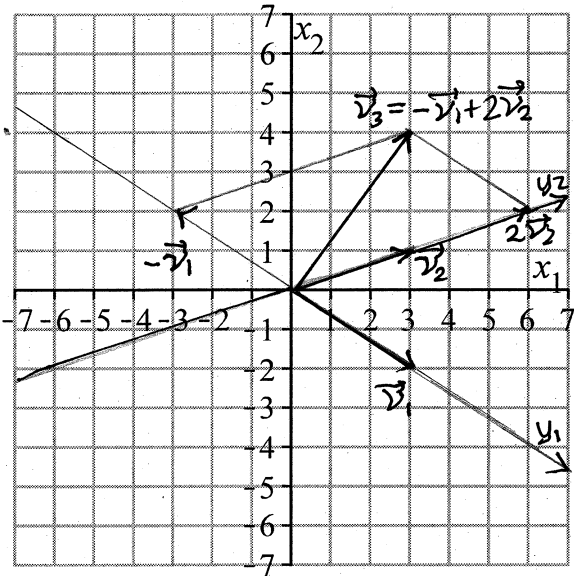


MAT2705 03/04 IIF TEST 2 Answers

① a) $\langle x_1, x_2 \rangle = \langle 3, 4 \rangle \rightarrow \langle y_1, y_2 \rangle = \langle -1, 2 \rangle$

The properly labeled parallelogram below shows these to be the coefficients of \vec{v}_1, \vec{v}_2 which express \vec{v}_3 .



b) $y_1 \vec{v}_1 + y_2 \vec{v}_2 = \vec{v}_3$
 $y_1 \begin{bmatrix} 3 \\ -2 \end{bmatrix} + y_2 \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$

$\begin{bmatrix} 3 & 3 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$

$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 3 & 3 \\ -2 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 3 \\ 4 \end{bmatrix}$

$= \frac{1}{+3+6} \begin{bmatrix} 1 & -3 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 3-12 \\ 6+12 \end{bmatrix}$

$= \begin{bmatrix} -1 \\ 2 \end{bmatrix}$ so

$\vec{v}_3 = -\vec{v}_1 + 2\vec{v}_2$

c) $\begin{bmatrix} 3 \\ 4 \end{bmatrix} = -\begin{bmatrix} 3 \\ -2 \end{bmatrix} + 2\begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} -3+6 \\ 2+2 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} \checkmark$

d) yes, they agree.

② a) $A = \begin{bmatrix} 1 & 2 & 5 & -1 \\ 3 & 1 & 5 & 7 \\ 2 & 1 & 4 & 4 \\ -1 & 0 & -1 & -3 \end{bmatrix} \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \vec{b} = \begin{bmatrix} 8 \\ 9 \\ 7 \\ 0 \end{bmatrix}$

$A\vec{x} = \vec{b} \rightarrow \langle A|\vec{b} \rangle = \begin{bmatrix} 1 & 2 & 5 & -1 & 8 \\ 3 & 1 & 5 & 7 & 9 \\ 2 & 1 & 4 & 4 & 7 \\ -1 & 0 & -1 & -3 & 0 \end{bmatrix} \xrightarrow{\text{rred}}$

$\begin{bmatrix} 1 & 0 & 1 & 3 & 0 \\ 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow 0 = 1$ inconsistent system, no soln.

② a) continued.

\vec{v}_3 cannot be expressed in terms of $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$ i.e., it does not lie in its span.

b) Let $\vec{b} = \langle 8, 9, 7, -2 \rangle : A\vec{x} = \vec{b}$

$\langle A|\vec{b} \rangle = \begin{bmatrix} 1 & 2 & 5 & -1 & 8 \\ 3 & 1 & 5 & 7 & 9 \\ 2 & 1 & 4 & 4 & 7 \\ -1 & 0 & -1 & -3 & -2 \end{bmatrix} \xrightarrow{\text{rred}}$

LLFF
 $\begin{bmatrix} x_1 & x_2 & x_3 & x_4 \\ 1 & 0 & 1 & 3 & 2 \\ 0 & 1 & 2 & -2 & 3 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{aligned} x_1 + x_3 + 3x_4 &= 2 \rightarrow x_1 = 2 - t_1 - 3t_2 \\ x_2 + 2x_3 - 2x_4 &= 3 \rightarrow x_2 = 3 - 2t_1 + 2t_2 \\ 0 &= 0 \\ 0 &= 0 \end{aligned}$
 $\hookrightarrow x_3 = t_1, x_4 = t_2 \uparrow$

Therefore

$\langle 8, 9, 7, -2 \rangle = (2 - t_1 - 3t_2)\vec{v}_1 + (3 - 2t_1 + 2t_2)\vec{v}_2 + t_1\vec{v}_3 + t_2\vec{v}_4$

lies in the span of these 4 vectors.

c) $A\vec{x} = \vec{0} : \rightarrow$ explicitly

$\langle A|\vec{0} \rangle = \begin{bmatrix} 1 & 2 & 5 & -1 & 0 \\ 3 & 1 & 5 & 7 & 0 \\ 2 & 1 & 4 & 4 & 0 \\ -1 & 0 & -1 & -3 & 0 \end{bmatrix} \xrightarrow{\text{rred}} \begin{bmatrix} 1 & 2 & 5 & -1 \\ 3 & 1 & 5 & 7 \\ 2 & 1 & 4 & 4 \\ -1 & 0 & -1 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$
 matrix equation

LLFF
 $\begin{bmatrix} x_1 & x_2 & x_3 & x_4 \\ 1 & 0 & 1 & 3 & 0 \\ 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{aligned} x_1 + x_3 + 3x_4 &= 0 & x_1 &= -t_1 - 3t_2 \\ x_2 + 2x_3 - 2x_4 &= 0 & x_2 &= -2t_1 + 2t_2 \\ 0 &= 0 \\ 0 &= 0 \end{aligned}$
 $\hookrightarrow x_3 = t_1, x_4 = t_2 \uparrow$

$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -t_1 - 3t_2 \\ -2t_1 + 2t_2 \\ t_1 \\ t_2 \end{bmatrix} = t_1 \begin{bmatrix} -1 \\ -2 \\ 1 \\ 0 \end{bmatrix} + t_2 \begin{bmatrix} -3 \\ 2 \\ 0 \\ 1 \end{bmatrix}$
 $\underbrace{\begin{bmatrix} -1 \\ -2 \\ 1 \\ 0 \end{bmatrix}}_{\vec{u}_1} + \underbrace{\begin{bmatrix} -3 \\ 2 \\ 0 \\ 1 \end{bmatrix}}_{\vec{u}_2}$

$\{\vec{u}_1, \vec{u}_2\} = \{ \langle -1, -2, 1, 0 \rangle, \langle -3, 2, 0, 1 \rangle \}$ = basis soln space

e) $\langle -1, -2, 1, 0 \rangle : -\vec{v}_1 - 2\vec{v}_2 + \vec{v}_3 = 0$
 $\langle -3, 2, 0, 1 \rangle : -3\vec{v}_1 + 2\vec{v}_2 + \vec{v}_4 = 0$

f) only 2 of the 4 vectors form a lin. ind. set so their span is a 2-dimensional subspace of \mathbb{R}^4 , i.e., a plane.

$\{\vec{v}_1, \vec{v}_2\} = \{ \langle 1, 3, 2, -1 \rangle, \langle 2, 1, 1, 0 \rangle \}$ is a basis of this plane although any 2 of the 4 vectors would do the job.