

Lie Derivatives yet again

by bob jantzen [March 1991]

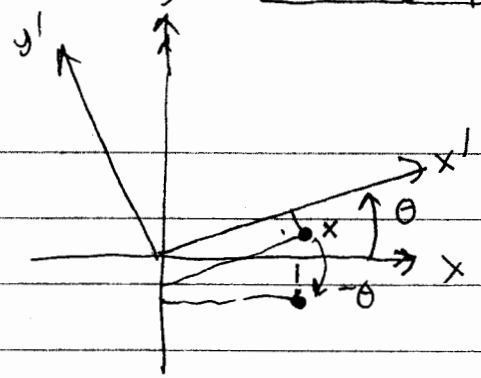
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4 short pages on the Lie derivative starting with rotations and angular momentum operators..

- [lieder1991.pdf](#) 5 pages

BACKGROUND

Rotation group and Angular momentum operator on wavefunction in Quantum Mechanics



$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = f_\theta \begin{pmatrix} x \\ y \end{pmatrix} \quad \text{active}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} x' \\ y' \end{pmatrix} = f_{-\theta} \begin{pmatrix} x' \\ y' \end{pmatrix} \quad \text{passive}$$

drag along coordinate functions by active transformation

any function:

$$\varphi'(\text{new point}) = \varphi(\text{old point})$$

$$\varphi'(\bar{x}, \bar{y}) = \varphi(x, y) \quad \text{compose with } f_{-\theta}$$

$$\varphi'(x, y) = \varphi(f_\theta(x, y))$$

new field

$$\rightarrow \varphi' = \varphi \circ f_{-\theta}$$

$$= \varphi(x', y')$$

same function of new coordinates as of old.

$$\left. \frac{d}{d\theta} \right|_{\theta=0} \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} -\sin\theta & \cos\theta \\ \cos\theta & \sin\theta \end{pmatrix} \Big|_{\theta=0} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} y \\ -x \end{pmatrix}$$

$$\left. \frac{d}{d\theta} \right|_{\theta=0} \varphi' = \left[\underbrace{\frac{\partial \varphi}{\partial x}}_y \frac{\partial x'}{\partial \theta} + \frac{\partial \varphi}{\partial y} \underbrace{\frac{\partial y'}{\partial \theta}}_{-x} \right] \Big|_{\theta=0} = - \underbrace{\left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)}_{L_3} \varphi(x, y)$$

angular momentum operator

$$\left(\frac{d}{d\theta} \right) \Big|_{\theta=0} \varphi' = (-L_3) \varphi$$

$$\varphi' = \sum_{n=0}^{\infty} \frac{\theta^n}{n!} \left(\frac{d}{d\theta} \right) \Big|_{\theta=0}^n \varphi = e^{-\theta L_3} \varphi$$

rotation operator.

"generator of rotation"

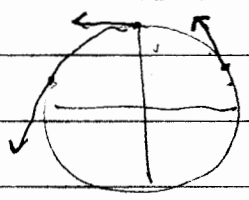
interpretation of vector field generator:

$$(x^\mu) = (x, y)$$

$$L_3 = \sum^\mu \frac{\partial}{\partial x^\mu}$$

$$\xi^\mu = \left. \frac{d}{d\theta} \right|_{\theta=0} f^\mu(x, \theta)$$

representation on the space of functions of the group of rotations.



tangent to orbits

$$\begin{pmatrix} x' \\ y' \end{pmatrix} \approx \begin{pmatrix} x \\ y \end{pmatrix} + \theta \begin{pmatrix} L_3 \\ L_2 \end{pmatrix}$$

one parameter family of point transformations:

$$x^M \rightarrow f_{(\lambda)}^M(x), \quad f_{(0)}^M(x) = x^M$$

$$\xi^M(x) = \frac{df_{(\lambda)}^M(x)}{d\lambda}, \quad \xi = \xi^M(x) \frac{\partial}{\partial x^M}$$

$$\bar{x}^M = f_{(\lambda)}^M(x) + \lambda \frac{df_{(\lambda)}^M(x)}{d\lambda} + \frac{1}{2} \lambda^2 \frac{d^2 f_{(\lambda)}^M}{d\lambda^2} + \dots$$

$$\approx x^M + \lambda \xi^M(x) \quad \lambda \ll 1$$

$$f_{(\lambda)}^{-1 M}(x) = \dots \approx x^M - \lambda \xi^M(x)$$

$\phi_{(\lambda)}^{\bullet}(x) \equiv \phi(f_{(\lambda)}^{-1}(x))$ dragged along field (for each λ)

$$\left. \frac{d}{d\lambda} \right|_{\lambda=0} \phi_{(\lambda)}(x) = \frac{\partial \phi}{\partial x^M} \underbrace{f_{(\lambda)}^{-1 M}(x)}_x \underbrace{\frac{df_{(\lambda)}^{-1 M}(x)}{d\lambda}}_{-\xi^M(x)} = -\xi^M(x) \frac{\partial}{\partial x^M} \phi(x) = -\xi \phi(x)$$

Lie derivative along vector field ξ^M

$$\mathcal{L}_{\xi} \phi \equiv - \left. \frac{d}{d\lambda} \right|_{\lambda=0} \phi_{(\lambda)} = \xi \phi = \xi^M \frac{\partial}{\partial x^M} \phi$$

derivative of ϕ along vector field ξ .

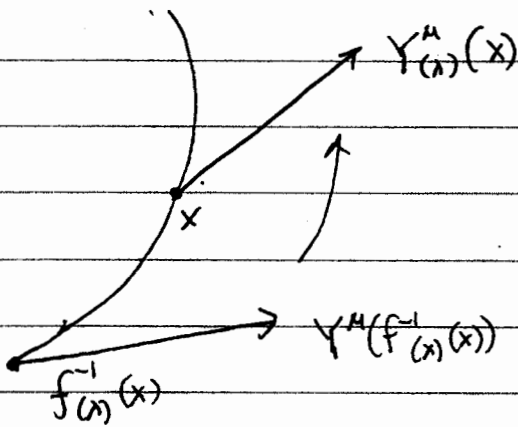
$$\begin{aligned} \phi_{(\lambda)} &\approx \phi - \lambda \mathcal{L}_{\xi} \phi && \text{describes how } \phi \\ &= e^{-\lambda \mathcal{L}_{\xi}} \phi && \text{begins to change under} \\ & && \text{dragging.} \\ & && \text{"dragging operator"} \end{aligned}$$

dragged along coordinates $x'^M = (f^{-1})^M_{(\lambda)}(x)$

coordinates of point $f_{(\lambda)}^{-1}(x)$
from which x came

or $x^M = f^M_{(\lambda)}(x')$

How to drag along a vector field?



$$Y^{\mu'}(x) = Y^{\mu}(f^{-1}(x))$$

new components of new field at new point

old components of old field at old point

old components of new field at new point:

$$Y^{\mu}(x) = \frac{\partial X^{\mu}(x')}{\partial X^{\nu'}} Y^{\nu'}(x')$$

$$\frac{\partial f^{\mu}(x')}{\partial x^{\nu}} \underbrace{Y^{\nu}(f^{-1}(x))}_{\text{differential of } f(x)}$$

differential of $f(x)$ maps tangent space at $f^{-1}(x)$ to x .

$$\left(\frac{d}{ds} Y^{\mu} \right) (x) \equiv - \frac{d}{d\lambda} \Big|_{\lambda=0} Y^{\mu}(x) = - \frac{d}{d\lambda} \Big|_{\lambda=0} \left[\frac{\partial f^{\mu}(x')}{\partial x^{\nu'}} Y^{\nu'}(f^{-1}(x')) \right]$$

$$= - \frac{\partial f^{\mu}(x')}{\partial x^{\nu'}} \underbrace{Y^{\nu'}(f^{-1}(x'))}_x \frac{\partial Y^{\mu}(f^{-1}(x'))}{\partial x^{\rho'}} \underbrace{\frac{df^{\rho'}(x')}{d\lambda}}_{-\xi^{\rho}(x)} - \frac{\partial}{\partial x^{\nu'}} \left[\frac{df^{\mu}(x')}{d\lambda} \underbrace{Y^{\mu}(f^{-1}(x'))}_x \right]$$

$$\left[\frac{df^{\mu}(x')}{d\lambda} \right] = \sum_{\mu} \frac{d^2 f^{\mu}(x')}{d\lambda^2} \underbrace{Y^{\mu}(f^{-1}(x'))}_x \underbrace{\xi^{\mu}(x)}_0$$

$$= \sum_{\rho} \xi^{\rho} \frac{\partial}{\partial x^{\rho}} Y^{\mu}(x) - Y^{\nu}(x) \frac{\partial}{\partial x^{\nu}} \xi^{\mu}(x)$$

$$= \xi Y^{\mu} - Y \xi = [\xi, Y]^{\mu} \quad \text{exercise.}$$

$$\xi Y - Y \xi$$

commutator of operators \equiv Lie bracket of vector fields

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covector field?

$$Z_{(x)\mu}(x) = \frac{\partial f^{-1\nu}}{\partial x^\mu}(x) Z_{\nu\alpha}(f^\alpha_\mu(x))$$

$$\begin{aligned} \int_{\mathcal{L}_3} \phi &= \int_{\mathcal{L}_3} \frac{\partial \phi}{\partial x^\mu} \frac{\partial x'^\mu}{\partial x^\mu} \\ \int_{\mathcal{L}_3} Y^\mu &= \int_{\mathcal{L}_3} \frac{\partial Y^\mu}{\partial x^\rho} \frac{\partial x^\rho}{\partial x^\mu} - \frac{\partial \xi^\mu}{\partial x^\rho} Y^\rho \\ \int_{\mathcal{L}_3} Z_\mu &= \int_{\mathcal{L}_3} \frac{\partial Z_\mu}{\partial x^\rho} \frac{\partial x^\rho}{\partial x^\mu} + Z_\rho \frac{\partial \xi^\rho}{\partial x^\mu} \end{aligned}$$

dragging of
currents/fields

dragging
of coordinate axes.

other
contraction.

opposite sign

(For rotation group : orbital angular momentum spin orbital momentum.)

$$\begin{aligned} \int_{\mathcal{L}_3} T^{\mu\dots}_{\nu\dots} &= \int_{\mathcal{L}_3} \frac{\partial}{\partial x^\rho} T^{\mu\dots}_{\nu\dots} \frac{\partial x^\rho}{\partial x^\mu} - \frac{\partial \xi^\rho}{\partial x^\mu} T^{\mu\dots}_{\nu\dots} + \frac{\partial \xi^\rho}{\partial x^\nu} T^{\mu\dots}_{\rho\dots} \\ &= T^{\mu\dots}_{\nu\rho} \xi^\rho - \xi^\rho_{,\mu} T^{\mu\dots}_{\nu\dots} + \xi^\rho_{,\nu} T^{\mu\dots}_{\rho\dots} + \dots \end{aligned}$$

$$\begin{aligned} \int_{\mathcal{L}_3} g_{\mu\nu} &= g_{\mu\nu,\rho} \xi^\rho + \xi^\rho_{,\mu} g_{\rho\nu} + \xi^\rho_{,\nu} g_{\mu\rho} \\ &= \dots g_{\mu\nu;\rho} \xi^\rho + \xi^\rho_{,\mu} g_{\rho\nu} + \xi^\rho_{,\nu} g_{\mu\rho} \\ &= \xi_{\nu;\mu} + \xi_{\mu;\nu} \end{aligned}$$

$$T_{(x)}^{\mu\dots}_{\nu\dots}(x) = e^{-\lambda \int_{\mathcal{L}_3} T^{\mu\dots}_{\nu\dots}(x)} \approx T^{\mu\dots}_{\nu\dots} - \lambda \int_{\mathcal{L}_3} T^{\mu\dots}_{\nu\dots}$$

$$T_{(x)}^{\mu\dots}_{\nu\dots}(x) = T^{\mu\dots}_{\nu\dots}(x) \quad \text{invariance} \iff \int_{\mathcal{L}_3} T^{\mu\dots}_{\nu\dots} = 0 \quad \text{for all } \lambda$$

these notes March 1991
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useful text:

B. Schutz Geometrical Methods of Mathematical Physics Cambridge U. Press (paperback)