac{1}{2}R_2} \begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

$\det U = 1 \cdot 2 \cdot 1 \cdot (-2) = -4$ or evaluate using technology. nonzero determinant means they are linearly independent, equivalent to U row reducing to the identity $\begin{bmatrix} R_2 \rightarrow \frac{1}{2}R_2, R_4 \rightarrow -\frac{1}{2}R_4 \end{bmatrix}$

followed by add row operations to eliminate entries above leading 1's] Gauss-Jordan row reduction by technology reduces U to identity, so solution of $U\vec{x} = \vec{0}$ reduces to $\vec{x} = \vec{0}$, ie, no linear relationships exist among these vectors.