

Show all work, including mental steps, in a clearly organized way that speaks for itself. Use proper mathematical notation, identifying expressions by their proper symbols (introducing them if necessary), and use arrows and equal signs when appropriate. Always simplify expressions. BOX final short answers. LABEL parts of problem. Keep answers EXACT (but give decimal approximations for interpretation). Indicate where technology is used and what type (Maple, GC, MathCad). **You may use technology for row reductions, matrix inverses, plotting and root finding without showing intermediate steps. Print** the requested 7 technology plots, **annotate them appropriately by hand** and attach to the relevant problems.

1. The displacement  $x(t)$  of an underdamped harmonic oscillator system satisfies

$$m x''(t) + c x'(t) + K x(t) = F(t).$$

Let  $m = 9$ ,  $c = 6$ ,  $K = 37$  and the initial conditions  $x(0) = 0$ ,  $x'(0) = 0$ .

a) Express this DE in standard form with a unit coefficient of the second derivative term. What are the natural frequency  $\omega_0$ , natural decay time  $\tau_0$ , the quality factor  $Q = \omega_0 \tau_0$  and the period  $T_0 = 2\pi/\omega_0$  for this system? (Give both exact and numeric values to 3 decimal places.)

Consider the following driving force functions  $F(t)$ :

b)  $F(t) = 0$ .

Find the general solution of the differential equation. What is the frequency  $\omega_1$ , decay time  $\tau_1$  and the period

$T_1 = 2\pi/\omega_1$  for this decaying sinusoidal solution? (Give both exact and numeric values to 3 decimal places.)

c)  $F(t) = 5 \cos(2t)$ .

Find the initial value problem solution by hand (but check with Maple!)

Evaluate the values of the amplitude  $A$  and phase shift  $\delta$  for the steady state solution (the part of the solution which remains after the transient has died away) and express the phase shift in radians, degrees and cycles (divide radians by  $2\pi$ ). Make a single **plot (#1)** in an appropriate viewing window showing both the solution function and the steady state solution until they merge. In a separate plot for comparison with the driving cosine function, **plot (#2)** both the steady state solution and  $A \cos(2t)$  (same amplitude as the steady state solution) to see how the peaks of the steady state solution compare to the peaks of the driving function. Does your plot agree with your calculated phase shift angle (does the steady state solution lead or lag behind the driving function by a corresponding amount)? Explain.

d)  $F(t) = F_0 \cos(\omega t)$ ,  $F_0 > 0$ .

Explore resonance for this system by finding the steady state solution by hand, where the nonnegative frequency  $\omega$  of the driving force function is a parameter.

e) Evaluate the steady state amplitude function  $A(\omega)$  and use calculus to find the exact and numerical value of the frequency  $\omega_p$  and the amplitude  $A(\omega_p)$  where it has its peak value for  $\omega \geq 0$ . Does  $A(2)$  with  $F_0 = 5$  agree with your value for  $A$  from part c) as it should? What is the numerical value of the ratio  $A(\omega_p)/A(0)$ ? How does it compare to the quality factor  $Q$ ?

f) **Plot (#3)** the amplitude function ratio  $A(\omega)/F_0$  in an appropriate window (showing the limiting behavior of the entire function for  $\omega \geq 0$ ) together with the constant function  $A(\omega_p)/F_0$  (its peak value) and hand annotate on your axes the values of these frequencies and amplitudes and indicate the points on the curve which correspond to  $\omega_0$  and  $\omega_p$ .

$$2. x_1'(t) = -\frac{1}{2} x_1(t) + \frac{1}{2} x_3(t), x_2'(t) = \frac{1}{2} x_1(t) - \frac{1}{5} x_2(t), x_3'(t) = \frac{1}{5} x_2(t) - \frac{1}{2} x_3(t),$$

$$x_1(0) = 18, x_2(0) = 0, x_3(0) = 0.$$

a) Write this system of differential equations for the vector variable  $\vec{x} = \langle x_1, x_2, x_3 \rangle$  AND its initial conditions in explicit matrix form (showing all components, not just vector symbols) and identifying the coefficient matrix  $A$ .

b) Use the eigenvector approach to find its general solution by hand, showing all steps.

c) Find the IVP solution, using matrix methods showing all steps. Make sure it agrees with Maple's solution.

- d) Evaluate the asymptotic solution  $\vec{x}_\infty$  for  $t \rightarrow \infty$ , which is the equilibrium solution approached by your solution.
- e) **Plot (#4)** the three solution curves together with their horizontal asymptotes in an appropriate viewing window that shows them reaching and settling down to those equilibrium values without compressing the interesting part before reaching that limit.
- f) Consider the difference solution  $x_3 - x_{\infty 3}$ , which is an exponentially damped sinusoidal function. What is the amplitude and phase shift of the sinusoidal factor? [Give the phase shift exactly in radians, then numerically in radians, cycles and degrees.] Evaluate its envelope curves and **plot (#5)** this difference together with its envelope for 5 characteristic times of the decaying exponential factor in these expressions (i.e., in an appropriate viewing window). Hand annotate each solution curve with its variable name.

3.  $x_1'(t) = -3x_1(t) + 4x_2(t)$ ,  $x_2'(t) = 6x_1(t) - 5x_2(t)$ ,  $x_1(0) = -1$ ,  $x_2(0) = 4$ .

- a) Identify the coefficient matrix and by hand find a new basis for  $R^2$  consisting of eigenvectors  $\vec{b}_1, \vec{b}_2$  of this matrix using the standard hand recipe, rescaling them to be the minimal integer eigenvectors. Order the real eigenvalues  $\lambda_1 \geq \lambda_2$  by decreasing value. Identify  $B = \left\langle \vec{b}_1 \middle| \vec{b}_2 \right\rangle$ .
- b) Evaluate the new coordinates  $\langle y_1, y_2 \rangle$  of the point  $\langle x_1, x_2 \rangle = \langle 0, 5 \rangle$  with respect to this basis of eigenvectors.
- c) Solve this initial value problem by hand, showing all steps.
- d) Use technology to **plot (#6)** a directionfield for this DE with the solution curve through the single initial data point, and (by hand if necessary) include the lines through the two eigenvectors representing the two subspaces of eigenvectors. Choose the window  $x_1 = -2.5 \dots 2.5$ ,  $x_2 = 0 \dots 5$ . By hand label these lines by their new coordinate labels, draw in and label the eigenvectors and the initial data vector  $\vec{x}(0)$  themselves as arrows, and include the parallelogram projection of the latter vector onto the new coordinate axes, i.e., the parallelogram parallel to the new coordinate axes with the initial data vector as the main diagonal. Do the projections along the coordinate axes agree with the values you found for the new coordinates of this vector? Explain. Does your directionfield correspond to the eigenvectors you have drawn? Explain why.
- d) **Plot (#7)** the two variables versus  $t$  for an appropriate viewing window for this initial value problem. Explain your window choice. The second variable  $x_2$  has a global minimum (for  $t > 0$ ) obvious in your plot. Find its coordinates and the corresponding value of  $t$  exactly and approximately. Annotate your diagram to show this point.

**Advice.** When in doubt about how much work to show, show more. Explain using words if it helps. Think of this take-home test as an exercise in "writing intensive" technical expression. Try to impress bob as though it were material for a job interview. In a real world technical job, you need to be able to write coherent technical reports that other people can follow.

## ► solution

### ▼ pledge

When you have completed the exam, please read and sign the dr bob integrity pledge and hand this test sheet stapled on top of your answer sheets as a cover page, with the first test page facing up:  
 "During this examination, all work has been my own. I have read the long instructions on the class web page. I give my word that I have not resorted to any ethically questionable means of improving my grade or anyone else's on this examination and that I have not discussed this exam with anyone other than my instructor, nor will I until after the exam period is terminated for all participants."

Signature:

Date: