

36. Suppose $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ and $B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}$ are 2×2 matrices. For what values of $a, b, c, d, e, f, g,$ and h is the matrix $A + B$ invertible?

$$\det(A + B)$$

Write your solution set using set notation.

$$\det(A + B) = 0$$

37. Suppose $A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$ and $B = \begin{bmatrix} j & k & l \\ m & n & o \\ p & q & r \end{bmatrix}$ are 3×3 matrices. For what values of $a, b, c, d, e, f, g, h, i, j, k, l, m, n, o, p, q,$ and r is the matrix $A + B$ invertible?

$$\det(A + B) = 0$$

$$\det(A + B) = 0$$

$$\det(A + B) = 0$$

7.8 Application: Earthquake-Induced Vibrations of Multistory Buildings



FIGURE 81 The building model.



FIGURE 82 Mass-spring-damper system.

Figure 81 shows an example of a multistory building subjected to an earthquake-induced vibration. This figure shows the mass-spring-damper model of such a structure in two steps. Figure 82 illustrates the mass-spring-damper model of a single building floor. The horizontal displacement of the building floor is denoted by x . The mass of the floor is m , the spring constant is k , and the damping coefficient is c . The equation of motion for the mass is

$$m \ddot{x} + c \dot{x} + kx = F \cos(\omega t) \quad (8)$$

The steady-state response to the earthquake is a function of frequency ω . The response amplitude A and phase ϕ are given by

ω	Amplitude A	Phase ϕ (rad)	Ratio A/F (rad)
0	1.00000	0.00000	0.00000
1	1.00000	0.00000	0.00000
2	1.00000	0.00000	0.00000
3	1.00000	0.00000	0.00000
4	1.00000	0.00000	0.00000
5	1.00000	0.00000	0.00000
6	1.00000	0.00000	0.00000
7	1.00000	0.00000	0.00000

FIGURE 83 Response amplitude of mass-spring-damper system.

The solution to the second-order constant-coefficient differential equation (1) is $x(t) = c_1 e^{i\omega t} + c_2 e^{-i\omega t}$ for some constants c_1 and c_2 . In order to determine the initial conditions, this has to be written in terms of trigonometric functions. For a pair of constants A and B , we can write $c_1 e^{i\omega t} + c_2 e^{-i\omega t} = A \cos \omega t + B \sin \omega t$ (see Exercise 14).

Choosing $x(0) = x_0$ and $x'(0) = v_0$ as the given initial conditions and applying $x(t) = A \cos \omega t + B \sin \omega t$ to equations (2) and (3) yields the system of equations $A = x_0$ and $B\omega = v_0$. Solving this system gives us

$$x(t) = x_0 \cos \omega t + \frac{v_0}{\omega} \sin \omega t. \quad (4)$$

When $\omega = 1$, $x(t) = x_0 \cos t + v_0 \sin t$. The graph of $x(t)$ is shown in Figure 1.10. It shows a periodic motion with the period 2π . If we show that $x(t)$ satisfies the physical equation, then we have proved that the solution to the second-order differential equation (1) is $x(t) = x_0 \cos \omega t + \frac{v_0}{\omega} \sin \omega t$. In fact, we have the following theorem. The solution to the second-order differential equation (1) with initial conditions (2) and (3) is $x(t) = x_0 \cos \omega t + \frac{v_0}{\omega} \sin \omega t$.

In the next section we discuss the physical interpretation of the initial conditions in the case of a mass-spring system. For a mass-spring system, the mass is displaced from its equilibrium position and released from rest. In this case, the initial conditions are $x(0) = x_0$ and $v(0) = 0$.

The main characteristics of the motion of a mass-spring system are:

1. The motion is periodic. The period of the motion is $2\pi/\omega$.
2. The amplitude of the motion is $\sqrt{x_0^2 + (v_0/\omega)^2}$.
3. The phase angle of the motion is $\arctan(v_0/\omega x_0)$.
4. The maximum displacement and the minimum displacement of the motion are $x_0 + (v_0/\omega)$ and $x_0 - (v_0/\omega)$, respectively.
5. The average kinetic energy of the mass is $\frac{1}{2} m v_0^2$.



FIGURE 1.10 Graph of $x(t) = x_0 \cos \omega t + \frac{v_0}{\omega} \sin \omega t$ for a mass-spring system. The initial conditions are $x(0) = x_0$ and $v(0) = v_0$.