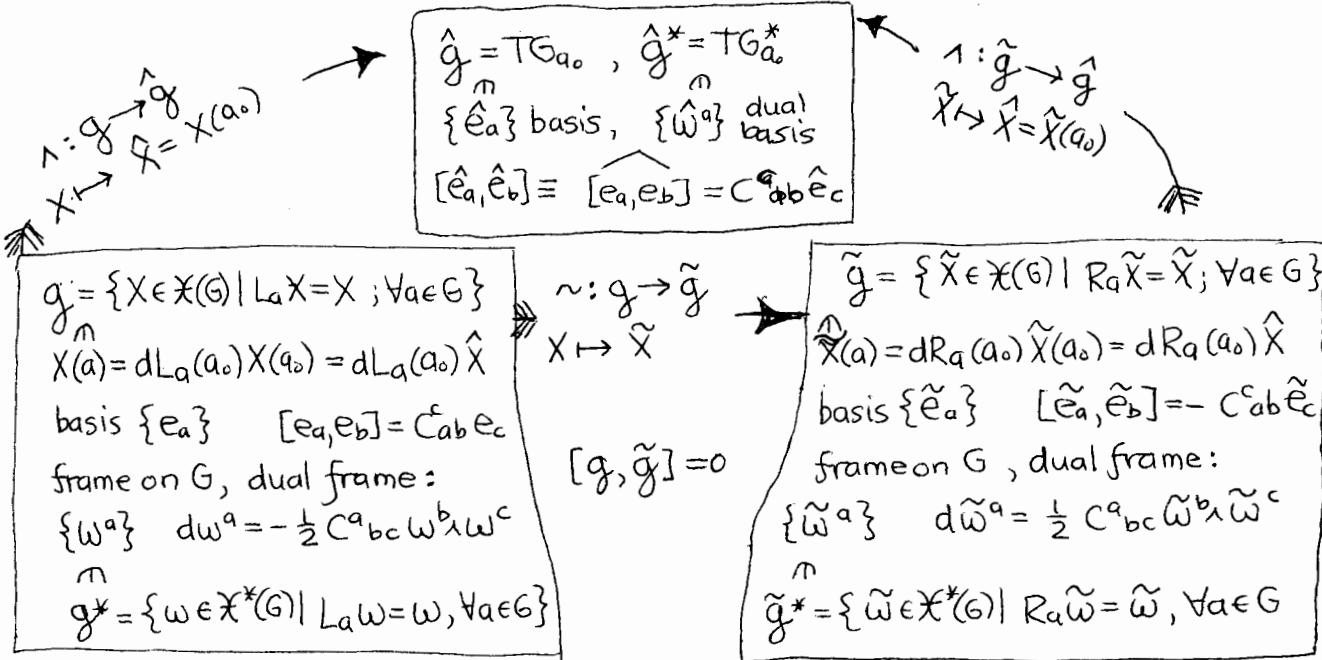


r -dimensional Lie group G , points a , identity a_0

Notes by Robert Jantzen (1)

$$\begin{array}{ll} \text{(left) translation by } a_1 \in G: & a \mapsto L_{a_1}(a) = a_1 a \\ & a \mapsto R_{a_1}(a) = a a_1 \\ \text{innerautomorphism:} & a \mapsto A D_{a_1}(a) = a_1 a a_1^{-1} = L_{a_1} \circ R_{a_1^{-1}}(a) = R_{a_1^{-1}}(a) \circ L_{a_1}(a) \end{array}$$

The Lie algebras $\hat{g} \cong g, \tilde{g}$ (\hat{g} and g are usually identified and called the Lie algebra of G)



$$X(a) = L_a(a_0)\hat{X} = L_a \circ R_{a^{-1}}(a)\tilde{X}(a) = AD_a(a)\tilde{X}(a) = (AD_a\tilde{X})(a)$$

$$Ad(a)\hat{e}_b \equiv (\widehat{AD_a e_b}) = Ad(a)^c{}_b \hat{e}_c \equiv R^c{}_b(a) \hat{e}_c$$

$$\Rightarrow (R_{a^{-1}} L_a e_b) = (\widehat{R_{a^{-1}} e_b})$$

$$\tilde{e}_a = e_b R^{-1}{}^b{}_a \quad \tilde{w}^a = R^a{}_b w^b \quad R^a{}_b = e_b \lrcorner \tilde{w}^a = \tilde{w}^a(e_b)$$

$$\underline{R}^{-1}d\underline{R} = \underline{R}^a w^a \quad d\underline{R} \underline{R}^{-1} = \underline{R} a \tilde{w}^a$$

$$\underline{R} \underline{R}^{-1} = \underline{R} b R^b{}_a \quad \underline{R}(\exp X^a \hat{e}_a) = e^{X^a \underline{R} a}$$

$$\exp: g \cong \hat{g} \rightarrow G \quad : \quad X \mapsto \exp X = X_1 a_0 = \tilde{X}_1 a_0$$

one-dimensional subgroups: $C_X(t) = \exp t X$.

fact: $AD_a(\exp X) = \exp Ad(a)X$

$$\begin{array}{l} \left(\begin{matrix} g \\ \hat{g} \\ \tilde{g} \end{matrix}\right) \text{ generate } \left(\begin{matrix} \text{right} \\ \text{left} \end{matrix}\right) \text{ translations:} \\ \boxed{X_t a = R \exp t X(a)} = (a \exp t X \lrcorner) = \text{Lexpt Ad}(a)X(a) \\ \boxed{\tilde{X}_t a = L \exp t X(a)} = \dots = \text{Rexpt Ad}(a)X(a) \end{array}$$

Thus through each point $a \in G$ passes a unique curve with tangent $Y \in TG_a$, namely the integral curve of either invariant vector field which coincides with Y at a , which in turn is a coset by a of the corresponding one-dimensional subgroups. These are the geodesics of a certain connection on G .

∇ and $\tilde{\nabla}$ are flat transpose connections, ie have ~~the~~ opposite torsion coinciding with the different tensor (in coordinates: $\Gamma^a_{bc} = \tilde{\Gamma}^a_{cb}$) and therefore the same geodesics and have zero curvature.

$\bar{\nabla}$ is the unique symmetric connection having same geodesics (described on the previous page)

$$\nabla_{e_a} e_b = C^c_{ab} e_c$$

components of

In frame $\{e_a\}$

components of connection:

$$\Gamma^a_{bc} = C^a_{bc}$$

connection one-form:

$$\underline{\sigma} = \underline{\omega}^a \underline{k}_a$$

torsion two-form:

$$\underline{\Omega} = d\underline{\omega} + \underline{\sigma} \wedge \underline{\omega} = \frac{1}{2} \underline{\sigma} \wedge \underline{\omega}$$

curvature two-form:

$$\underline{\Omega} = d\underline{\sigma} + \underline{\sigma} \wedge \underline{\sigma} = 0$$

In frame $\{\tilde{e}_a\}$

$$(\underline{\Omega})^\sim = R \cancel{\underline{\Omega}} \cancel{\underline{\Omega}} \cancel{\underline{\Omega}} \cancel{\underline{\Omega}} \cancel{\underline{\Omega}} \cancel{\underline{\Omega}} = -\tilde{\underline{\Omega}}$$

$$(\underline{\Omega})^\sim = R(dR^{-1} + \underline{\sigma} R^{-1}) = 0$$

ie $\nabla \tilde{e}_a = 0$

so ∇ -parallel transport is just right translation

$$\bar{\nabla}_{\tilde{e}_a} e_b = \frac{1}{2} C^c_{ab} e_c$$

In frame $\{e_a\}$

$$\bar{\Gamma}^a_{bc} = \frac{1}{2} C^a_{bc}$$

$$\bar{\Omega} = \frac{1}{2} \bar{\omega}^a \bar{k}_a$$

$$\bar{\Omega} = d\bar{\omega} + \bar{\Omega} \wedge \bar{\omega} = 0$$

$$\begin{aligned} \bar{\Omega} &= d\bar{\omega} + \bar{\Omega} \wedge \bar{\omega} \\ &= \frac{1}{8} R e C^e_{ab} \bar{\omega}^a \bar{\omega}^b \end{aligned}$$

$$\bar{R}^c_{dab} = -\frac{1}{4} C^c_{ed} C^e_{ab}$$

Ricci tensor:

$$\bar{R}_{db} = \bar{R}^c_{dc} \bar{R}_{cb} = -\frac{1}{4} \gamma_{db}$$

components of adjoint invariant Killing form:

$$\chi_{ab} = C^f_{ag} C^g_{bf}; \quad R^T \chi R = \chi, \quad \chi k_a + (\chi k_a)^T = 0$$

$$\tilde{\nabla}_{\tilde{e}_a} \tilde{e}_b = -C^c_{ab} \tilde{e}_c$$

In frame $\{\tilde{e}_a\}$

$$\tilde{\Gamma}^a_{bc} = -C^a_{bc}$$

$$\tilde{\Omega} = -\tilde{\omega}^a \tilde{k}_a$$

$$\tilde{\Omega} = d\tilde{\omega} + \tilde{\Omega} \wedge \tilde{\omega} = -\frac{1}{2} \tilde{\Omega} \wedge \tilde{\omega}$$

$$\tilde{\Omega} = d\tilde{\omega} + \tilde{\Omega} \wedge \tilde{\omega} = 0$$

In frame $\{e_a\}$

$$(\tilde{\Omega})^\sim = R^{-1} \tilde{\Omega} = -\underline{\Omega}$$

$$(\tilde{\Omega})^\sim = R^{-1} (dR + \tilde{\Omega} R) = 0$$

ie $\tilde{\nabla} e_a = 0$
so $\tilde{\nabla}$ -parallel transport is just left translation

Compatible metric g ($\nabla g = \bar{\nabla} g = \tilde{\nabla} g = 0$) \leftrightarrow bi-invariant \leftrightarrow adjoint invariant

$$g = g_{ab} \omega^a \otimes \omega^b = g_{ab} \tilde{\omega}^a \otimes \tilde{\omega}^b$$

$$R^T g R = g$$

$$\left\{ \begin{array}{l} 0 = \nabla g_{ab} = dg_{ab} - 2 C^c_{cc(a} g_{b)} e \omega^c = (L_{e,c} g)_{ab} \omega^c \\ 0 = \bar{\nabla} g_{ab} = dg_{ab} - C^c_{cc(a} g_{b)} e \omega^c = \\ 0 = \tilde{\nabla} g_{ab} = dg_{ab} \end{array} \right\} \rightarrow dg_{ab} = 0 = \underbrace{C_{cc(a} c_{b)}}_{g_{ab} + (g_{ab})^T} = 0.$$

Since $\bar{\nabla}$ is symmetric and $\bar{\nabla} g = 0$, it is the connection generated by g .

For semi-simple groups the Killing form is nondegenerate (and the adjoint group unimodular: $0 = \text{TR } k_a = C^b_{ab}$) and hence determines a bi-invariant metric : $g_{ab} = -1/2 \gamma_{ab}$.

We include a minus since compact groups have negative definite Killing forms and a $1/2$ so $g_{ab} = \delta_{ab}$ when a "canonical basis" is chosen in this case (at least for $r=3$).

For abelian groups $C^a_{abc} \equiv 0$ and the adjoint group is trivial (the identity) so g arbitrary is satisfactory. (for example $g_{ab} = \delta_{ab}$).

No other groups have nondegenerate bi-invariant metrics.

Hence: $R_{ab} = \begin{cases} \frac{1}{2} g_{ab} & \text{semi-simple} \\ 0 & \text{abelian} \end{cases}$ scalar curvature: $\begin{cases} r/2 & \text{semi-simple} \\ 0 & \text{abelian} \end{cases}$

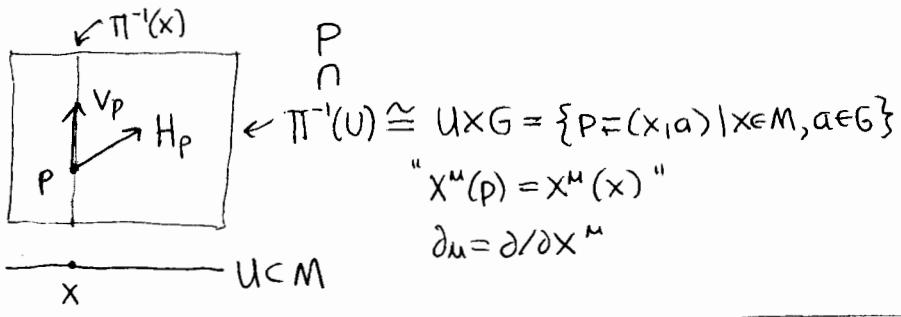
(EXCEPT FOR DIRECT PRODUCT GROUPS WITH ANY NUMBER OF FACTOR MANIFOLDS OF THESE TYPES.)

"TRIVIAL LOCAL COMPUTATION"

Notes by Robert Jantzen ③

Consider a principal bundle P over base manifold $M = \text{spacetime}$ with Yang-Mills group G acting on the fibers on the right (so that in a local trivialization this action becomes right translation). The generators of this action called fundamental vector fields (left invariant vector fields in a local trivialization) span the vertical subspaces. The horizontal subspaces are picked out by a connection on P .

For simplicity we assume from the start a local trivialization over $U \subset M$ which is a coordinate patch for local coordinates $\{x^\mu\}$ on M . These naturally lift up to ~~co~~ part of a local coordinate system $\{\tilde{x}^\mu\}$ on $U \times G$: [We indulge in many identifications].



$$\text{Define } A^a = A_{\mu}^a dx^\mu \quad A = A^a \hat{e}_a$$

$$F = F^a \hat{e}_a = dA + A \wedge A \quad \hat{F}^a = R^{-1}{}^a{}_b F^b \quad \hat{A}^a = R^{-1}{}^a{}_b A^b$$

Introduce the natural frame: $\{D_\mu\} = \{D_\mu, \xi_a\}$
Its dual frame: $\{W^\mu\} = \{dx^\mu, \bar{A}^a = w^a + \hat{A}^a\}$

The connection form is: $\bar{A} = \bar{A}^a \hat{e}_a$

It annihilates H_p and maps V_p onto the Lie algebra of G : $\bar{A}(X^a \xi_a) = X^a \hat{e}_a$.

The curvature form is: $\bar{F} = d\bar{A} + \bar{A} \wedge \bar{A} = \hat{F}^a \hat{e}_a$

The structure functions $C^a{}_{bc}$ for this frame:

$$[D_\mu, D_\nu] = -\hat{F}^c{}_{\mu\nu} \xi_c$$

$$[D_\mu, \xi_a] = 0$$

$$[\xi_a, \xi_b] = C^c{}_{ab} \xi_c$$

$$\begin{aligned} C^c{}_{\mu\nu} &= -\hat{F}^c{}_{\mu\nu} \\ C^c{}_{ab} &= C^c{}_{ba} \end{aligned}$$

Metric on P We can pull up the spacetime metric $g^{(4)}$ on M to an inner product on each horizontal subspace H_p and complete it to a metric on P by requiring $V_p \perp H_p$ and the inner product of elements of V_p to be the killing inner product of the corresponding elements of \hat{g} up to a factor as on the previous page (any inner product on an abelian group):

$$\bar{g} = \underbrace{g_{\mu\nu}(x) dx^\mu \otimes dx^\nu}_{\Pi^* g^{(4)}} + \underbrace{g_{ab} \bar{A}^a \otimes \bar{A}^b}_{\text{horizontal metric}}$$

$$\bar{g}(X, Y) = g(\bar{A}(X), \bar{A}(Y)) \quad X, Y \in V_p$$

The restriction of the metric to a fiber makes the fiber isometric to the pseudo-Riemannian manifold of the previous page.

The volume form on P is just the exterior product of the spacetime volume form with the volume form on the fiber:

$$\begin{aligned} \bar{n} &= \sqrt{|\det(g_{AB})|} W^0 \wedge \dots \wedge W^a \wedge W^1 \wedge \dots \wedge W^r = |\bar{g}|^{1/2} |\det(g_{ab})|^{1/2} dx^0 \wedge \dots \wedge dx^r \wedge \dots \wedge dx^a \\ &\quad = n_{ST} \wedge n_{\text{fiber}} \end{aligned}$$

Components of Metric Connection in our frame.

Notes by Robert Jantzen (4)

$$\bar{\Gamma}^c_{AB} = \frac{1}{2} g^{CD} (D_A g_{DB} + D_B g_{DA} - D_D g_{AB}) + \frac{1}{2} g^{CD} (g_{AE} C^E_{DB} + g_{BE} C^E_{DA}) + \frac{1}{2} C^c_{AB}$$

nonzero components:

$\bar{\Gamma}^x_{AB} = \{ \bar{\Gamma}^x_{AB} \}$	$\bar{\Gamma}^x_{AB} = \bar{\Gamma}^x_{BA} = -\frac{1}{2} \tilde{F}_a \bar{\Gamma}^x_B$	$\bar{\Gamma}^c_{AB} = \left(\frac{1}{2} \right) C^c_{AB}$
$\bar{\Gamma}^c_{AB} = -\frac{1}{2} \tilde{F}^c_{AB}$		

Scalar curvature:

$$\bar{R} = \bar{g}^{AB} \bar{R}_{AB} = \dots = \underbrace{R_{ST.} - \frac{1}{4} F_a^{\alpha\beta} F^a_{\alpha\beta}}_{\text{function only of } x.} + R_{FIBER}$$

$\begin{cases} r \\ 2 \\ 0 \end{cases}$ semi-simple
 $\begin{cases} 0 \end{cases}$ abelian

multiply by ± 2 and connection on fiber becomes D or \tilde{D} which are flat and have zero scalar curvature

By introducing torsion on the fiber, the scalar curvature density Lagrangian becomes:

$$L = \bar{R} n = [(\underbrace{L_{EINSTEIN} + L_{Y.M.}}_{\text{Independent of fiber coordinates.}})^{(4)} n] \wedge n_{FIBER}$$

(for the bundle metric with torsion on fiber)

The Einstein equations (Ricci tensor = 0) are therefore the combined gravitational and Yang-Mills field equations.

Bonus

Geodesics on P (some for metric connection or with added torsion on fiber)

Let $\bar{C}(t) = (x(t), q(t))$ be a geodesic with tangent:

$$\bar{C}'(t) = \bar{C}'^A(t) D_A \quad \left\{ \begin{array}{l} \bar{C}'^M(t) = \frac{dx^M}{dt}(t) \\ \bar{C}'^a(t) = \bar{A}^a(C'(t)) = \omega^a(a'(t)) + R^a_b(a(t)) A^b_M(x(t)) \frac{dx^M}{dt} \end{array} \right.$$

$$0 = \frac{d\bar{C}'^M}{dt} + \bar{\Gamma}^M_{AB} \bar{C}'^A \bar{C}'^B = \frac{d^2x^M}{dt^2} + \bar{\Gamma}^M_{\alpha\beta} dx^\alpha \frac{dx^\beta}{dt} + \underbrace{2\bar{\Gamma}^M_{\alpha\beta} dx^\alpha \bar{C}'^a}_{-\tilde{F}_a^\alpha dx^\alpha} \frac{dx^a}{dt} \equiv \dot{q}^M(t)$$

$$0 = \frac{d\bar{C}'^a}{dt} + \underbrace{\bar{\Gamma}^a_{AB} \bar{C}'^A \bar{C}'^B}_V \equiv 0$$

so $\bar{C}'^a = q^a$ is constant along the geodesic (the vertical component of the tangent vector)

Define the components of the charge vector (really charge/mass vector):

$$Q^a(t) = R^a_b(t) q^b$$

Then:

$$\frac{d^2x^M(t)}{dt^2} = Q^a(t) F_a^M \alpha(x(t)) \frac{dx^a}{dt}$$

"Lorentz force law"

$$Q^a = \tilde{\omega}^a(a'(t)) + A^a(x'(t))$$

$$\frac{dQ^a}{dt} = \frac{dR^a_b}{dt} q^b = \frac{dR^a_b}{dt} R^b_a Q^b = \tilde{\omega}^a(a'(t)) R^b_a Q^b = [-A^a(x'(t)) + Q^a(t)] k_a Q$$

$$\frac{dQ^a}{dt} + A^c C^a_{cb} Q^b = C^a_{cb} Q^c Q^b = 0$$

$$\frac{dQ^a(t)}{dt} = 0$$

G-gauge covariant derivative.

charge vector parallel transported along trajectory on spacetime.

Presumably these equations describe a test Yang-Mills particle on this spacetime.

CONTINUATION OF PRINCIPAL FIBER BUNDLE NOTES (including explicit computational techniques)

We now generalize by relaxing bi-invariance of the induced metric on the fiber to merely right invariance (maintaining the orthogonality of the horizontal and vertical subspaces) so that the bundle metric \bar{g} is invariant under the right action of G on P , i.e. $\mathcal{L}_{\xi_a} \bar{g} = 0$.

In the locally trivial notation of pages 3 and 4:

$$\bar{g} = g_{uv}(x) dx^u \otimes dx^v + g_{ab} \bar{A}^a \otimes \bar{A}^b, \quad g_{ab} = \tilde{g}_{cd}(x) R^c_a R^d_b$$

$$\bar{g}|_{\pi^{-1}(x)} = \tilde{g}_{cd} \tilde{w}^c \otimes \tilde{w}^d = \text{manifestly right invariant.}$$

To evaluate the connection components in the frame $\{D_A\}$ we have to compute the derivatives $D_c g_{ab}$ and $D_u g_{ab}$; first a matrix calculation with ~~d~~ differentiating only along the fiber:

$$\underline{g} = \underline{R}^T \underline{\tilde{g}} \underline{R} \quad \begin{matrix} \leftarrow \\ \text{transpose} \end{matrix} \quad (\text{underline indicates matrix})$$

$$dg = \underline{R}^T \underline{\tilde{g}} \underline{R} \underline{R}' d\underline{R} + (\underline{R}' d\underline{R})^T \underline{R}^T \underline{\tilde{g}} \underline{R}$$

$$\underline{g} = \underline{g}^T$$

$$= (\underline{g} \underline{k} \underline{a} + (\underline{g} \underline{k} \underline{a})^T) \underline{w}^a$$

$$D_c \underline{g} = e_c \lrcorner dg = \underline{g} \underline{k} \underline{a} + (\underline{g} \underline{k} \underline{a})^T$$

$$\boxed{D_c g_{ab} = g_{ad} C^d_{eb} + g_{bd} C^d_{ea}}$$

$$= 2 C_{(a|c|b)}$$

$$dg = \underline{R}^T \underline{\tilde{g}} \underline{dR} \underline{R}' \underline{R} + \underline{R}^T (\underline{dR} \underline{R}')^T \underline{\tilde{g}} \underline{R}$$

$$\underline{g} = \underline{g}^T$$

$$= \underline{R}^T (\underline{\tilde{g}} \underline{k} \underline{a} + (\underline{\tilde{g}} \underline{k} \underline{a})^T) \underline{R} \underline{w}^a$$

$$\tilde{e}_c \underline{g} = \tilde{e}_c \lrcorner dg = \underline{R}^T (\underline{\tilde{g}} \underline{k} \underline{a} + (\underline{\tilde{g}} \underline{k} \underline{a})^T) \underline{R}$$

$$\tilde{e}_c g_{ab} = R^d_a R^e_b (\tilde{g}_{ad} C^d_{eb} + \tilde{g}_{bd} C^d_{ea})$$

$$= R^d_a R^e_b (2 \tilde{C}_{(d|e|b)})$$

$$\boxed{D_u g_{ab} = R^e_a R^f_b (d_u \tilde{g}_{ab} - 2 A^e_u \tilde{C}_{(a|e|b)})}$$

$$= R^c_a R^d_b \overset{G}{\nabla}_u \tilde{g}_{ab}$$

These are both special cases of a general formulas.

Suppose $T^{a...b...c...}(x)$ are the components of a tensor field on the base which transforms under the indicated tensor product of the adjoint representation under gauge transformations. Then define ~~notation~~

$$\tilde{T}^{a...b...c...} = R^{-1}{}^a_c R^d_b T^{c...d...}$$

$$D_e \tilde{T}^{a...b...c...} = - C^a_d c \tilde{T}^c d ... + C^c_d b \tilde{T}^a d ...$$

$$D_u \tilde{T}^{a...b...c...} = R^{-1}{}^a_c R^d_b \overset{G}{\nabla}_u T^{c...d...}$$

(This is even a special case of formulas for representation-valued fields of any kind.)

[↑] no ~~Christoffel symbols summed~~ on greek indices

For example:

$$D_a \tilde{F}^c_{ab} = - C^c_d a \tilde{F}^d_{ab}, \quad D_u \tilde{F}^c_{ab} = R^{-1}{}^c_d (d_u F^c_{ab} + A^d_u C^e_d F^c_{eb})$$

$$D_a \tilde{F}^c_{cb} = C^d_{ac} \tilde{F}^c_{db}, \quad D_u \tilde{F}^c_{cb} = R^d_c (d_u F^c_{db} - A^d_u C^e_d F^c_{eb})$$

Now we use the standard formula to compute the components of the metric connection in the frame $\{D_A\}$:

$$\tilde{\Gamma}^c_{AB} = \frac{1}{2} g^{cd} (D_A g_{dB} + D_B g_{dA} - D_d g_{AB}) + \frac{1}{2} g^{cd} (g_{AE} C^E_{dB} + g_{BE} C^E_{dA}) + \frac{1}{2} C^c_{AB}$$

Since we know C^E_{AB} from page 3 & only $g_{uv}, g_{ab}, g^{uv}, g^{ab}$ are nonzero & we just evaluated $D_u g_{ab}, D_v g_{ab}$, with $D_u g_{uv} = \cancel{D_u g_{uv}}$ & $D_v g_{uv}$ the only remaining nonzero derivatives, it is just a matter of plugging in. The result (nonzero components):

$\tilde{\Gamma}^x_{dB} = \{x_B\}$	}
$\tilde{\Gamma}^c_{ab} = \frac{1}{2} C^c_{ab} - C(a^c_b)$	

$\tilde{\Gamma}^x_{aB} = \tilde{\Gamma}^x_{Ba} = -\frac{1}{2} \tilde{F}_a^x x_B$	}
$\tilde{\Gamma}^c_{aB} = -\frac{1}{2} \tilde{F}^c_{aB}$	

$\tilde{\Gamma}^x_{ab} = -\frac{1}{2} g^{x\delta} D_\delta g_{ab}$	}
$\tilde{\Gamma}^c_{ab} = \tilde{\Gamma}^c_{Ba} = \frac{1}{2} g^{cd} D_B g_{da}$	

$$\tilde{\Gamma}^c_{cb} = 0$$

{ the minus sign arises since we are expressing the components of a right invariant connection on the fiber in a left invariant frame (locally trivial language) }

$$g_F = \det(g_{ab}) = \det(\tilde{g}_{ab})$$

because $\det R = 1 \uparrow$ since G is unimodular

$$\tilde{\Gamma}^{x_0}_a = -\frac{1}{2} g^{x\delta} g_{ab}^{ab} D_\delta g_{ab}$$

$$= -\frac{1}{2} g^{x\delta} D_\delta \ln g_F^{1/2}$$

$$\tilde{\Gamma}^a_{Ba} = \tilde{\Gamma}^a_{aB} = \frac{1}{2} g^{ad} D_B g_{da} = D_B \ln g_F^{1/2}$$

$$g^{ab} D_B g_{ab} = \tilde{g}^{ab} (D_B \tilde{g}_{ab} - 2 A_B^e C_{ea}^b)$$

$$= D_B \ln \tilde{g}_F - 2 A_B^e C_{ea}^b$$

To evaluate Ricci tensor components we need in addition $D_E \tilde{\Gamma}^c_{AB}$. The only nonzero such derivatives are:

$$D_\delta \tilde{\Gamma}^x_{ab} = D_\delta \{x_B\} \quad \text{etc...}$$

fill in yourself.

The components of the Ricci tensor of \bar{g} in the frame $\{\mathbf{D}_A\}$ are:

$$\bar{R}_{DB} = D_A \bar{\Gamma}^A_{DB} - D_D \bar{\Gamma}^A_{AB} - \bar{\Gamma}^A_{EB} C^E_{AD} + \bar{\Gamma}^A_{AE} \bar{\Gamma}^E_{DB} - \bar{\Gamma}^A_{DE} \bar{\Gamma}^E_{AB}$$

$$\begin{aligned}\bar{R}_{DB} &= D_A \bar{\Gamma}^A_{SB} - D_S \bar{\Gamma}^A_{AB} - \bar{\Gamma}^A_{EB} C^E_{AD} + \bar{\Gamma}^A_{AE} \bar{\Gamma}^E_{SB} - \bar{\Gamma}^A_{SE} \bar{\Gamma}^E_{AB} \\ &= R_{DB} - \underbrace{D_S \bar{\Gamma}^a_{ab}}_{\nabla_S \bar{\Gamma}^a_{ab}} + \underbrace{\Gamma^a_{ae} \bar{\Gamma}^e_{sb}}_{-\Gamma^a_{se} \bar{\Gamma}^e_{ab}} - \underbrace{\bar{\Gamma}^a_{ab} C^a_{ad}}_{-\Gamma^a_{ab} C^a_{ad}} \\ &= R_{DB} - \underbrace{\nabla_S \bar{\Gamma}^a_{ab}}_{-\frac{1}{4} g^{ad} D_S g_{de} g^{ef} D_S g_{fa}} - \underbrace{\frac{1}{4} g^{ad} g^{ef} \nabla_S \bar{\Gamma}^a_{de} \nabla_S \bar{\Gamma}^e_{fb}}_{-\frac{1}{4} \tilde{g}^{ad} \tilde{g}^{ef} \nabla_S \bar{\Gamma}^a_{de} \nabla_S \bar{\Gamma}^e_{fb}} \\ &\quad - \frac{1}{4} \nabla_S \nabla_B (\ln \tilde{g}_F^{-2})\end{aligned}$$

$$g^{BD} \bar{R}_{DB} = R - \frac{1}{2} F_a{}^{\alpha B} F^a{}_{\alpha B} - \frac{1}{4} \tilde{V}^\alpha \tilde{V}_\alpha (\ln \tilde{g}_F^{-2}) - \frac{1}{4} \tilde{g}^{ad} \tilde{g}^{ef} \tilde{V}^\alpha \tilde{g}_{de} \tilde{V}_\alpha \tilde{g}_{ef}$$

$$\begin{aligned}\bar{R}_{db} &= D_A \bar{\Gamma}^A_{db} - D_d \bar{\Gamma}^A_{Ab} - \bar{\Gamma}^A_{Eb} C^E_{Ad} + \bar{\Gamma}^A_{Af} \bar{\Gamma}^E_{db} - \bar{\Gamma}^A_{de} \bar{\Gamma}^E_{Ab} \\ &= (D_a \bar{\Gamma}^a_{db} - D_d \bar{\Gamma}^a_{ab} - \bar{\Gamma}^a_{eb} C^e_{ad} + \bar{\Gamma}^a_{ae} \bar{\Gamma}^e_{db} - \bar{\Gamma}^a_{de} \bar{\Gamma}^e_{ab}) \\ &\quad - \underbrace{\bar{\Gamma}^a_{de} \bar{\Gamma}^e_{ab}}_{\frac{1}{4} \tilde{F}_d{}^e \tilde{F}_{ba}^e} + D_a \bar{\Gamma}^a_{db} + (\bar{\Gamma}^a_{ae} + \bar{\Gamma}^a_{de}) \bar{\Gamma}^c_{db} - \underbrace{\bar{\Gamma}^a_{de} \bar{\Gamma}^e_{ab}}_{R_d^c R_b^e (\frac{1}{2} \tilde{g}^{sf} \tilde{V}_a \tilde{g}_f \tilde{V}^b \tilde{g}_{bs})} \\ &\quad + \frac{1}{4} R_d^c R_b^e F_f{}^{ab} F_g{}^{cb} \\ &= R_d^c R_b^e (-\frac{1}{2} \tilde{V}_a \tilde{V}^b \tilde{V}_b \tilde{g}_{ab}) \\ &\quad - \frac{1}{2} R_d^c R_b^e (-\frac{1}{2} \tilde{V}_a (\ln \tilde{g}_F^{-2}) \tilde{V}^\alpha \tilde{g}_{ce}) \\ &= R_d^c R_b^e \left(\tilde{R}_{db} + \frac{1}{4} F_c{}^{\alpha B} F_{\alpha B} - \frac{1}{2} \tilde{g}_F^{-1/2} \tilde{V}_a (\tilde{g}_F^{-1/2} \tilde{V}^\alpha \tilde{g}_{ce}) + \frac{1}{2} \tilde{g}^{fg} \tilde{V}_d \tilde{g}_{fc} \tilde{V}^\alpha \tilde{g}_{eg} \right)\end{aligned}$$

missing in Tabensky

$$g^{bd} \bar{R}_{db} = \tilde{R}_F + \frac{1}{4} F_a{}^{\alpha B} F^a{}_{\alpha B} - \frac{1}{2} \tilde{g}_F^{-1/2} \tilde{V}_a (\tilde{g}_F^{-1/2} \tilde{V}^\alpha \tilde{g}_{ab}) \tilde{g}^{ab} + \frac{1}{2} \tilde{g}^{ab} \tilde{g}^{cd} \tilde{V}_d \tilde{g}_{ac} \tilde{V}^\alpha \tilde{g}_{bd}$$

$$\bar{R} = R + \tilde{R}_F - \frac{1}{4} F_a{}^{\alpha B} F^a{}_{\alpha B} - \frac{1}{4} \tilde{V}_a \tilde{V}^\alpha (\ln \tilde{g}_F^{-2}) - \frac{1}{2} \tilde{g}_F^{-1/2} \tilde{V}_a (\tilde{g}_F^{-1/2} \tilde{V}^\alpha \tilde{g}_{ab}) \tilde{g}^{ab} + \frac{1}{4} \tilde{g}^{ab} \tilde{g}^{cd} \tilde{V}_d \tilde{g}_{ac} \tilde{V}^\alpha \tilde{g}_{bd}$$

$$\begin{aligned}\bar{R}_{db} &= D_A \bar{\Gamma}^A_{db} - D_d \bar{\Gamma}^A_{Ab} - \bar{\Gamma}^A_{Eb} C^E_{Ad} + \bar{\Gamma}^A_{Af} \bar{\Gamma}^E_{db} - \bar{\Gamma}^A_{de} \bar{\Gamma}^E_{Ab} \\ &= -\frac{1}{2} D_d \tilde{F}_d{}^a{}_\beta + D_a \bar{\Gamma}^a_{db} - \bar{\Gamma}^a_{eb} C^e_{ad} + \bar{\Gamma}^a_{ae} \bar{\Gamma}^c_{db} + \bar{\Gamma}^a_{de} \bar{\Gamma}^e_{db} - \bar{\Gamma}^a_{de} \bar{\Gamma}^e_{ab} - \bar{\Gamma}^a_{de} \bar{\Gamma}^e_{ab} \\ &= R_d^a (-\frac{1}{2} \tilde{V}_d \tilde{F}_d{}^a{}_\beta - \frac{1}{2} F_d{}^a{}_\beta \tilde{V}_d \ln \tilde{g}_F^{-2}) + \frac{1}{2} \tilde{g}^{bc} \tilde{V}_d \tilde{g}_{ab} F_c{}^a{}_\beta \\ &\quad + \frac{1}{2} \tilde{g}^{bc} \tilde{V}_d \tilde{g}_{ab} \tilde{F}_c{}^a{}_\beta \\ &\quad + \frac{1}{2} \tilde{g}^{bc} \tilde{V}_d \tilde{g}_{ab} (-\frac{1}{2} \tilde{F}_d{}^a{}_\beta \tilde{V}_d \tilde{g}_{bc}) \\ &\quad + \frac{1}{2} C^{bc}{}_\beta \tilde{V}_d \tilde{g}_{bc}\end{aligned}$$

(opposite sign relative to Tabensky
given that all F terms switch sign)

We thus have on spacetime, a field theory involving the spacetime metric, a gauge field $A^a dx^a$ and a ~~metric valued~~ Lie algebra inner product valued field with components \tilde{g}_{ab} . The end result should be identical to what Tabensky does without fiber bundles using an equivalent formalism living entirely on spacetime & not in a bundle over it.

I don't trust my computation completely (as it is 8:15 am) but neither do I trust either Tabensky or the typesetter. You have all the machinery to check every detail for yourself.

We have assumed the group G to be unimodular for this generalization.

(existence of a bi-invariant metric is no longer relevant). This is a necessary assumption in order that the ~~equation~~ Lagrange equation's are equivalent to $\text{Ricci}(\bar{g}) = 0$.

For a nonunimodular group the ^{Lagrange} equations ~~\tilde{g}_{ab}~~ are not equivalent to $\bar{R}_{AB} = 0$.

Wednesday, Sept. 21, 1978

Dear Arthur,

As I promised, I spent my first "day at the office" figuring out how Tabensky's junk relates to the principal bundle approach, and in so doing cleaned up my computational scheme for the latter approach. The results are sketched in a continuation of the notes I've already given you on principal fiber bundle computations. I hope you can decipher them. I'm waiting to hear from you about the stuff you mentioned on the phone. I hope I can still be of some further use to you. I will think about the variational problem next.

Just a cute side remark. The splitting up of the bundle into a four-parameter family of fibers is very similar to the slicing of spacetime into a one-parameter family of hypersurfaces. In adapted coordinates zero shift in the spacetime case corresponds to orthogonality of the horizontal and vertical subspaces (zero "supershift") in the bundle case.

$$K_{ab} = -\frac{1}{2} \overset{\circ}{V}_a g_{ab} \text{ corresponds to the extrinsic curvature}$$

$$K_{ab} = -\frac{1}{2N} \frac{\partial}{\partial t} g_{ab} \text{ in the spacetime case}$$

g_{ab} to be induced metric, $\overset{F}{R}$ to be hypersurface scalar curvature R^*

and the spacetime Lagrangian:

$$\begin{aligned} L &= 4R^{1/2} = 4RNg^{1/2} = -g_{ab}\overset{F}{V}^{ab} - Ng^{1/2}(TRK^2 - TR^2K - R^*) \\ &= -2(g^{1/2})^{..} + Ng^{1/2}(TRK^2 - TR^2K + R^*) \end{aligned}$$

to the fiber part of the bundle Lagrangian

$$-2\overset{\circ}{V}_a\overset{\circ}{V}^a(4g_F)^{1/2} + g_F^{1/2}(-TR^2K + TR^2K + \overset{F}{R})$$

etc.

I will be waiting patiently to hear from you again. I miss California weather. Among other things. But I've got an office in the basement next to the computers so I am assured the best airconditioning available.

bob jantzen

In this continuation we adopt a slight change in notation which is more consistent than above (just what you needed right) by introducing in a given local trivialization two frames: a barred "left invariant frame" $\{\bar{D}_A\} = \{D_\alpha, E_\alpha\}$ whose elements vertical elements are fundamental vector fields and an unbarred "right invariant frame" $\{D_A\} = \{D_\alpha, \tilde{E}_\alpha\}$ whose vertical elements are invariant under the right action of the group G on the fiber $\sim G$. In this local trivialization, $\{E_\alpha\}$ is just a left invariant frame on the group G and $\{\tilde{E}_\alpha\}$ is the corresponding right invariant frame (the right action of G on the bundle becomes right translation on G in the local trivialization and fundamental vector fields became left invariant vector fields on G .)

The right invariant frame has the advantage that components of fields which telescope along the fibers (i.e. have nice transformation properties under the right action of the group G on the bundle) depend only on the base point and are constant along the fibers.

So turn to page 3 of these notes and compare with our new notation. Again let $\{\hat{e}_\alpha\}$ be a basis of TG_e considered as the Lie algebra of G .

$$\{\bar{D}_A\} = \{D_\alpha, E_\alpha = \tilde{E}_\alpha\}$$

dual frame:

$$\{\bar{W}^A\} = \{dx^\alpha, \bar{A}^\alpha = R^{-1}{}^\alpha{}_b A^b + w^b\}$$

$$D_\alpha = \partial_\mu - A^\alpha_\mu \tilde{e}_\alpha = \cancel{\partial_\mu - \bar{A}^\alpha_\mu e_\alpha}$$

$$A^\alpha = A^\alpha_\mu dx^\mu \quad \bar{A}^\alpha = \cancel{R^{-1}{}^\alpha{}_b A^b} + w^b$$

$$F^\alpha = \frac{1}{2} F^\alpha_{\mu\nu} dx^\mu \otimes dx^\nu \quad \bar{F}^\alpha = R^{-1}{}^\alpha{}_b F^b$$

$$A = A^\alpha \hat{e}_\alpha \quad F = F^\alpha \hat{e}_\alpha = dA + [A \wedge A]$$

$$\{D_A\} = \{D_\alpha, \tilde{E}_\alpha\}$$

dual frame:

$$\{W^A\} = \{dx^\alpha, R^\alpha{}^\mu \bar{A}^\mu = A^b + \tilde{w}^b\}$$

$$\bar{A}^\bullet = \bar{A}^\alpha \hat{e}_\alpha$$

$$\bar{F} = \bar{F}^\alpha \hat{e}_\alpha = d\bar{A} + [\bar{A} \wedge \bar{A}]$$

connection and curvature forms as TG_e -valued forms

$$g = g_{\alpha\beta} dx^\alpha \otimes dx^\beta + \bar{g}_{ab} \bar{A}^a \otimes \bar{A}^b$$

$$= g_{\alpha\beta} dx^\alpha \otimes dx^\beta + g_{ab} (R^a{}_c A^c) \otimes (R^b{}_d A^d)$$

depend only on base point. as do F^α_α and $F^\alpha_{\alpha\beta}$

PRINCIPAL FIBER BUNDLE

notes by
Robert Jantzen (10)

By choice we restrict to
unimodular groups
 $C^a_{ba} = 0$.

LEFT INVARIANT FRAME (USING FUNDAMENTAL VECTOR FIELDS)

$$\xi_a = e_a$$

THIS FRAME IS DEFINED UP TO A LIE GROUP AUTOMORPHISM OF EACH FIBER INDEPENDENT OF THE BASE POINT (i.e. a finite dimensional class) whereas the RIGHT FRAME IS DEFINED UP TO AN INDEPENDENT LIE GROUP AUTOMORPHISM OF EACH FIBER (i.e. an infinite class) once C^a_{bc} is fixed.

$\{\bar{D}_A\}$, dual frame $\{\bar{W}^A\}$	" "
$\{D_a, e_a\}$	" "
$\{dx^a, \bar{A}^a\}$	

$$\tilde{e}_a = e_b R^{-1}{}^b{}_a$$

LIE BRACKETS:

$$[D_a, D_b] = -\bar{F}^c{}_{ab} e_c$$

$$[D_a, e_b] = 0$$

$$[e_a, e_b] = C^c{}_{ab} e_c$$

STRUCTURE FUNCTIONS:

$$[\bar{D}_A, \bar{D}_B] = \bar{C}^c{}_{AB} \bar{D}_c$$

$\bar{C}^c{}_{AB} = -\bar{F}^c{}_{AB}$
$\bar{C}^c{}_{ab} = C^c{}_{ab}$

METRIC

$$\begin{aligned} \bar{g} &= g_{ab} dx^a \otimes dx^b + \bar{g}_{ab} \bar{A}^a \otimes \bar{A}^b \\ &= \bar{g}_{AB} \bar{W}^A \otimes \bar{W}^B \end{aligned}$$

METRIC CONNECTION COMPONENTS

$$\nabla_{\bar{D}_A} \bar{D}_B = \bar{\Gamma}^c{}_{AB} \bar{D}_c$$

for example: $\bar{\Gamma}^c{}_{AB} = \frac{1}{2} g^{cd} (D_A g_{dB} + D_B g_{dA} - D_d g_{AB}) + \frac{1}{2} C^c{}_{AB} + \frac{1}{2} g^{cd} (g_{AE} C^E{}_{dB} + g_{BE} C^E{}_{dA})$

$\bar{\Gamma}^x{}_{AB} = \{\bar{x}\}$
$\bar{\Gamma}^x{}_{AB} = \bar{\Gamma}^x{}_{BA} = -\frac{1}{2} \bar{F}_a{}^x{}_B$
$\bar{\Gamma}^c{}_{AB} = -\frac{1}{2} \bar{F}^c{}_{AB}$
$\bar{\Gamma}^x{}_{ab} = -\frac{1}{2} \bar{\nabla}^x g_{ab}$
$\bar{\Gamma}^c{}_{ab} = \bar{\Gamma}^c{}_{ba} = \frac{1}{2} g^{cd} \bar{\nabla}_B g_{da}$
$\bar{\Gamma}^c{}_{ab} = \frac{1}{2} C^c{}_{ab} - \frac{1}{2} \bar{C}(a^c b)$

$$\bar{\Gamma}^a{}_a = \bar{\Gamma}^a{}_a$$

$$\bar{\Gamma}^a{}_{BA} = \bar{\Gamma}^a{}_{aB} = \bar{\Gamma}^a{}_{Ba}$$

$$\bar{\Gamma}^c{}_{bc} = 0 = \bar{\Gamma}^c{}_{cb}$$

UNIMODULARITY
USED HERE

RIGHT INVARIANT FRAME

USING "RIGHT INVARIANT" VECTOR FIELDS

$$e_a ; \quad \mathcal{L}_{\bar{e}_a} D_A = 0$$

THIS HAS THE ADVANTAGE THAT THE COMPONENTS OF INVARIANT FIELDS DEPEND ONLY ON THE BASE POINT (THE SAME IS TRUE OF ~~TENSORIAL~~ TENSORIAL FORMS WHICH PROJECT DOWN TO FIELDS ON SPACETIME).

$\{D_A\}$, dual frame $\{W^A\}$
" "

$\{D_a, \tilde{e}_a\}$
" "

$\{dx^a, R^a{}_b \bar{A}^b\}$
" "

LIE BRACKETS:

$$[D_a, D_b] = -F^c{}_{ab} \tilde{e}_c$$

$$[D_a, \tilde{e}_b] = A^c{}_{aB} C^B{}_{cb} \tilde{e}_c$$

$$[\tilde{e}_a, \tilde{e}_b] = -C^c{}_{ab} \tilde{e}_c$$

STRUCTURE FUNCTIONS:

$$[D_A, D_B] = C^c{}_{AB} D_c$$

$C^c{}_{AB} = -F^c{}_{AB}$
$C^c{}_{ab} = A^c{}_{aB} C^B{}_{ab}$
$C^c{}_{ab} = -C^c{}_{ab}$

METRIC

$$\begin{aligned} \bar{g} &= g_{ab} dx^a \otimes dx^b + g_{ab} (R^a{}_c \bar{A}^c) \otimes (R^b{}_d \bar{A}^d) \\ &= g_{AB} \bar{W}^A \otimes \bar{W}^B \end{aligned}$$

METRIC CONNECTION COMPONENTS

$$\nabla_{D_A} D_B = \Gamma^c{}_{AB} D_c$$

$$\Gamma^x{}_{AB} = \{\bar{x}\}$$

$$\Gamma^x{}_{AB} = \Gamma^x{}_{BA} = -\frac{1}{2} F_a{}^x{}_B$$

$$\Gamma^c{}_{AB} = -\frac{1}{2} F^c{}_{AB}$$

$$\Gamma^x{}_{ab} = -\frac{1}{2} \bar{\nabla}^x g_{ab}$$

$$\Gamma^c{}_{ab} = \frac{1}{2} g^{cd} \bar{\nabla}_B g_{da}$$

$$\Gamma^c{}_{ab} = \frac{1}{2} g^{cd} \bar{\nabla}_a g_{db} + A^d{}_a C^c{}_{db}$$

$$\Gamma^c{}_{ab} = -\frac{1}{2} C^c{}_{ab} - C(a^c b)$$

$$\Gamma^a{}_a = \cancel{\Gamma^a{}_a} - g^a{}_\delta \delta^a{}_\delta \ln g_F^{-\frac{1}{2}}$$

$$\Gamma^a{}_{BA} = \Gamma^a{}_{aB} = \frac{1}{2} g^{ad} \delta_B{}^d g_{da} = \delta_B{}^d \ln g_F^{-\frac{1}{2}}$$

$$\Gamma^c{}_{cb} = 0 = \Gamma^c{}_{bc}$$

TABENSKY'S EXTENDED RIEMANNIAN GEOMETRY

(10)

See page 13
for more
explanation

He assumes semi-simplicity so that "ad" is an isomorphism (semisimple \subset unimodular) and hence his extended tangent space on spacetime is isomorphic to the tangent space of the corresponding principal fiber bundle over spacetime.

A BASIS FOR HIS EXTENDED TANGENT SPACE (AN EXTENDED FRAME)

IS $\{\overset{E}{D}_A\} = \{\overset{G}{\nabla}_a, ad(e_a)\}$ ACTING ON LIE ALGEBRA VALUED

FUNCTIONS ON SPACE TIME :

$$\overset{G}{\nabla}_a (X^d e_d) = (\partial_a X^d + A_a^b C_b^d X^c) e_d$$

$$ad(e_a) (X^d e_d) = (C^d_{ab} X^b) e_d.$$

COMMUTATORS (OR "EXTENDED LIE BRACKETS")

$$[\overset{E}{D}_a, \overset{E}{D}_b] = F^c_{ab} ad(e_a)$$

$$[\overset{E}{D}_a, ad(e_b)] = A_a^c C^c_{ab} ad(e_b)$$

$$[ad(e_a), ad(e_b)] = C^c_{ab} ad(e_c)$$

EXTENDED STRUCTURE FUNCTIONS

$$[\overset{E}{D}_a, \overset{E}{D}_b] = \overset{E}{C}_{AB}^c \overset{E}{D}_c$$

THESE ARE THE SAME AS THE STRUCTURE FUNCTIONS FOR THE RIGHT FRAME EXCEPT FOR A SIGN :

(-1) number latin indices

THIS COULD BE REMEDIED BY USING INSTEAD THE FRAME $\{\overset{E}{D}_a, -\overset{E}{e}_a\}$ IN WHICH CASE THE CORRESPONDENCE WOULD BE EXACT OR WE JUST USE THE SIGN RULE TO GO FROM THE RIGHT FRAME TO THE EXTENDED FRAME.

EXTENDED METRIC :

~~$\overset{E}{g}(D_A, D_B) = g_{AB}$~~

METRIC CONNECTION COMPONENTS

$$\overset{E}{\nabla}_{D_A}^E D_B = \overset{E}{\Gamma}_{AB}^C \overset{E}{D}_C$$

$$\overset{E}{\Gamma}_{11}^1 = \overset{E}{\Gamma}_{11}^1$$

$$\overset{E}{\Gamma}_{12}^1 = -\overset{E}{\Gamma}_{21}^1$$

$$\overset{E}{\Gamma}_{21}^1 = -\overset{E}{\Gamma}_{12}^1$$

$$\overset{E}{\Gamma}_{11}^2 = \overset{E}{\Gamma}_{11}^2$$

$$\overset{E}{\Gamma}_{12}^2 = \overset{E}{\Gamma}_{21}^2$$

$$\overset{E}{\Gamma}_{21}^2 = \overset{E}{\Gamma}_{12}^2$$

$$\overset{E}{\Gamma}_{11}^3 = \overset{E}{\Gamma}_{11}^3$$

$$\overset{E}{\Gamma}_{12}^3 = -\overset{E}{\Gamma}_{21}^3$$

$$\overset{E}{\Gamma}_{21}^3 = -\overset{E}{\Gamma}_{12}^3$$

The right invariant frame has the advantage that the components of everything we're interested in depend only on the base point (whereas the components of these guys in the left frame pick up adjoint matrices $R^a{}_b$ and $R^{-1}{}^a{}_b$ on all latin indices). If we evaluate the Ricci tensor in the right invariant frame, then its components in the left invariant frame may be obtained by performing the adjoint transformation on all Latin indices while the components of Tabensky's extended Ricci tensor may be obtained by using the above sign correspondence. (For comparison with Tabensky's formulas one should note that his bar covariant derivative is inconsistently defined in his paper, obscures the dependence on the individual fields and is just generally fucked.)

$$R_{DB} = R^A{}_{BAD} = D_A \Pi^A{}_{DB} - D_D \Pi^A{}_{AB} - \Pi^A{}_{EB} C^E{}_{AD} + \Pi^A{}_{AE} \Pi^E{}_{DB} - \Pi^A{}_{DE} \Pi^E{}_{AB}$$

conveniently and suggestively define:

$$\begin{aligned} K_{\alpha ab} &= -\frac{1}{2} \overset{\text{G}}{\nabla}_\alpha g_{ab} & TRK^2 &= K_\alpha{}^\alpha{}_b K^{\alpha b} = \frac{1}{4} g^{ab} g^{cd} \overset{\text{G}}{\nabla}_\alpha g_{ab} \overset{\text{G}}{\nabla}{}^\alpha g_{cd} \\ && TR^2 K &= K_\alpha{}^\alpha{}_a K^{\alpha b}{}_b = \frac{1}{4} g^{ac} g^{db} \overset{\text{G}}{\nabla}_\alpha g_{ab} \overset{\text{G}}{\nabla}{}^\alpha g_{cd} \end{aligned}$$

$$R_{\delta B} = {}^4R_{\delta B} - \frac{1}{2} F_\alpha{}^\beta F^\alpha{}_\beta - \overset{\text{G}}{\nabla}_\delta \overset{\text{G}}{\nabla}_B \ln g_F^{1/2} - K_\delta{}^{ab} K_B{}_{ab}$$

$$g^{\delta B} R_{\delta B} = {}^4R - \frac{1}{2} F^2 - \overset{\text{G}}{\nabla}{}^\alpha \overset{\text{G}}{\nabla}_\alpha \ln g_F^{1/2} - TRK^2$$

$$R_{db} = {}^F R_{db} + \frac{1}{4} F_d{}^{ab} F_{bab} - \frac{1}{2} g_F^{-1/2} \overset{\text{G}}{\nabla}_\alpha (g_F^{1/2} \overset{\text{G}}{\nabla}{}^\alpha g_{db}) + 2 K^{\alpha c}{}_d K_{\alpha cb}$$

$$g^{bd} R_{db} = {}^F R + \frac{1}{4} F^2 - g_F^{-1/2} \overset{\text{G}}{\nabla}_\alpha \overset{\text{G}}{\nabla}{}^\alpha g_F^{1/2}$$

$$R = {}^4R - \frac{1}{4} F^2 - 2 g_F^{-1/2} \overset{\text{G}}{\nabla}_\alpha \overset{\text{G}}{\nabla}{}^\alpha g_F^{1/2} + TR^2 K - TRK^2 + {}^F R$$

$$\mathcal{L} = (g_F{}^4 g)^{1/2} R = g_F^{1/2} (\underbrace{{}^4R}_{\text{LEYM}} + TR^2 K - TRK^2 + {}^F R) - \underbrace{2 \nabla_\alpha \nabla^\alpha (g g_F)^{1/2}}_{\text{spacetime divergence}}$$

$$\begin{aligned} R_{db} &= -\frac{1}{2} g_F^{-1/2} \overset{\text{G}}{\nabla}_\alpha (g_F^{1/2} F_d{}^\alpha{}_b) + \underbrace{\frac{1}{2} C^{ab}{}_d \nabla_b g_{ab}}_{= TR \underline{R}_d \underline{K}_B} \\ &= C^a{}_{db} K_B{}^b{}_a \end{aligned}$$

equations of motion

for

$$R_{\delta B} = 0$$

$${}^4g_{\alpha\beta}$$

$$R_{db} = 0$$

$$A^\alpha_a$$

$$R_{db} = 0$$

$$g_{ab}$$

These follow from independent variation of these fields in the scalar curvature density Lagrangian \mathcal{L} on the bundle. (This is why we impose unimodularity)

FIBER CURVATURE

The fiber Ricci tensor components ${}^F R_{db}$ are given by the formula for R_{db} with all indices Latin and $D_c g_{ab} = D_d \Gamma^c_{ab} = 0$:

$$\begin{aligned} {}^F R_{db} &= -\underbrace{\Gamma^a_{eb} \Gamma^e_{ad}}_{\Gamma^e_{ad} - \Gamma^e_{da}} + \underbrace{\Gamma^a_{ae} \Gamma^e_{db}}_{C^a_{ea}} - \underbrace{\Gamma^e_{ad} \Gamma^e_{ab}}_{\text{CANCEL}} \\ &= -C^a_{ea} \Gamma^e_{db} - \Gamma^a_{eb} \Gamma^e_{ad} \end{aligned}$$

PLUG IN $\Gamma^a_{ab} = \frac{1}{2} C^c_{ab} + \underbrace{C^a_{eb}}_{\Gamma^c_{(eb)}} \underbrace{C^c_{eb}}_{\Gamma^c_{(ab)}}$ (note $C^a_{ea} \Gamma^e_{db} = C^a_{ea} C^{(c)}_{(ab)}$ by the contracted Riccati identity $C^e_{ae} C^a_{bc} = 0$)

$$\rightarrow {}^F R_{db} = -C^a_{ea} \Gamma^e_{(ab)} + \frac{1}{4} C_{dfg} C^{fg}_{(b)} - C_{fgd} C^{(fg)}_{(b)}$$

$${}^F R = -C^a_{ea} C^{be}_{(b)} + \frac{1}{4} C_{dfg} C^{fgd} - C_{fgd} C^{(fg)d}$$

these terms
vanish for
unimodular group

In Tabensky's final line of section 3, in the formula for the fiber curvature in ${}^F R_{db}$ the vertical-vertical part of RICCI (R_{ab} in his notation), he has omitted the term $-C^S_a C_S^B$ inside the parentheses.

All indices are raised and lowered with g^{ab} and g_{ab} of course.

This is formula 2 of §1 of Jensen's paper *The Scalar Curvature of Left-Invariant Riemannian Metrics*, except for the fact that he assumes an orthonormal frame.

$M = \text{spacetime manifold}$

$G = \text{semi-simple Lie group with Lie algebra } g, \text{ with basis } \{e_a\}$
 $[e_a, e_b] = C_{ab}^c e_c$

Tabensky introduces "extended functions" as elements of $L(M) = \text{Lie algebra-valued functions on } M$, and "extended vector fields" as derivations on $L(M)$. Since all derivations of a semi-simple Lie algebra are inner (and "ad" is an isomorphism), an extended vector field is just a pair (X, Ω) consisting of a vector field X and $\Omega \in L(M)$ acting on $\theta \in L(M)$ as follows:

$$(X, \Omega) \theta = (\overset{G}{\nabla}_X + \text{ad}(\Omega)) \theta$$

$$\overset{G}{\nabla}_X \theta = (X + \text{ad}(A)) \theta$$

$$\theta = \theta^a e_a, \quad \Omega = \Omega^a e_a, \quad X = X^\alpha d_\alpha$$

$$(X, \Omega)(\theta^a e_a) = \underbrace{(\partial_\alpha \theta^a + A_\alpha^c C_{cb}^a \theta^b)}_{\overset{G}{\nabla}_X \theta^a} e_a + (\Omega^c C_{cb}^a \theta^b) e_a$$

A basis for each extended tangent space is therefore:

$$\{\overset{E}{D}_A\} = \{\overset{G}{\nabla}_\alpha, \text{ad}(e_a)\},$$

This extended tangent space is isomorphic to the tangent space of a principal fiber bundle over spacetime with group G and his entire extended Riemannian geometry is equivalent to putting a right invariant metric on this bundle but he only works in a single gauge patch so the bundle approach is the only natural way to globalize his approach.

Whenever a symmetry group acts simply transitively on its orbits, one can introduce a frame on the manifold on which it is acting that is invariant under the action of the group; imposing symmetry on a tensor field simply kills the component derivatives along the orbits. One can then easily compare the Lagrange derivative of a Lagrangian before and after the symmetry is imposed on the Lagrangian.

In our case choose the frame $\{\tilde{D}_A\} = \{\partial_\alpha, \tilde{e}_a\}$ with dual frame $\{\tilde{W}^A\} = \{dx^\alpha, \tilde{\omega}^a\}$.

$$\tilde{C}^A{}_{BC} = -\delta_a^A \delta_B^b \delta_C^c C^a{}_{bc} \quad \partial_A \equiv \tilde{D}_A, \quad \tilde{\partial}_A \equiv \partial_A - C^B{}_{AB}$$

$$= \partial_A - \delta_A^a C^b{}_{ab}.$$

$$\begin{aligned} \bar{g} &= g_{\alpha\beta} dx^\alpha \otimes dx^\beta + g_{ab} (A^\alpha{}_\beta dx^\alpha + \tilde{\omega}^a) \otimes (A^\beta{}_\gamma dx^\gamma + \tilde{\omega}^b) \\ &= \underbrace{g_{\alpha\beta} dx^\alpha \otimes dx^\beta}_{\equiv \tilde{g}_{AB}} + \underbrace{A^\alpha{}_\beta (dx^\alpha \otimes \tilde{\omega}^a + \tilde{\omega}^a \otimes dx^\alpha)}_{\equiv \tilde{g}^{a\alpha}} + \underbrace{g_{ab} \tilde{\omega}^a \otimes \tilde{\omega}^b}_{\equiv \tilde{g}^{ab}} \end{aligned}$$

Imposing the bundle symmetry on \bar{g} means $\partial_a \tilde{g}_{AB} = 0 = \partial_D \partial_a \tilde{g}_{AB} = \partial_a \partial_D \tilde{g}_{AB}$.

The scalar curvature Lagrangian form:

$$L = L dx^0 dx^1 dx^2 dx^3 \wedge \tilde{\omega}^1 \wedge \dots \wedge \tilde{\omega}^r$$

$$L(\tilde{g}_{AB}, \partial_c \tilde{g}_{AB}, \partial_c \partial_d \tilde{g}_{AB}, C^A{}_{BC}) = R \tilde{g}^{1/2}$$

The components of the Lagrange derivative of L with respect to \bar{g} in this frame are:

$$\frac{\delta L}{\delta \tilde{g}_{AB}} = \frac{\partial L}{\partial \tilde{g}_{AB}} - \tilde{\partial}_C \left(\frac{\partial L}{\partial \partial_C \tilde{g}_{AB}} \right) + \tilde{\partial}_D \tilde{\partial}_C \left(\frac{\partial L}{\partial \partial_C \partial_D \tilde{g}_{AB}} \right) = -\tilde{g}^{1/2} G^{AB}.$$

$\tilde{\partial}_A$ rather than ∂_A appears since the divergence of $\tilde{\omega}^1 \wedge \dots \wedge \tilde{\omega}^r$ enters in any "integration by parts". Imposing the bundle symmetry on the Lagrangian means inserting zeros in the arguments $\partial_a \tilde{g}_{AB}$, $\partial_D \partial_a \tilde{g}_{AB}$, $\partial_a \partial_D \tilde{g}_{AB}$; the same for its Lagrange derivative.

The Lagrange The Einstein tensor density (x^{-1}) of the symmetric metric minus the Lagrange derivative of the symmetrized Lagrangian is easily computed:

$$\begin{aligned} \underbrace{\text{SYM} \frac{\delta L}{\delta \tilde{g}_{AB}}}_{-\tilde{g}^{1/2} G^{AB}} - \underbrace{\text{SYM} L}_{\delta \tilde{g}_{AB}} &= \delta_A^a \delta_B^b \left(-C^d{}_a \frac{\partial L}{\partial \partial_d \tilde{g}_{ab}} + C^f{}_c C^g{}_d \frac{\partial L}{\partial \partial_c \partial_d \tilde{g}_{ab}} \right. \\ &\quad \left. + C^f{}_c \delta_d \left(\frac{\partial L}{\partial \partial_d \tilde{g}_{ab}} + \frac{\partial L}{\partial \partial_c \tilde{g}_{ab}} \right) \right) \end{aligned}$$

Thus unless $C^b{}_{ab} = 0$, the Lagrange derivative of the Lagrange ~~with~~ with the symmetry imposed does not equal the Einstein tensor density, i.e. one does not obtain the Einstein equations by varying the Lagrangian evaluated on the symmetric field.

LAGRANGE MULTIPLIER DILEMMA

If we want to extremize $\int C R g^{1/2}$ subject to the constraints $\int_{\Sigma_a} g_{ab} = 0$ we just add the constraints to the Lagrangian with Lagrange multipliers and vary both g and the Lagrange multipliers freely:

$$I = \int_C (R g^{1/2} + \lambda^a \delta_{ab} \int_{\Sigma_a} g_{ab})$$

C compact ^{region} manifold
~~subset~~

$$I' = \int_C - (g^{1/2} G^{ab} + \int_{\Sigma_a} \lambda^{ab}) g'_{ab} + \lambda'^{ab} \int_{\Sigma_a} g_{ab}$$

$$+ \underbrace{\int_C g^{1/2} (-g^{ab} g^{cd} + g^{ad} g^{cb}) g'_{ab;cd} + \int (\lambda^{ab} \delta^{cd} g'_{ab})}_{\text{divergence integrals — forget about since}};$$

integrate to ∂C where g'_{ab} and derivatives vanish.

$$g^{1/2} G^{ab} + \int_{\Sigma_a} \lambda^{ab} = 0$$

$$\int_{\Sigma_a} g_{ab} = 0$$

now what. usually one can solve for the Lagrange multipliers.
 Here one seems to be at a dead end.

January 11, 1979

Dear Arthur,

Thanks for getting in touch with me again. I've dashed off answers to all of your questions but got stuck on one term in the variation of the Lagrangian. Since I've only got a week left to prepare a new talk I'm giving in Waterloo, Canada, I'll have to leave it for now and get back to it later.

- Misner Thorne and Wheeler use a different (and I think unnatural) convention:

$$\Gamma^A_{BC} = \omega^A (\nabla_{e_B} e_C) = {}^{MTW} \Gamma^A_{CB}$$

Since $\Gamma^A_{[BC]} = \frac{1}{2} C^A_{BC}$ for a symmetric connection,

${}^{MTW} \Gamma^A_{BC} = \Gamma^A_{B[C} - C^A_{BC}$ which accounts for the different sign $-\frac{1}{2} C^A_{BC}$ instead of $\frac{1}{2} C^A_{BC}$ in the connection formula.

- On page 14 it is noted that one may rewrite $R_{\delta B}$ (page 12) as:

$$R_{\delta B} = 4R_{\delta B} - \frac{1}{2} F_a^d F^a_{dB} - g_F^{-1/2} \nabla_\delta \nabla_B g_F^{1/2}$$

$$+ \underbrace{\text{Tr } K_\delta \text{Tr } K_B - \text{Tr } K_\delta K_B}_{\text{this combination occurs all over the place}}$$

$\overbrace{\quad}^{\text{now its } g_F^{1/2} \text{ instead of } \ln g_F^{1/2}}$
does that make you happier?

- Gauge derivatives aren't needed for $g_F^{1/2}$ which is a weight one scalar density under gauge transformations only since the groups we are considering are unimodular (ie no difference between gauge scalars and gauge scalar densities).

- I have no idea what $\overset{G}{\nabla}_\delta \overset{G}{\nabla}_B g_F^{1/2}$ means geometrically.

I'm looking forward to hearing from you again.

Best regards,
bob

USEFUL IDENTITY: $\nabla_\alpha \nabla_B \ln g_F^{1/2} = -\text{Tr} K_\alpha \text{Tr} K_B + g_F^{-1/2} \nabla_\alpha \nabla_B g_F^{1/2}$

If. Expand ln derivative and use: $\text{Tr} K_\alpha = -\nabla_\alpha \ln g_F^{1/2}$.

BUNDLE EINSTEIN TENSOR COMPONENTS

$$\begin{aligned} \blacksquare G_{\delta\beta} &= R_{\delta\beta} - \frac{1}{2} R g_{\delta\beta} = {}^4G_{\delta\beta} - {}^T Y^M{}_{\delta\beta} \\ &\quad + \text{Tr} K_\delta \text{Tr} K_\beta - \text{Tr} K_\delta K_\beta - \frac{1}{2} g_{\delta\beta} (\text{Tr}^2 K - \text{Tr} K^2 + {}^F R) \\ &\quad - g_F^{-1/2} {}^4g^{-1/2} G^{\alpha\delta}{}_{\alpha\beta} \nabla_\alpha \nabla_\delta g_F^{1/2} \end{aligned}$$

$$\text{DEFINITIONS: } {}^T Y^M{}_{\delta\beta} = \frac{1}{2} (F_\alpha{}^\alpha{}_\beta F^\alpha{}_\alpha{}_\delta - \frac{1}{4} F^2 g_{\beta\delta})$$

$$G^{\alpha\beta\gamma\delta} = {}^4g^{1/2} (g^{\alpha(\gamma} g^{\delta)\beta} - g^{\alpha\beta} g^{\gamma\delta})$$

NOTE THAT USING THE USEFUL IDENTITY ONE CAN REWRITE $R_{\delta\beta}$ AND R_{db} :

$$R_{\delta\beta} = {}^4R_{\delta\beta} - \frac{1}{2} F_\alpha{}^\alpha{}_\beta F^\alpha{}_\alpha{}_\delta - g_F^{-1/2} \nabla_\delta \nabla_\beta g_F^{1/2} + \text{Tr} K_\delta \text{Tr} K_\beta - \text{Tr} K_\delta K_\beta$$

$$R_{db} = {}^F R_{db} + \frac{1}{4} F_d{}^{\alpha\beta} F_{b\alpha\beta} - \frac{1}{2} \nabla_\alpha \nabla^\alpha g_{db} + 2 K^{\alpha c}{}_\alpha K_{c b} - \text{Tr} K_\alpha K^\alpha{}_{db}$$

$$\begin{aligned} \blacksquare G_{db} &= R_{db} - \frac{1}{2} R g_{db} = {}^F G_{db} + \frac{1}{4} (F_d{}^{\alpha\beta} F_{b\alpha\beta} + \frac{1}{2} g_{db} F^2) - \frac{1}{2} g_{db} {}^4R \\ &\quad - \frac{1}{2} \nabla_\alpha \nabla^\alpha g_{db} + g_F^{-1/2} g_{db} \nabla_\alpha \nabla^\alpha g_F^{1/2} \\ &\quad + 2 K_d{}^c K^\alpha{}_{cb} - \text{Tr} K_\alpha K^\alpha{}_{db} - \frac{1}{2} g_{db} (\text{Tr}^2 K - \text{Tr} K^2) \end{aligned}$$

$$\blacksquare G_{d\beta} = R_{d\beta}$$

USEFUL VARIATION FORMULAS (for any metric $g_{\alpha\beta}$)

$$\left\{ \begin{array}{l} (g^{1/2}R)' = -g^{1/2}G^{\alpha\beta}g'_{\alpha\beta} + g^{1/2}g^{\alpha\beta}R'_{\alpha\beta} \\ g^{1/2}g^{\alpha\beta}R'_{\alpha\beta} = G^{\alpha\beta\gamma\delta}\nabla_\gamma\nabla_\delta g'_{\alpha\beta} \\ Ng^{1/2}g^{\alpha\beta}R'_{\alpha\beta} = (G^{\alpha\beta\gamma\delta}\nabla_\gamma\nabla_\delta N)g'_{\alpha\beta} + \nabla_\mu X^\alpha. \end{array} \right.$$

VARIATION OF BUNDLE LAGRANGIAN

$$\mathcal{L} = g_F^{1/2}g^{1/2}R = g_F^{1/2} \underbrace{\mathcal{L}_{\text{SYM}}}_{\text{SYM}} + {}^4g^{1/2}g_F^{1/2}(\text{Tr}^2K - \text{Tr}K^2 + {}^F R) + \text{div } {}^4g^{1/2}({}^4R - \frac{1}{4}F^2)$$

$$\frac{\delta}{\delta g_{\alpha\beta}} (g_F^{1/2} \mathcal{L}_{\text{SYM}}) = g_F^{1/2} {}^4g^{1/2} (-4G^{\alpha\beta} + T^{\alpha\beta}) + G^{\alpha\beta\gamma\delta}\nabla_\gamma\nabla_\delta g_F^{1/2}$$

$$\begin{aligned} \frac{\delta}{\delta g_{\alpha\beta}} ({}^4g^{1/2} g^{\gamma\delta}) g_F^{1/2} (\text{Tr}K\gamma\text{Tr}K\delta - \text{Tr}K\gamma K\delta) \\ = -{}^4g^{1/2}g_F^{1/2} (\text{Tr}K^\alpha\text{Tr}K^\beta - \text{Tr}K^\alpha K^\beta - \frac{1}{2}g^{\alpha\beta}(\text{Tr}^2K - \text{Tr}K^2)) \end{aligned}$$

$$\frac{\delta}{\delta g_{\alpha\beta}} ({}^4g^{1/2}g_F^{1/2} {}^F R) = \frac{1}{2} {}^4g^{1/2}g_F^{1/2} g_{\alpha\beta} {}^F R$$

compare with previous page:

$$\boxed{\frac{\delta}{\delta g_{\alpha\beta}} \mathcal{L} = -{}^4g^{1/2}g_F^{1/2} G^{\alpha\beta}}$$

$$\frac{\delta}{\delta A_d^\alpha} \left(-\frac{1}{4}g_F^{1/2}g^{1/2}F^2 \right) = g^{1/2} \overset{G}{\nabla}_\alpha (g_F^{1/2}F_d^{\alpha\beta}) \quad \text{just as in usual computation}$$

$$\overset{G}{\nabla}_\alpha g_{ab} = \nabla_\alpha g_{ab} - A_c^\alpha (C_{acb} + C_{bca})$$

$$(\overset{G}{\nabla}_\alpha g_{ab})' = -2A_d^\alpha C_{(a|c|b)}$$

$$(K_{ab})' = C_{(a|c|b)} A_c^\beta'$$

$$(\text{Tr}K)_a' = f(\text{Tr}K_a) A_c^\beta'$$

" unimodular groups

$$(\text{Tr}K^2)' = (K_{ab}K^{\alpha\beta})' = 2\text{Tr}K_d K^\alpha A_d^\beta'$$

$$\frac{\delta}{\delta A_d^\alpha} \mathcal{L} = g^{1/2} \overset{G}{\nabla}_\alpha (g_F^{1/2} F_d^{\alpha\beta}) - 2g_F^{1/2} g^{1/2} \text{Tr}K_d K^\beta$$

$$= -2g^{1/2}g_F^{1/2} R_d^\beta = \boxed{-2g^{1/2}g_F^{1/2} G_d^\beta = \frac{\delta}{\delta A_d^\beta} \mathcal{L}}$$

The following computation of $\frac{\delta}{\delta g_{ab}} \mathcal{L} = -4g^{1/2}g_F^{-1/2} G^{ab}$

is a near miss. The variation of $\text{Tr}^2 K$ isn't coming out right and I'm temporarily puzzled. Perhaps you can figure it out. I'll get back to it when I have more time.

$$\begin{aligned} (g_F^{1/2} g^{1/2} ({}^4R - \frac{1}{4} g_{ab} F_a^{ab} F_b^{ab} + {}^F R))' &= \\ g_F^{1/2} g^{1/2} \left(\frac{1}{2} {}^4R g^{ab} - \frac{1}{4} (F_a^{ab} F_b^{ab} + \frac{1}{2} g^{ab} F^2) \right) g'_{ab} + \\ g_F^{1/2} g^{1/2} (-{}^F G^{ab} g'_{ab}) \end{aligned}$$

This uses the fact that $(g_F^{1/2} {}^F R)' = -g_F^{1/2} {}^F G^{ab} g'_{ab}$.

The divergence vanishes identically by unimodularity and right invariance.

$$\begin{aligned} (g^{1/2} g_F^{1/2} (\text{Tr}^2 K - \text{Tr} K^2))' &= \\ g^{1/2} g_F^{1/2} \left(\frac{1}{2} g^{ab} (\text{Tr}^2 K - \text{Tr} K^2) g'_{ab} + (\text{Tr}^2 K)' - (\text{Tr} K^2)' \right) \end{aligned}$$

$$\begin{aligned} (\text{Tr} K^2)' &= (g^{ab} g^{ac} g^{bd} K_{ab} K_{cd})' \\ &= -2 K^{\alpha ac} K_{\alpha a}{}^d g'_{cd} + \underbrace{2 K^{\alpha ab} \left(-\frac{1}{2} \nabla^\alpha g'_{cd} \right)}_{\nabla_\alpha K^{\alpha cd} g'_{cd} + \text{div}} \end{aligned}$$

$$\begin{aligned} \nabla^\alpha K^{\alpha cd} &= -\frac{1}{2} \nabla_\alpha (g^{ca} g^{db} \nabla^\alpha g_{ab}) \\ &= -\frac{1}{2} g^{ca} g^{db} \nabla_\alpha \nabla^\alpha g_{ab} - \underbrace{\frac{1}{2} \nabla_\alpha (g^{ca} g^{db}) \nabla^\alpha g_{ab}}_{-(K_\alpha{}^{cagdb} + g^{ca} K_\alpha{}^{db}) - 2 K^{\alpha ab}} \\ &\quad \underbrace{- 4 K_{\alpha a}{}^c K^{\alpha ad}}_{4 K_{\alpha a}{}^c K^{\alpha ad}} \end{aligned}$$

$$(\text{Tr} K^2)' = (2 K^{\alpha ac} K_{\alpha a}{}^d - \frac{1}{2} g^{ca} g^{db} \nabla_\alpha \nabla^\alpha g_{ab}) g'_{cd}$$

$$\begin{aligned} (\text{Tr}^2 K)' &= (g^{ab} g^{cd} K_{ab} g^{cd} K_{cd})' = 2 \text{Tr} K^\alpha (g^{cd} K_{cd})' \\ &= -2 \text{Tr} K^\alpha K_{\alpha cd} g'_{cd} + \underbrace{2 \text{Tr} K^\alpha g^{cd} \left(-\frac{1}{2} \nabla_\alpha g'_{cd} \right)}_{\nabla_\alpha (\text{Tr} K^\alpha g^{cd}) g'_{cd} + \text{div}} \\ &\quad \underbrace{((\nabla_\alpha \text{Tr} K^\alpha) g^{cd} + 2 \text{Tr} K^\alpha K_{\alpha cd}) g'_{cd}}_{\nabla_\alpha (\text{Tr} K^\alpha) g^{cd} g'_{cd}} \\ &= (\nabla_\alpha \text{Tr} K^\alpha) g^{cd} g'_{cd} = (\text{Tr}^2 K - g_F^{-1/2} \nabla_\alpha \nabla^\alpha g_F^{1/2}) g^{cd} g'_{cd} \end{aligned}$$

If the term $(\text{Tr}^2 K)g^{cd}$ had been instead $\text{Tr}K^\alpha K^\alpha{}^{cd}$, we would have obtained $\frac{\delta \mathcal{L}}{\delta g_{ab}} = -4g^{1/2}g_F{}^{1/2}G^{ab}$

because all the other terms agree. I don't understand what I've done wrong yet.