

PARABOLOIDAL COORDINATES ON  $\mathbb{R}^3$

$$\begin{aligned} x &= \rho \cos \varphi = \mu v \cos \varphi \\ y &= \rho \sin \varphi = \mu v \sin \varphi \\ z &= z = \frac{1}{2}(\mu^2 - v^2) \end{aligned}$$

cylindrical                      paraboloidal

$\rho z$  plane transformation:

$$\begin{aligned} \rho &= \mu v \\ z &= \frac{1}{2}(\mu^2 - v^2) \end{aligned}$$

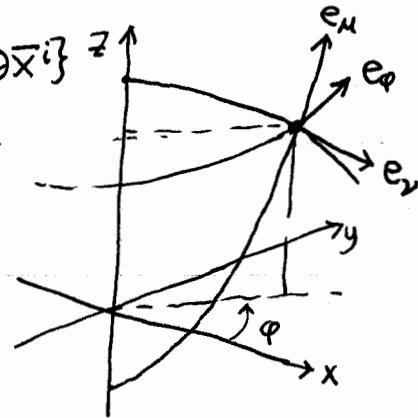
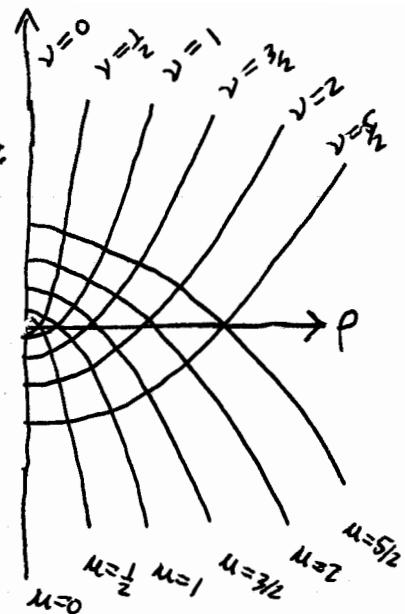
Revolve around  $z$ -axis  
to get 3-dim picture.

$\mu, v$  coord surfaces are

parabolas of revolution. The  $\varphi$  coordinate surfaces are still the  $\rho z$  half planes. The  $\mu$  and  $v$  coordinate lines are parabolas, while the  $\varphi$  coordinate lines are still circles about the  $z$ -axis. From the figure one can see that  $\{\mathbf{e}_\mu, \mathbf{e}_v, \mathbf{e}_\varphi\} \equiv \{\partial/\partial\mu, \partial/\partial v, \partial/\partial\varphi\} \equiv \{\partial/\partial\bar{x}^i\}$  is a righthanded frame ( $\mathbf{e}_\mu \times \mathbf{e}_v$  is along  $\mathbf{e}_\varphi$ ).

The coordinate ranges are

$$\mu \geq 0, \quad v \geq 0, \quad 0 \leq \varphi \leq 2\pi.$$



- 1) Show that the transformation between  $\rho$  and  $z$  and  $\mu$  and  $v$  may be inverted to obtain

$$\mu = \sqrt{z + \sqrt{z^2 + \rho^2}}, \quad v = \sqrt{-z + \sqrt{z^2 + \rho^2}}$$

so the coordinate map is

$$\mu = \sqrt{z + \sqrt{x^2 + y^2 + z^2}}, \quad v = \sqrt{-z + \sqrt{x^2 + y^2 + z^2}}, \quad \varphi = \tan^{-1} \frac{y}{x} + \begin{cases} 0 & \text{I, IV} \\ \pi & \text{II} \\ -\pi & \text{III} \end{cases}$$

- 2) Compute the transformation matrix  $A^{-1}(\bar{x})^i_j = \frac{\partial \bar{x}^i}{\partial x^j}$  by evaluating the differentials  $d\bar{x}^i = A^{-1}(\bar{x})^i_j d\bar{x}^j$ .

- 3) Since  $\frac{\partial}{\partial \bar{x}^i} = A^{-1}(\bar{x})^j_i \frac{\partial}{\partial x^j}$ , the columns of  $A^{-1}(\bar{x})$  represent the Cartesian coordinate components of the new coordinate frame vectors. Their dot products, considered as vectors in  $\mathbb{R}^3$  give the dot products  $\bar{g}_{ij} = \bar{e}_i \cdot \bar{e}_j$  of the new coordinate frame vectors. Show that they are orthogonal and evaluate their lengths, namely

$$(\bar{g}_{ij}) = [A^{-1}(\bar{x})]^T A^{-1}(\bar{x}).$$

Using these results, express the metric  $g = \bar{g}_{ij} dx^i \otimes dx^j$  in this orthogonal coordinate system.

4) Evaluate the oriented unit volume 3-form

$$\eta = dx^1 \wedge dy \wedge dz = [\det \underline{A}^{-1}(\bar{x})] \underbrace{dx^1 \wedge d\bar{x}^2 \wedge d\bar{x}^3}_{du \wedge dv \wedge dw}$$

Since  $[\det \underline{A}^{-1}(\bar{x})]$  is positive, these are oriented coordinates and  $[\det \underline{g}]^{1/2} = [\det \underline{A}^{-1}(\bar{x})]$ .

5) Introduce the associated orthonormal frame

$$\{\bar{e}_i^\uparrow\} = \{e_1^\uparrow, e_2^\uparrow, e_3^\uparrow\} \quad \bar{e}_i^\uparrow = (\bar{g}_{ii})^{-1/2} \bar{e}_i$$

$$\{\bar{\omega}^i\} = \{\omega_1^i, \omega_2^i, \omega_3^i\} \quad \bar{\omega}^i = (\bar{g}_{ii})^{1/2} \bar{\omega}^i, \quad \bar{\omega}^i = d\bar{x}^i$$

Let  $\underline{A}(\bar{x})$  be the transformation matrix between the old and new orthonormal frames:

$$\bar{e}_i^\uparrow = \underline{A}(\bar{x})^{-1} j_i \frac{\partial}{\partial \bar{x}^i}$$

$$\bar{\omega}^i = \underline{A}(\bar{x})^i j_i dx^i$$

Then this orthogonal matrix is

$$\underline{A}(\bar{x})^i j_i = (\bar{g}_{ii})^{-1/2} A(\bar{x})^{-1} j_i \quad (\text{normalize columns of } A(\bar{x})^{-1})$$

What is it?

Take its transpose to obtain  $\underline{A}(x)$ .

Get  $\underline{A}(x)$  by dividing the rows of  $\underline{A}(x)$  by the same normalizing factors used to divide the columns of  $\underline{A}(\bar{x})^{-1}$ :

$$A(x)^i j_i = \underline{A}(x)^i j_i (\bar{g}_{ii})^{-1/2} = \frac{\partial \bar{x}^i}{\partial x^j}(x)$$

6) By differentiating the coordinate map of part 1) and re-expressing its matrix of entries in terms of the new coordinates, verify that  $A(\bar{x})$  has the value obtained in 5). [Check also that  $\underline{A}(x) \underline{A}^{-1}(\bar{x}) = I$ ]

- 7) Compute the independent structure functions of the orthonormal frame  $\{\hat{C}_{jk}^i\}_{j < k}$  defined by:  $[\bar{e}_j^i, \bar{e}_k^i] = \hat{C}_{jk}^i \bar{e}_i^i$ .
- 8) Compute the components of the covariant derivative in the coordinate and associated orthonormal frame using the formulas
- $$\underline{A} d\underline{A}^{-1} = \underline{\omega} = (\bar{\Gamma}^i_{kj} dx^j)$$
- $$\underline{d} d\underline{A}^{-1} = \hat{\underline{\omega}} = (\bar{\Gamma}^i_{kj} \bar{\omega}^k)$$
- 9) Verify these results using the formulas involving the derivatives of the metric and the structure functions.

- 10) Now for something new, well not new, but a putting together of things we already know. Consider the coordinate frame formula:

$$R^i_{jmn} = \partial_m \Gamma^i_{nj} - \partial_n \Gamma^i_{mj} + \Gamma^l_{ml} \Gamma^l_{nj} - \Gamma^l_{nl} \Gamma^l_{mj}$$

$$= 2 \partial_{[m} \Gamma^i_{n]j} + 2 \overset{\substack{\text{no antisym} \\ \text{on 2}}}{} \Gamma^i_{[m l} \Gamma^l_{n]j} = R^i_{j[mn]}$$

$$\underline{\Omega}^i_j \equiv \frac{1}{2} R^i_{jmn} dx^{mn} = \frac{1}{2} [ 2 \underset{[d\omega^i_j]_{mn}}{\underbrace{\partial_{[m} \Gamma^i_{n]j} dx^{mn}}} + 2 \underset{[\omega^i_j \wedge \omega^l_j]_{mn}}{\underbrace{\Gamma^i_{[m l} \Gamma^l_{n]j} dx^{mn}}} ]$$

$$= d\omega^i_j + \omega^i_e \wedge \omega^e_j$$

By introducing a curvature 2-form  $\underline{\omega}$ , matrix  $\underline{\Omega} = (\underline{\Omega}^i_j)$  one can more efficiently compute the curvature tensor components

$$\underline{\Omega} = \underline{d}\underline{\omega} + \underline{\omega} \wedge \underline{\omega}$$

$\uparrow$     matrix product of matrix indices  
 read off                                      wedge product of 1 form matrix entries  
 curvature tensor components — matrix indices give left pair of tensor indices, coefficients of  $dx^{mn}$  give second pair.

If we use this in the new coordinate frame:

$$\underline{\Omega} = \underline{d}\underline{\omega} + \underline{\omega} \wedge \underline{\omega} = \frac{d(A d A^{-1}) + A d A^{-1} \wedge A d A^{-1}}{d A \wedge d A^{-1} + A \underbrace{d A^{-1}}_{=0}}$$

$$\text{But } \underline{A} \underline{A}^{-1} = \mathbb{I} \rightarrow [\underline{dA} \underline{A}^{-1} + \underline{A} \underline{dA}^{-1}] \underline{A} \\ \underline{dA} + \underline{A} \underline{dA}^{-1} \underline{A} = 0 \rightarrow \underline{dA} = -\underline{A} \underline{dA}^{-1} \underline{A}$$

$$\text{so } \underline{dA} \wedge \underline{dA}^{-1} = -\underline{A} \underline{dA}^{-1} \underline{A} \wedge \underline{dA}^{-1} = -\underline{A} \underline{dA}^{-1} \wedge \underline{A} \underline{dA}^{-1}$$

$\uparrow$                              $\uparrow$

wedge can be anywhere between differentials since matrices are just functions and can be put anywhere as factors with respect to the wedge product.

$$\text{hence } \underline{\Omega} = 0.$$

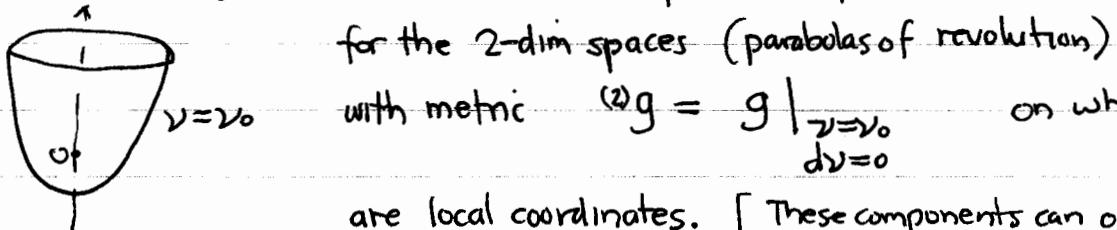
Of course we knew the curvature tensor to be zero, but this matrix method most efficiently achieves this result.

[Note: if  $\underline{\omega} \wedge \underline{\omega}$  bothers you, here is an example of  $2 \times 2$  matrices of 1-forms]

$$\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} \wedge \begin{pmatrix} A & B \\ C & D \end{pmatrix} = \begin{pmatrix} \alpha \Lambda A + \beta \Lambda C & \alpha \Lambda B + \beta \Lambda D \\ \gamma \Lambda A + \delta \Lambda C & \gamma \Lambda B + \delta \Lambda D \end{pmatrix}$$

where all the entries are assumed to be 1-forms. (or, in fact, p-forms).

II) You only had to follow 10), not do anything. Now, from your results for  $\tilde{\Gamma}^i_{jk}$  you can read off the components of the covariant derivative



for the 2-dim spaces (parabolas of revolution)

$$\text{with metric } {}^{(2)}g = g|_{\substack{v=v_0 \\ du=0}}$$

are local coordinates. [These components can only be defined by the 2-dimensional formula in terms of the metric derivatives.]

What is the 2-dimensional matrix  ${}^{(2)}\underline{\omega} = {}^{(2)}(\omega^\alpha_\beta) = {}^{(2)}\int^\alpha \partial_\beta d\bar{x}^\alpha$

where  $\alpha, \beta, \dots = u, \phi$  indices. (1,3 in numbers)?

Now compute the 2-curvature 2-form matrix

$${}^{(2)}\underline{\Omega} = d{}^{(2)}\underline{\omega} + {}^{(2)}\underline{\omega} \wedge {}^{(2)}\underline{\omega} = \left( \frac{1}{2} {}^{(2)}R^\alpha_{\beta\gamma\delta} d\bar{x}^\alpha \wedge d\bar{x}^\delta \right)$$

Read off the two components  ${}^{(2)}R^u_{\phi\mu\phi}, {}^{(2)}R^\phi_{\mu\mu\phi}$ .

Does  ${}^{(2)}R_{\mu\phi\mu\phi} = -{}^{(2)}R_{\phi\mu\mu\phi}$ ?

12) Evaluate  ${}^{(2)}R^{\hat{u}} \hat{\varphi} \wedge \hat{\vartheta} = (\bar{g}_{\varphi\vartheta})^{-1} {}^{(2)}R^{\hat{u}}_{\varphi\vartheta\vartheta}$ .

What is the value at  $\mu=0$ , the vertex of the parabola of revolution?

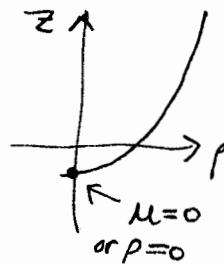
The parabola which is revolved is

$$\rho = \mu v_0 \rightarrow \mu = \rho/v_0$$

$$z = \frac{1}{2}(\mu^2 - v_0^2) = \frac{1}{2}(\rho^2/v_0^2 - v_0^2)$$

The curvature of this parabola at any point comes from the multivariable calculus formula

$$K = \frac{|d^2z/d\rho^2|}{[1 + (dz/d\rho)^2]^{3/2}}$$



Evaluate  $K(\rho=0)$  and compare it to the value of  ${}^{(2)}R^{\hat{u}} \hat{\varphi} \wedge \hat{\vartheta}$ . Do you notice any relationship?

- 13) Show that the  $\mu$  coordinate lines are geodesics on these parabolas, but that the  $\varphi$  coordinate lines are not.

- 14) What is the single independent structure function  $C^{\hat{\vartheta}}_{\hat{u}\hat{\vartheta}}$  for the 2-dim orthonormal frame?

Use it to compute the components of the covariant derivative in the orthonormal frame:  $(2)\Gamma^{\hat{u}}_{\hat{\vartheta}\hat{\vartheta}}$ .

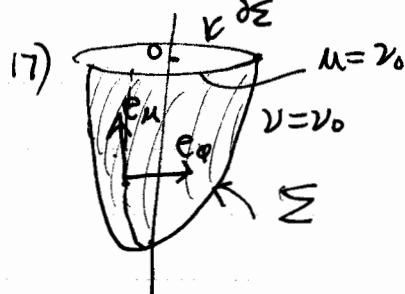
Use them to show that  $e^{\hat{u}}$  and  $e^{\hat{\vartheta}}$  are parallel transported along the  $\mu$  coordinate lines.

- 15) All of these computations (with the exception of the curvature 2-form notation) have been done with either cylindrical or spherical coordinates in the notes, so you should have no problem if you understood them.

16) Let  $\begin{cases} \underline{\mathbf{X}} = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} + (x^2+y^2+z^2) \frac{\partial}{\partial z} \\ \underline{\mathbf{X}}^b = -y dx + x dy + (x^2+y^2+z^2) dz \end{cases}$

Evaluate  $\underline{\mathbf{X}}^b$  in paraboloidal coordinates. Find  $\underline{\mathbf{X}}$  in these coordinates.

Evaluate  $\nabla_{\underline{\mathbf{X}}} \underline{\mathbf{X}}$ .



Let  $\Sigma$  be the 2-surface  $\begin{cases} z = z_0 \\ 0 \leq x \leq x_0 \end{cases}$

parametrized by  $\{u, v\}$ .

What choice of normal does this inner orientation imply by the right hand rule? (inward/upper or outward/downward(?))

Looking down from above, what is the induced orientation of  $\partial\Sigma$ : clockwise or counterclockwise?

As on pages 152-153, verify Stokes' theorem  $\int_{\partial\Sigma} \underline{\mathbf{X}}^b = \int_{\Sigma} d\underline{\mathbf{X}}^b$   
for  $\underline{\mathbf{X}}^b$  of part 16).

18) That's all folks. Have fun. Stop by if you have any difficulty.

I need your work by 5pm Friday May 3 to make up grades for Monday.

W: 645-7335 h: 527-4641. [Slippage to Monday noon if you really have a time problem].

TAKE HOME FINAL WORKED PROBLEMS

$$\rho = \mu v \rightarrow v = \rho/\mu$$

$$1) Z = \frac{1}{2}(\mu^2 - v^2) = \frac{1}{2}(\mu^2 - \rho^2/\mu^2)$$

$$\mu^4 - 2Z\mu^2 - \rho^2 = 0$$

$$\mu^2 = \frac{\alpha z \pm \sqrt{4z^2 + 4\rho^2}}{2} = z + \sqrt{z^2 + \rho^2}$$

$\geq 0$

$$\mu = \sqrt{z + \sqrt{z^2 + \rho^2}} \quad (\mu \geq 0)$$

$$\text{or } \mu = \rho/v$$

$$Z = \frac{1}{2}(\rho^2/v^2 - v^2)$$

$$2Z + v^2 = \rho^2/v^2$$

$$v^4 + 2Zv^2 - \rho^2 = 0$$

$$v^2 = -\frac{2Z \pm \sqrt{4z^2 + 4\rho^2}}{2}$$

$$= -z + \sqrt{z^2 + \rho^2} \quad (\text{dilute})$$

$$v = \sqrt{-z + \sqrt{z^2 + \rho^2}} \quad (v \geq 0)$$

$$\text{Note } \underbrace{z^2 + \rho^2}_{z^2 + x^2 + y^2} = \frac{4\mu^2 v^2 + \mu^4 - 2\mu^3 v^2 + v^4}{4} = \left(\frac{\mu^2 + v^2}{2}\right)^2$$

$$z^2 + x^2 + y^2 = r^2$$

$$\text{so } r = \sqrt{z^2 + \rho^2} = \frac{\mu^2 + v^2}{2}$$

$$2) x = \mu v \cos \varphi \quad dx = v \cos \varphi d\mu + \mu \cos \varphi dv + \mu v \sin \varphi d\varphi$$

$$y = \mu v \sin \varphi \quad dy = v \sin \varphi d\mu + \mu \sin \varphi dv + \mu v \cos \varphi d\varphi$$

$$z = \frac{1}{2}(\mu^2 - v^2) \quad dz = \mu d\mu - v dv$$

$$\underline{A}^{-1}(\bar{x}) = \begin{bmatrix} v \cos \varphi & \mu \cos \varphi & -\mu v \sin \varphi \\ v \sin \varphi & \mu \sin \varphi & \mu v \cos \varphi \\ \mu & -v & 0 \end{bmatrix}$$

$$3) g_{\mu\mu} = \mu^2 + v^2 \quad g_{\nu\nu} = \mu^2 + v^2 \quad g_{\varphi\varphi} = \mu^2 v^2$$

$$g = \delta_{ij} dx^i \otimes dx^j = (\mu^2 + v^2) [d\mu \otimes d\mu + dv \otimes dv] + \mu^2 v^2 d\varphi \otimes d\varphi$$

4) Row expansion on last row

$$\begin{aligned} \det \underline{A}^{-1}(\bar{x}) &= \mu \begin{vmatrix} \mu \cos \varphi & -\mu v \sin \varphi \\ \mu \sin \varphi & \mu v \cos \varphi \end{vmatrix} - (-v) \begin{vmatrix} v \cos \varphi & -\mu v \sin \varphi \\ v \sin \varphi & \mu v \cos \varphi \end{vmatrix} \\ &= \mu(\mu^2 v) + v(\mu v^2) = \mu v(\mu^2 + v^2) \geq 0 \text{ so positively oriented.} \end{aligned}$$

$$\eta = \underbrace{\mu v(\mu^2 + v^2)}_{(g_{\mu\mu} g_{\nu\nu} g_{\varphi\varphi})^{1/2}} d\mu \wedge dv \wedge d\varphi$$

$$(g_{\mu\mu} g_{\nu\nu} g_{\varphi\varphi})^{1/2}$$

$$5) e_{\hat{\mu}} = \frac{1}{(\mu^2 + v^2)^{1/2}} \frac{\partial}{\partial \mu}, \quad e_{\hat{\nu}} = \frac{1}{(\mu^2 + v^2)^{1/2}} \frac{\partial}{\partial v}, \quad e_{\hat{\varphi}} = \frac{1}{(\mu v)} \frac{\partial}{\partial \varphi}$$

$$\omega^{\hat{\mu}} = (\mu^2 + v^2)^{1/2} d\mu, \quad \omega^{\hat{\nu}} = (\mu^2 + v^2)^{1/2} dv, \quad \omega^{\hat{\varphi}} = \mu v d\varphi$$

$$(\text{note } \eta = \omega^{\hat{\mu}} \wedge \omega^{\hat{\nu}} \wedge \omega^{\hat{\varphi}} = \omega^{\hat{\mu}\hat{\nu}\hat{\varphi}})$$

$$\underline{A}^{-1}(\bar{x}) = \begin{bmatrix} \frac{\nu}{(u^2+v^2)^{1/2}} \cos\varphi & \frac{u}{(u^2+v^2)^{1/2}} \cos\varphi & -\sin\varphi \\ \frac{\nu}{(u^2+v^2)^{1/2}} \sin\varphi & \frac{u}{(u^2+v^2)^{1/2}} \sin\varphi & \cos\varphi \\ \frac{u}{(u^2+v^2)^{1/2}} & \frac{-\nu}{(u^2+v^2)^{1/2}} & 0 \end{bmatrix}$$

$$\underline{A}(\bar{x}) = \begin{bmatrix} \frac{\nu}{(u^2+v^2)^{1/2}} \cos\varphi & \frac{\nu}{(u^2+v^2)^{1/2}} \sin\varphi & \frac{u}{(u^2+v^2)^{1/2}} \\ \frac{u}{(u^2+v^2)^{1/2}} \cos\varphi & \frac{u}{(u^2+v^2)^{1/2}} \sin\varphi & \frac{-\nu}{(u^2+v^2)^{1/2}} \\ -\sin\varphi & \cos\varphi & 0 \end{bmatrix}$$

$$\underline{A}(\bar{x}) = \begin{bmatrix} \frac{\nu}{u^2+v^2} \cos\varphi & \frac{\nu}{u^2+v^2} \sin\varphi & \frac{u}{u^2+v^2} \\ \frac{u}{u^2+v^2} \cos\varphi & \frac{u}{u^2+v^2} \sin\varphi & \frac{-\nu}{u^2+v^2} \\ -\frac{1}{uv} \sin\varphi & \frac{1}{uv} \cos\varphi & 0 \end{bmatrix} = \left( \frac{\partial \bar{x}^i}{\partial x^j}(x(\bar{x})) \right)$$

e) Now recall that  $2\sqrt{z^2+p^2} = u^2+v^2$ , so for example,

$$\begin{aligned} M &= (z + (z^2+p^2)^{1/2})^{1/2} \\ dM &= \frac{1}{2(z)}^{1/2} [dz + \frac{1}{2} \frac{[2zdz + 2xdx + 2ydy]}{(z^2+p^2)^{1/2}}] = \frac{1}{2M} \left[ \frac{(u^2+v^2)dz + [\sqrt{2z}dz + 2xdx + 2ydy]}{u^2+v^2} \right] \\ &= \frac{1}{2M} \left[ \frac{2xdx + 2ydy + 2M^2dz}{u^2+v^2} \right] = \frac{xdx + ydy + u^2dz}{M(u^2+v^2)} \\ &= \frac{uv \cos\varphi dx + uv \sin\varphi dy + u^2 dz}{M(u^2+v^2)} \end{aligned}$$

and these components of  $dM$  are exactly the first row of  $\underline{A}(\bar{x})$ . Second row similar.

The last row comes from  $d\varphi = -\frac{\sin\varphi}{p}dx + \frac{\cos\varphi}{p}dy$  which is the cylindrical coordinate result with  $p$  then replaced by  $uv$ .

$$7) [e_{\hat{s}}, e_{\hat{\phi}}] = [(u^2+v^2)^{-1/2} \frac{\partial}{\partial s}, (uv)^{-1} \frac{\partial}{\partial \phi}] = (u^2+v^2)^{-1/2} \frac{1}{u} (-\frac{1}{v^2}) \frac{\partial}{\partial \phi}$$

$$= -\frac{1}{(u^2+v^2)^{1/2} v} e_{\hat{\phi}}$$

$$C_{\hat{s}\hat{\phi}}^{\hat{\phi}} = -\frac{1}{(u^2+v^2)^{1/2} v}$$

$$[e_{\hat{s}}, e_{\hat{u}}] = [(u^2+v^2)^{-1/2} \frac{\partial}{\partial s}, (uv)^{-1} \frac{\partial}{\partial u}] = \dots = -\frac{1}{(u^2+v^2)^{1/2} u} e_{\hat{\phi}}$$

$$C_{\hat{s}\hat{u}}^{\hat{\phi}} = -\frac{1}{(u^2+v^2)^{1/2} u}$$

$$[e_{\hat{u}}, e_{\hat{s}}] = [(u^2+v^2)^{-1/2} \frac{\partial}{\partial u}, (u^2+v^2)^{-1/2} \frac{\partial}{\partial s}] = (u^2+v^2)^{-1} \frac{\partial}{\partial u} (\ln(u^2+v^2)^{-1/2}) \frac{\partial}{\partial s} - \dots$$

$$= -\frac{1}{2} (u^2+v^2)^{-1} \frac{2u}{(u^2+v^2)} \frac{\partial}{\partial s} + \frac{1}{2} (u^2+v^2)^{-1} \frac{2v}{u^2+v^2} \frac{\partial}{\partial u} = \frac{1}{(u^2+v^2)^{3/2}} [-u e_{\hat{s}} + v e_{\hat{u}}]$$

$$C_{\hat{u}\hat{s}}^{\hat{u}} = \frac{v}{(u^2+v^2)^{3/2}}, \quad C_{\hat{u}\hat{s}}^{\hat{u}} = \frac{-u}{(u^2+v^2)^{3/2}}$$

letting  $\rho^2 = u^2 + v^2$   
 $\rho = uv$

$$\textcircled{3} \quad \underline{\omega} = \underline{A} d\underline{A}^{-1} = \begin{bmatrix} \frac{v}{(2r)} c & \frac{v}{(2r)} s & \frac{u}{(2r)} \\ \frac{u}{(2r)} c & \frac{u}{(2r)} s & -\frac{v}{(2r)} \\ -\frac{1}{\rho} s & \frac{1}{\rho} c & 0 \end{bmatrix} d \begin{bmatrix} vc & uc & -uv s \\ vs & us & uv c \\ u & -v & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{u}{(2r)} & \frac{v}{(2r)} & 0 \\ -\frac{v}{(2r)} & \frac{u}{(2r)} & 0 \\ 0 & 0 & \frac{1}{\rho} \end{bmatrix} du + \begin{bmatrix} \frac{v}{(2r)} & -\frac{u}{(2r)} & 0 \\ \frac{u}{(2r)} & \frac{v}{(2r)} & 0 \\ 0 & 0 & \frac{1}{\rho} \end{bmatrix} dv + \begin{bmatrix} 0 & 0 & -\frac{uv^2}{(2r)} \\ 0 & 0 & -\frac{u^2v^2}{(2r)} \\ \frac{v}{\rho} & \frac{u}{\rho} & 0 \end{bmatrix} d\varphi$$

or 9g)  $\Gamma_{ijk} = \frac{1}{2}(g_{ij,k} - g_{jk,i} + g_{ki,j}) \quad \Gamma^i_{jk} = g^{ii} \Gamma_{ijk} = (\theta_{ii})^{-1} \Gamma_{ijk}$  (orthog coords)

$$\Gamma_{MMM} = \frac{1}{2}(g_{MM,M} - g_{MM,M} + g_{MM,M}) = u \quad \Gamma^M_{MM} = \frac{M}{u^2+v^2} = [\omega^M_M]_M \checkmark$$

$$\Gamma_{MMV} = \frac{1}{2}(g_{MM,V} - g_{MV,M} + g_{VM,M}) = v \quad \Gamma^M_{MV} = \frac{v}{u^2+v^2} = [\omega^M_V]_M \checkmark$$

$$\Gamma_{VMM} = \frac{1}{2}(g_{VM,M} - g_{NM,V} + g_{MV,M}) = -2u \quad \Gamma^V_{MM} = \frac{-2u}{u^2+v^2} = [\omega^V_M]_M \checkmark$$

$$\Gamma_{VMM} = \frac{1}{2}(g_{VM,V} - g_{MV,V} + g_{VV,M}) = u \quad \Gamma^V_{MV} = \frac{u}{u^2+v^2} = [\omega^V_V]_M \checkmark$$

Same  
for  
next  
four  
(lets  
pretend  
we did it)

$$\Gamma^M_{VMM} = \frac{v^2}{u^2+v^2}$$

$$\Gamma^M_{VVV} =$$

$$\Gamma^V_{VMM} =$$

$$\Gamma^V_{VVV} =$$

$$\Gamma_{QQM} = \frac{1}{2}(g_{QQ,M} - g_{QM,Q} + g_{QM,Q}) = 2u^2, \quad \Gamma^Q_{QQM} = \frac{1}{2u^2} = \frac{1}{\rho} \checkmark$$

$$\Gamma_{QQV} = \frac{1}{2}(g_{QQ,V} - g_{QV,Q} + g_{VQ,Q}) = 2u^2, \quad \Gamma^Q_{QVQ} = \frac{1}{2u} = \frac{1}{\rho} \checkmark$$

$$\Gamma_{MQQ} = \frac{1}{2}(g_{MQ,Q} - g_{QQ,M} + g_{QM,Q}) = -u^2, \quad \Gamma^M_{QQ} = \frac{-u^2}{u^2+v^2} \checkmark$$

$$\Gamma_{VQQ} = \frac{1}{2}(-g_{VQ,V} - g_{QV,V}) = -2u^2, \quad \Gamma^V_{QQ} = \frac{-2u^2}{u^2+v^2} \checkmark$$

stoppiness in mental multiplication for got these:

$$\Gamma_{QMM} = \frac{1}{2}(g_{QM,Q} - g_{QM,Q} + g_{QM,Q}) = u^2, \quad \Gamma^Q_{QMM} = \frac{1}{u^2}$$

$$\Gamma_{QVV} = \quad = u^2, \quad \Gamma^Q_{QVV} = \frac{1}{u^2}$$

$$g_b) \quad M = \frac{M}{(M^2 + V^2)^{1/2}}, \quad V = \frac{V}{(M^2 + V^2)^{1/2}}, \quad M^2 + V^2 = 1.$$

$$\frac{\partial M}{\partial M} = \frac{(M^2 + V^2)^{1/2} 1 - M \cdot \frac{1}{2} \frac{2M}{(M^2 + V^2)^{1/2}}}{(M^2 + V^2)} = \frac{(M^2 + V^2) - M^2}{(M^2 + V^2)^{3/2}} = \frac{V^2}{(M^2 + V^2)^{3/2}}$$

$$\frac{\partial M}{\partial V} = -\frac{1}{2} \frac{M \cdot 2V}{(M^2 + V^2)^{1/2}} = \frac{-MV}{(M^2 + V^2)^{3/2}}$$

$$\frac{\partial V}{\partial M} = \frac{-MV}{(M^2 + V^2)^{3/2}}$$

$$\frac{\partial V}{\partial V} = \frac{M^2}{(M^2 + V^2)^{3/2}}$$

$$\hat{\underline{\omega}} = \underline{d} \underline{\omega} \underline{d}^{-1} = \begin{bmatrix} V_c & V_s & M \\ M_c & M_s - V \\ -S & C & 0 \end{bmatrix} d \underbrace{\begin{bmatrix} V_c & M_c & -S \\ V_s & M_s & C \\ M - V & 0 & 0 \end{bmatrix}}_{d\varphi}$$

$$\begin{bmatrix} -MVc & V^2c & 0 \\ -MVs & V^2s & 0 \\ V^2 & Mv & 0 \end{bmatrix} \frac{dM}{(M^2 + V^2)^{3/2}} + \begin{bmatrix} M^2c & -MVc & 0 \\ M^2s & -MVs & 0 \\ -Mv & -M^2 & 0 \end{bmatrix} \frac{dV}{(M^2 + V^2)^{3/2}} + \begin{bmatrix} -Vs & Ms & -C \\ Vs & Mc & -S \\ 0 & 0 & 0 \end{bmatrix} d\varphi$$

$$= \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \frac{V}{(M^2 + V^2)} \underbrace{\left[ (M^2 + V^2)^{1/2} dM \right]}_{\hat{\omega}^M} + \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \frac{M}{(M^2 + V^2)} \underbrace{\left[ (M^2 + V^2)^{1/2} dV \right]}_{\hat{\omega}^V} + \begin{bmatrix} 0 & 0 & -V \\ 0 & 0 & -M \\ V & M & 0 \end{bmatrix} \frac{1}{Mv} \underbrace{\left[ Mv d\varphi \right]}_{\hat{\omega}^\varphi}$$

$$\Gamma^{\hat{M}}_{\hat{A}\hat{B}} = \frac{V}{(M^2 + V^2)^{3/2}} = -\Gamma^{\hat{B}}_{\hat{A}\hat{A}}, \quad \Gamma^{\hat{A}}_{\hat{B}\hat{B}} = -\frac{M}{(M^2 + V^2)^{3/2}} = -\Gamma^{\hat{B}}_{\hat{B}\hat{A}},$$

$$\Gamma^{\hat{M}}_{\hat{Q}\hat{P}} = -\frac{1}{M(M^2 + V^2)^{1/2}} = -\Gamma^{\hat{P}}_{\hat{Q}\hat{Q}}, \quad \Gamma^{\hat{P}}_{\hat{Q}\hat{P}} = -\frac{1}{M(M^2 + V^2)^{1/2}} = -\Gamma^{\hat{P}}_{\hat{P}\hat{Q}}$$

$$g_b) \text{ or } \Gamma^{\hat{I}}_{\hat{J}\hat{K}} = \Gamma^{\hat{I}}_{\hat{J}\hat{K}\hat{L}} = \frac{1}{2} (C_{\hat{I}\hat{J}\hat{K}} - C_{\hat{J}\hat{K}\hat{I}} + C_{\hat{K}\hat{I}\hat{J}})$$

$$C_{\hat{Q}\hat{A}\hat{Q}} = -\frac{1}{M(M^2 + V^2)^{1/2}}, \quad C_{\hat{Q}\hat{D}\hat{Q}} = -\frac{1}{M(M^2 + V^2)^{1/2}}, \quad C_{\hat{A}\hat{B}\hat{A}} = -\frac{V}{(M^2 + V^2)^{3/2}}, \quad C_{\hat{D}\hat{B}\hat{D}} = -\frac{M}{(M^2 + V^2)^{3/2}}$$

$$\Gamma^{\hat{M}}_{\hat{A}\hat{B}} = \frac{1}{2} (C_{\hat{A}\hat{B}\hat{M}} - C_{\hat{B}\hat{A}\hat{M}} + C_{\hat{M}\hat{A}\hat{B}}) = C_{\hat{A}\hat{B}\hat{M}} = \frac{V}{(M^2 + V^2)^{3/2}}$$

$$\Gamma^{\hat{A}}_{\hat{D}\hat{B}} = \frac{1}{2} (C_{\hat{A}\hat{D}\hat{B}} - C_{\hat{D}\hat{A}\hat{B}} + C_{\hat{B}\hat{A}\hat{D}}) = C_{\hat{D}\hat{A}\hat{B}} = \frac{M}{(M^2 + V^2)^{3/2}}$$

$$\Gamma^{\hat{A}}_{\hat{Q}\hat{Q}} = \frac{1}{2} (C_{\hat{Q}\hat{Q}\hat{A}} - C_{\hat{Q}\hat{A}\hat{Q}} + C_{\hat{A}\hat{Q}\hat{Q}}) = C_{\hat{Q}\hat{A}\hat{Q}} = -\frac{1}{M(M^2 + V^2)^{1/2}}$$

$$\Gamma^{\hat{D}}_{\hat{Q}\hat{P}} = \frac{1}{2} (C_{\hat{D}\hat{Q}\hat{P}} - C_{\hat{Q}\hat{P}\hat{D}} + C_{\hat{P}\hat{D}\hat{Q}}) = C_{\hat{Q}\hat{P}\hat{D}} = -\frac{1}{M(M^2 + V^2)^{1/2}}$$

$$11) \quad {}^{(2)}g = (M^2 + \nu_0^2) dM \otimes dM + M^2 \nu_0^2 d\varphi \otimes d\varphi, \quad {}^{(2)}n = M \nu_0 (M^2 + \nu_0^2)^{1/2} dM \wedge d\varphi$$

Only the components  $\tilde{\Gamma}^i_{jk}$  on page 164 with no  $\varphi$  indices are relevant here:

$${}^{(2)}\Gamma^M_{MM} = \frac{M}{M^2 + \nu_0^2}, \quad {}^{(2)}\Gamma^\varphi_{M\varphi} = \frac{1}{M} = {}^{(2)}\Gamma^\varphi_{\varphi M}, \quad {}^{(2)}\Gamma^M_{\varphi\varphi} = -\frac{M\nu_0^2}{M^2 + \nu_0^2}.$$

To get  ${}^{(2)}\underline{\omega}$ , just delete the second row and column of  $\underline{\omega}_M dM + \underline{\omega}_\varphi d\varphi$ :

$${}^{(2)}\underline{\omega} = \begin{bmatrix} M & 0 \\ \frac{M}{M^2 + \nu_0^2} & M^{-1} \end{bmatrix} dM + \begin{bmatrix} 0 & -\frac{M\nu_0^2}{M^2 + \nu_0^2} \\ M^{-1} & 0 \end{bmatrix} d\varphi = \begin{bmatrix} M dM & -\frac{M\nu_0^2}{M^2 + \nu_0^2} d\varphi \\ \frac{M dM}{M^2 + \nu_0^2} & M^{-1} dM \end{bmatrix}$$

$$d\left(\frac{M}{M^2 + \nu_0^2}\right) = \frac{(M^2 + \nu_0^2) - M(2M)}{(M^2 + \nu_0^2)^2} = \frac{\nu_0^2 - M^2}{(M^2 + \nu_0^2)^2} \quad dM^{-1} = -M^{-2} dM.$$

$$d{}^{(2)}\underline{\omega} = \begin{bmatrix} 0 & \frac{\nu_0^2(M^2 - \nu_0^2)}{(M^2 + \nu_0^2)^2} dM \wedge d\varphi \\ -M^{-2} dM \wedge d\varphi & 0 \end{bmatrix}$$

$$\left( d[f(u) dM] = f'(u) dM \wedge dM \right) = 0$$

$$\begin{aligned} {}^{(2)}\underline{\omega} \wedge {}^{(2)}\underline{\omega} &= \begin{bmatrix} M dM & -\frac{M\nu_0^2}{M^2 + \nu_0^2} d\varphi \\ \frac{M dM}{M^2 + \nu_0^2} & M^{-1} dM \end{bmatrix} \wedge \begin{bmatrix} M dM & -\frac{M\nu_0^2}{M^2 + \nu_0^2} d\varphi \\ M^{-1} d\varphi & M^{-1} dM \end{bmatrix} \\ &= \begin{bmatrix} 0 & \left[ \frac{-M^2 \nu_0^2}{(M^2 + \nu_0^2)^2} + \frac{\nu_0^2}{(M^2 + \nu_0^2)} \right] dM \wedge d\varphi \\ \left[ \frac{1}{M^2 + \nu_0^2} + \frac{1}{M^2} \right] dM \wedge d\varphi & 0 \end{bmatrix} \underbrace{\frac{\nu_0^4}{(M^2 + \nu_0^2)^2}}_{(M^2 + \nu_0^2)^2} \end{aligned}$$

$${}^2\underline{\Omega} = d{}^{(2)}\underline{\omega} + {}^{(2)}\underline{\omega} \wedge {}^{(2)}\underline{\omega} = \begin{bmatrix} 0 & \frac{M^2 \nu_0^2}{(M^2 + \nu_0^2)^2} dM \wedge d\varphi \\ -\frac{1}{M^2 + \nu_0^2} dM \wedge d\varphi & 0 \end{bmatrix}$$

$${}^{(2)}R^\varphi_{MM\varphi} = -\frac{1}{M^2 + \nu_0^2}$$

$${}^{(2)}R^M_{\varphi M\varphi} = \frac{M^2 \nu_0^2}{(M^2 + \nu_0^2)^2}$$

$${}^{(2)}R_{\varphi MM\varphi} = -\frac{M^2 \nu_0^2}{(M^2 + \nu_0^2)}$$

$${}^{(2)}R_{MM\varphi\varphi} = \frac{M^2 \nu_0^2}{(M^2 + \nu_0^2)} = -{}^{(2)}R_{\varphi M\varphi M}.$$

$$({}^{(2)}g_{\alpha\beta} {}^{(2)}R^\varphi_{MM\varphi})$$

$$({}^{(2)}g_{\alpha\beta} {}^{(2)}R^M_{\varphi M\varphi})$$

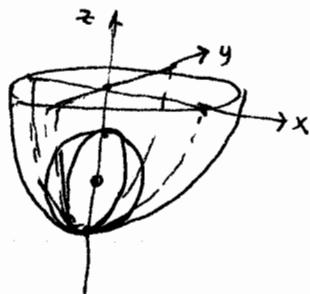
$$12) \quad {}^{(2)}R^A_{\hat{\alpha}\hat{\beta}\hat{\gamma}\hat{\delta}} = (g_{\alpha\beta})^{-1} {}^{(2)}R^M_{\varphi M\varphi} = \frac{1}{(M^2 + \nu_0^2)^2} \xrightarrow{\text{at } M=0} \boxed{\frac{1}{2\nu_0^4}}$$

$$(2) \quad z = \frac{1}{2\nu_0^2} p^2 - \frac{1}{2} \nu_0^2 \quad \frac{dz}{dp} = \frac{p}{\nu_0^2} \quad \frac{d^2z}{dp^2} = \frac{1}{\nu_0^2}$$

$$K = \frac{1/\nu_0^2}{[1 + p^2/\nu_0^4]^{3/2}} \quad K(p=0) = \frac{1}{\nu_0^2}.$$

The relationship is  $(^2R^{\alpha\beta})_{\gamma\delta} \hat{q}^{\mu\lambda} q(\alpha\lambda) = [K(p=0)]^2$

$$\text{so } (^2R^{\alpha\beta})_{\gamma\delta} = -2(^2K) \delta^{\alpha\beta}_{\gamma\delta}, \quad (^2K) = \frac{1}{(\mu^2 + \nu_0^2)^2}$$



At the vertex any orthogonal pair of vertical planes through the z-axis are the same and lead to 2 orthogonal osculating circles of best fit to those parabolas with the same radius and center.

The "2-curvature"  $(^2K) = R^{\hat{q}} q^{\mu\lambda} q$  there is just the product of these two "1-curvatures"  $K = \frac{1}{\nu_0^2}$ . (See page III.)

For very large  $\mu$  ( $\mu \gg \nu_0$ ), (so  $\frac{\mu^2}{\nu_0^4} = \frac{\mu^2 \nu_0^2}{\nu_0^4} = \frac{\mu^2}{\nu_0^2} \gg 1$ ) the horizontal cross-section ( $\varphi$ -coordinate circle of radius  $p = \mu \nu_0$ ) is a circle whose connecting vector from its center to the point of tangency is almost along the normal direction. Together with the osculating circle of the parabola vertical cross-section, one obtains two nearly orthogonal circles of best fit:



$$K_{\text{circle}} = \frac{1}{p} = \frac{1}{\mu \nu_0}$$

$$K_{\text{parabola}} = \frac{1}{\nu_0^2} \left[ 1 + \frac{p^2}{\nu_0^4} \right]^{3/2} \approx \frac{1}{\nu_0^2 \left( \frac{p^2}{\nu_0^4} \right)^{3/2}} = \frac{\nu_0^4}{p^3} = \frac{\nu_0^4}{(\mu \nu_0)^3} = \frac{\nu_0}{\mu^3}$$

$$K_{\text{circle}} K_{\text{parabola}} \approx \left( \frac{1}{\mu \nu_0} \right) \left( \frac{\nu_0}{\mu^3} \right) = \frac{1}{\mu^4} \quad \text{approximately equal.}$$

$$(^2K) = \frac{1}{(\mu^2 + \nu_0^2)^2} \approx \frac{1}{\mu^4}$$

$\mu$  lines

$$(3) \quad \begin{aligned} \mu &= \lambda & \mu' &= 1 & \mu'' &= 0 \\ \varphi &= \varphi_0 & \varphi' &= 0 & \varphi'' &= 0 \end{aligned}$$

$$\left. \begin{aligned} \frac{D^2\mu}{d\lambda^2} &= \underbrace{\mu''}_{0} + \underbrace{\Gamma^{\mu}_{\alpha\beta}\frac{d\bar{x}^\alpha}{d\lambda}\frac{d\bar{x}^\beta}{d\lambda}}_{\Gamma^{\mu}_{\alpha\beta} = \frac{\mu}{\mu^2 + v_0^2}} \\ \frac{D^2\varphi}{d\lambda^2} &= \underbrace{\varphi''}_{0} + \underbrace{\Gamma^{\varphi}_{\alpha\beta}\frac{d\bar{x}^\alpha}{d\lambda}\frac{d\bar{x}^\beta}{d\lambda}}_{0} = 0 \end{aligned} \right\}$$

$$\frac{D^2\bar{x}^\alpha}{d\lambda^2} = \underbrace{\left(\frac{\mu}{\mu^2 + v_0^2}\right)}_{\text{proportional to tangent vector}} \frac{d\bar{x}^\alpha}{d\lambda}$$

so  $\lambda$  is nonaffine parametrization of geodesic.

$\varphi$  lines

$$\begin{aligned} \mu &= \mu_0 & \mu' &= 0 & \mu'' &= 0 \\ \varphi &= \lambda & \varphi' &= 1 & \varphi'' &= 0 \end{aligned}$$

$$\left. \begin{aligned} \frac{D^2\mu}{d\lambda^2} &= \underbrace{\mu''}_{0} + \underbrace{\Gamma^{\mu}_{\alpha\beta}\frac{d\varphi}{d\lambda}\frac{d\varphi}{d\lambda}}_{-\frac{\mu v_0^2}{\mu^2 + v_0^2}} = -\frac{\mu v_0^2}{\mu^2 + v_0^2} \\ \frac{D^2\varphi}{d\lambda^2} &= \underbrace{\varphi''}_{0} + \underbrace{\Gamma^{\varphi}_{\alpha\beta}\frac{d\varphi}{d\lambda}\frac{d\varphi}{d\lambda}}_{0} = 0 \end{aligned} \right\}$$

$$\frac{D^2\bar{x}^\alpha}{d\lambda^2} \neq \underbrace{-\frac{\mu v_0^2}{\mu^2 + v_0^2}}_{\text{not proportional}} \frac{d\bar{x}^\alpha}{d\lambda} \rightarrow \text{not geodesic.}$$

14) Evaluate  $C^{\hat{\varphi}}_{\hat{\mu}\hat{\varphi}}$  of part 7) at  $v=v_0$ :  $C^{\hat{\varphi}}_{\hat{\mu}\hat{\varphi}} = -\frac{1}{(\mu^2 + v_0^2)^{1/2}}$

$${}^{(2)}\Gamma^{\hat{\varphi}}_{\hat{\varphi}\hat{\mu}} = \frac{1}{2} \left( C_{\hat{\varphi}\hat{\mu}\hat{\varphi}} - C_{\hat{\varphi}\hat{\varphi}\hat{\mu}} + C_{\hat{\mu}\hat{\mu}\hat{\varphi}} \right) = -C_{\hat{\varphi}\hat{\mu}\hat{\varphi}} = \frac{1}{\mu(\mu^2 + v_0^2)^{1/2}} = -{}^{(2)}\Gamma^{\hat{\varphi}}_{\hat{\mu}\hat{\varphi}}$$

$${}^{(2)}\Gamma^{\hat{\varphi}}_{\hat{\mu}\hat{\mu}} = \frac{1}{2} \left( C_{\hat{\varphi}\hat{\mu}\hat{\mu}} - C_{\hat{\mu}\hat{\mu}\hat{\varphi}} + C_{\hat{\mu}\hat{\varphi}\hat{\mu}} \right) = 0 \text{ of course, antisym in outer indices.}$$

$${}^{(2)}\hat{\omega} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \frac{1}{\mu(\mu^2 + v_0^2)^{1/2}} (\mu v_0 d\varphi) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \left( \frac{v_0}{\mu^2 + v_0^2} \right)^{1/2} d\varphi ; {}^{(2)}\hat{\omega} \wedge {}^{(2)}\hat{\omega} = 0$$

$$d {}^{(2)}\hat{\omega} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \left( -\frac{1}{2} \frac{2\mu M}{(\mu^2 + v_0^2)^{3/2}} \right) d\mu \wedge d\varphi = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \frac{1}{(\mu^2 + v_0^2)^2} \omega^{\hat{\mu}\hat{\varphi}}$$

$${}^{(2)}R^{\hat{\mu}}_{\hat{\varphi}\hat{\mu}\hat{\varphi}} = \frac{1}{(\mu^2 + v_0^2)^2} .$$

$$\left[ {}^{(2)}\hat{\Omega} = d\hat{\omega} + {}^{(2)}\hat{\omega} \wedge {}^{(2)}\hat{\omega} \text{ also valid for} \right. \\ \left. \text{orthonormal frame or in general} \right. \\ \left. \text{any frame} \right]$$

$$14) b) \quad {}^{(2)}\nabla e_{\hat{m}} e_{\hat{m}} = \underbrace{\Gamma_{\hat{m}\hat{m}}^{\hat{m}}}_{0} e_{\hat{m}} + \underbrace{\Gamma_{\hat{m}\hat{q}}^{\hat{q}}}_{0} e_{\hat{q}} = 0$$

$${}^{(2)}\nabla e_{\hat{m}} e_{\hat{q}} = \underbrace{\Gamma_{\hat{m}\hat{q}}^{\hat{m}}}_{0} e_{\hat{m}} + \underbrace{\Gamma_{\hat{m}\hat{q}}^{\hat{q}}}_{0} e_{\hat{q}} = 0$$

so they are parallel transported along  $e_{\hat{q}}$  which is the unit tangent to the  $m$  coordinate lines. The first equality says  $e_{\hat{m}}$  is autoparallel along  $m$  & hence the curve must be a geodesic.

15) Yeah.

$$16) \quad \bar{x}^i = A^i_j(\bar{x}) x^j(x(\bar{x})) \quad \text{recall } x^2 + y^2 + z^2 = r^2 = \left(\frac{M^2 + v^2}{2}\right)^2$$

$$\begin{bmatrix} \bar{x}^m \\ \bar{x}^v \\ \bar{x}^q \end{bmatrix} = \begin{bmatrix} \frac{v^2}{r} & \frac{v^2}{r} & \frac{M}{r} \\ \frac{M}{r} & \frac{Mv}{r} & \frac{-v}{r} \\ -\frac{1}{Mv} & \frac{1}{Mv} & 0 \end{bmatrix} \begin{bmatrix} -MvS \\ MvC \\ \left(\frac{M^2 + v^2}{2}\right)^2 \end{bmatrix} = \begin{bmatrix} \frac{-Mv^2CS + Mv^2CS}{r} + \frac{M}{M^2 + v^2} \left(\frac{M^2 + v^2}{2}\right)^2 \\ \frac{-M^2vCS + M^2vCS}{r} - \frac{v}{M^2 + v^2} \left(\frac{M^2 + v^2}{2}\right)^2 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{M}{4} \left(\frac{M^2 + v^2}{2}\right)^2 \\ -\frac{v}{4} \left(\frac{M^2 + v^2}{2}\right)^2 \\ 1 \end{bmatrix}$$

$$\bar{x}_i = \dot{\bar{x}}_i(\bar{x}) A^{-1} j_i(\bar{x})$$

$$[\bar{x}_m \bar{x}_v \bar{x}_q] = \begin{bmatrix} -MvS & MvC & \left(\frac{M^2 + v^2}{2}\right)^2 \end{bmatrix} \begin{bmatrix} vC & Mv & -MvS \\ vS & Mv & MvC \\ M & -v & 0 \end{bmatrix}$$

$$= \begin{bmatrix} -Mv^2CS + Mv^2CS + \frac{M}{4} \left(\frac{M^2 + v^2}{2}\right)^2 & -M^2vCS + M^2vCS - \frac{v}{4} \left(\frac{M^2 + v^2}{2}\right)^2 & \left(\frac{M^2 + v^2}{2}\right)^2 \\ M & -v & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{M}{4} \left(\frac{M^2 + v^2}{2}\right)^2 & -\frac{v}{4} \left(\frac{M^2 + v^2}{2}\right)^2 & M^2v^2 \end{bmatrix} = (g_{mm} \bar{x}^m, g_{vv} \bar{x}^v, g_{qq} \bar{x}^q) \checkmark$$

$$\overline{(\nabla e_m \bar{x})}^i = \bar{x}_i ; m = \bar{x}_i , m + \bar{\Gamma}_m^i \bar{x}_j \bar{x}^j$$

$$\bar{x}^k = \frac{(M^2 + v^2)^2}{4} (MdM - vdv) + M^2v^2 d\varphi$$

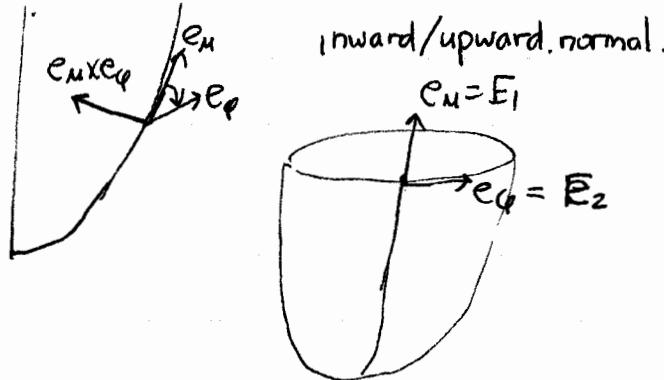
$$\bar{x}^m ; m = \underbrace{\bar{x}^m , m}_{\frac{1}{4}(3M^2 + v^2)} + \underbrace{\Gamma^m_{mm} \bar{x}^m}_{\frac{N}{M^2 + v^2}} + \underbrace{\Gamma^m_{mv} \bar{x}^v}_{\frac{v}{M^2 + v^2} - \frac{v}{4}(M^2v^2)} = \frac{1}{4}(3M^2 + v^2 + M^2 - v^2) = M^2$$

$$\bar{x}^v ; m = \underbrace{\bar{x}^v , m}_{-\frac{v}{4}(2M)} + \underbrace{\Gamma^v_{mm} \bar{x}^m}_{-\frac{v}{4} \frac{M(M^2v^2)}{(M^2+v^2)}} + \underbrace{\Gamma^v_{mv} \bar{x}^v}_{\frac{M}{(M^2+v^2)} \left(-\frac{v}{4}(M^2v^2)\right)} = \frac{1}{4}(-2Mv - Mv - Mv) = -Mv$$

$$\tilde{X}^{\mu} = \underbrace{X^{\mu}}_0 + \underbrace{\Gamma_{\mu\nu}^{\mu} X^{\nu}}_0 + \underbrace{\Gamma_{\mu\nu}^{\lambda} X^{\nu}}_0 + \underbrace{\Gamma_{\mu\nu}^{\rho} X^{\nu}}_{\frac{1}{\mu} I} = \frac{1}{\mu}$$

$$\nabla_{e_\mu} \tilde{X} = M^2 e_\mu - M^2 e_\nu + M^{-1} e_\rho.$$

17)



$E_1, E_2$  oriented,  $e_1$  outer so  $E_2$  gives induced orientation  
counterclockwise from above.

$\partial\Sigma$ :  $\begin{array}{ll} u = v_0 & u' = 0 \\ v = v_0 & v' = 0 \\ \varphi = \lambda & \varphi' = 1 \end{array}$   $0 \leq \lambda \leq 2\pi$  is an oriented parametrization of  $\partial\Sigma$ .

$$\begin{aligned} \int_{\partial\Sigma} \tilde{X}^v &= \int_{\partial\Sigma} \left( \frac{u^2 + v^2}{2} \right)^2 (u du - v dv) + M^2 v^2 d\varphi \\ &= \int_0^{2\pi} v_0^4 [ \textcircled{2} - 0 + \textcircled{3} d\lambda ] = 2\pi v_0^4 \end{aligned}$$

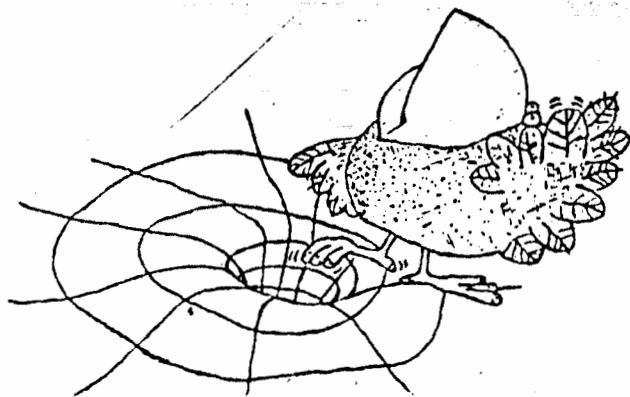
$$\begin{aligned} d\tilde{X}^v &= \underbrace{\frac{2}{4} (u^2 + v^2) (2v du \wedge u dv - 2u dv \wedge v du)}_{\textcircled{1}} + 2uv^2 du \wedge d\varphi \\ &\quad - \underbrace{\frac{uv(u^2 + v^2)}{2} du \wedge dv - \frac{1}{2} uv(u^2 + v^2) du \wedge dv}_{\textcircled{2}} \\ &\quad - \underbrace{2uv(u^2 + v^2) du \wedge dv}_{\textcircled{3}} \end{aligned}$$

$\begin{array}{ll} u = u^1 & 0 \leq u^1 \leq v_0 \\ v = v_0 & \\ \varphi = u^2 & 0 \leq u^2 \leq 2\pi \end{array} \} \text{ oriented parametrization of } \Sigma$

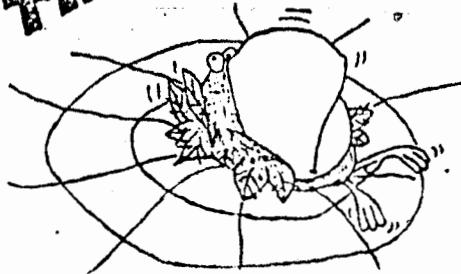
$$\begin{aligned} \int_{\Sigma} d\tilde{X}^v &= \iint_0^{2\pi} [ 0 + 2u^1 v_0^2 du^1 du^2 + 0 ] = 2\pi \int_0^{v_0} u^1 v_0^2 \Big|_0^{v_0} \\ &= 2\pi v_0^4 \checkmark \end{aligned}$$

The End (for real).

A takehome final or a blackhole...?



THREE/HAPPY!



Didnt mean to suck you into this group project  
at the end — there just wasnt enough time.

I know you are all anxious to take off.



Please read over these notes.  
Hope they made some impression.

— bob

( really, this is the last page )

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(for now)