

7.1-7.2

covariant derivative stuff

$$\boxed{1} \quad T^{i...}_{j...;k} = T^{i...}_{j...,k} + \Gamma^i_{k\ell} T^{i...}_{j...+\ell} - \Gamma^\ell_{k\ell} T^{i...}_{j...-\ell} - \dots$$

$$\begin{aligned} [\nabla_X T]^{i...}_{j...} &= T^{i...}_{j...;k} X^k = T^{i...}_{j...,k} X^k + \Gamma^i_{k\ell} X^\ell T^{i...}_{j...+\ell} - \Gamma^\ell_{k\ell} X^\ell T^{i...}_{j...-\ell} \\ &= \partial T^{i...}_{j...}(\mathbf{x}) + \omega^i_\ell(\mathbf{x}) T^{i...}_{j...+\ell} - \omega^\ell_j(\mathbf{x}) T^{i...}_{j...-\ell} \end{aligned}$$

basis:  $\{e_i\} \rightarrow \omega^i_j = \Gamma^i_{kj} \omega^k$  connection 1-forms,  $[e_i, e_j] = C^k_{ij} e_k$

metric:  $g_{ij} : \nabla g = 0$ ,  $\nabla$  "symmetric"  $\rightarrow \Gamma^i_{jk} = \frac{1}{2} g^{il} (g_{jk,l} - g_{jl,k} + g_{kl,j})$   
same order, then  $\Gamma^i_{jk} = \frac{1}{2} g^{il} (C_{jk,l} - C_{jl,k} + C_{kl,j})$   
 (I never remember the index order!)

|   |   |
|---|---|
| $\mathbb{R}^n$ : grid divergence — differential | multivariable calc ops!<br>what are they? |
|---|---|

$$\boxed{1} \quad df = \frac{\partial f}{\partial x^i} dx^i = (e_i f) \omega^i = f_{,i} \omega^i \quad (\text{coord frame/general frame})$$

1-form = covector field, no metric needed.

$$\boxed{2} \quad \vec{\nabla} f = g^{ij} f_{,i} e_j \equiv \text{grad } f \quad \text{components } [\vec{\nabla} f]^i = g^{ij} f_{,i}$$

vectorfield  $(df)^\# = \vec{\nabla} f$  need metric to raise index to get vector field from 1-form

$$\mathbb{R}^3 \text{ Cartesian coords: } [\vec{\nabla} f]^i = \delta^{ij} f_{,i} \quad \text{no need to distinguish vector field / 1-form}$$

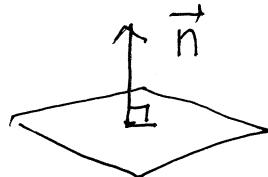
interpretation  
very different:

$df$  linearizes level surface family to tangent space



linear approximation for nearby points  $\sim$  vectors in tangent space

$\vec{\nabla} f$  is a normal to tangent plane to level surface



$\boxed{3}$  directional derivative

$$df(\mathbf{x}) = \mathbf{x} \cdot \vec{\nabla} f = \nabla_x f = \mathbf{x}^i f_{,i} \quad (\text{no metric needed}) \quad \text{linear approximation evaluation}$$

$$= \mathbf{x} \cdot \vec{\nabla} f = g_{ij} \mathbf{x}^i (\nabla f)^j \quad (\text{metric required}) \quad \text{"dot del"}$$

7.1-7.2

2

$\mathbb{R}^3$  Cartesian coordinates, vector field  $\mathbf{X} = X^i \partial_i$ ,  $\mathbf{X}^k = \epsilon^{ijk} \mathbf{X}^i dx^j$

$$\operatorname{curl} \mathbf{X} = \epsilon^{kij} \partial_i X_j \partial_k = \eta^{kij} \partial_i X_j \partial_k \\ = \eta^{kij} X_{j,i} \partial_k$$

$$\boxed{\eta^{kij} = (\det g)^{-\frac{1}{2}} \epsilon^{kij}}$$

in oriented frame

If start with 1-form  $X_i dx^i$ , no metric required.

To start with vector field  $X^i \partial_i$ , need metric to lower index

$$\operatorname{curl} \mathbf{X} = \eta^{kij} \partial_i X_j \partial_k = \eta^{kij} X_{j,i} \partial_k \\ = \eta^{kij} (X_{j,i} - \Gamma_{ij}^k \partial_k) \partial_k = \underbrace{\eta^{kij} X_{j,i} \partial_k}_{\Rightarrow \eta^{kij} (g_{jm} X^m)_{,i} = \eta^{kij} g_{jm} X^m_{,i}} \\ = \eta^{kij} (\nabla X^l)^#_{ji} \\ = \underbrace{g^{kn} \eta_{n}^{ji} (\nabla X^l)^{#}_{ji}}_{(\nabla \wedge X^l)^{#}_n} \\ \underbrace{[(\nabla \wedge X^l)^{#}]^k}_{}$$

$$\operatorname{curl} \mathbf{X} = ((\nabla \wedge X^l)^{#})^#$$

↑  
② ↑ ① ↑  
③ ④ ↑ ⑤

valid in any frame

5 operations in succession  
only for  $n=3$

dual of 2-form = 1-form

vector field

$$\text{Chapter 11: } (\operatorname{curl} X^k)^b = d X^b$$

exterior derivative  
of 1-form

no metric needed.

If start with 1-form

Simple:

valid for all  $n$

no metric, no connection

7.1-7.2

3

Cross product in  $\mathbb{R}^3$ 

$$[\underline{X} \times \underline{Y}]^i = \epsilon_{ijk} X^j Y^k = \delta^{ij} \epsilon_{ijk} X^j Y^k \text{ Cartesian coords.}$$

$$= \pi_{ijk}^i X^j Y^k \text{ any coords/frame.}$$

- $\text{curl } \underline{X} = \pi^{ki} \nabla_i X_j$

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$$= \vec{\nabla} \times \underline{X} \quad \text{"del cross"}$$

"del dot" = divergence

- $\text{div } \underline{X} = \frac{\partial \underline{X}^i}{\partial x^i} = \underline{X}^i_{,i} = \underbrace{\underline{X}^i}_{\text{valid in any frame}}{}_{;i} \text{ in Cartesian coords}$

$$= \vec{\nabla} \cdot \underline{X}$$

$$= \underline{X}^i_{,i} + \underbrace{\Gamma^i_{ik} X^k}_{*}$$

$$\pi^i_{jk} = \frac{1}{2} g^{il} (g_{ej,k} - g_{jk,e} + g_{ke,j}) + \frac{1}{2} (C^i_{jk} - C_{jk}^i + C_k^i)$$

$$\pi^i_{ik} = \frac{1}{2} g^{le} (g_{ei,k} - g_{ik,e} + g_{ke,i}) + \frac{1}{2} (C^i_{ik} - C_{ik}^i + C_k^i)$$

sym                          antisym                           $C^i_{ik} = -C^i_{ki}$   
 $\underbrace{-g_{ike} + g_{ke,i}}$                    $\underbrace{+C^i_{ik}}$   
 $\underbrace{\phantom{-g_{ike} + g_{ke,i}}}_{\text{antisym}} \quad \underbrace{\phantom{+C^i_{ik}}}_{\text{sym}}$   
 $\cancel{C_{ek}^i} \cancel{g_{ei}^i} \rightarrow 0$

$$= \frac{1}{2} \text{Tr}(\underline{g}^{-1} \underline{g}_{,k})$$

$$\frac{1}{2} \text{Tr}(\underline{g}^{-1} d\underline{g})(\partial_k) = d(\ln |\det \underline{g}|^{1/2})$$

$$\underbrace{d \ln |\det \underline{g}|}_{}$$

$$\pi^i_{ik} = (\ln |\det \underline{g}|^{1/2})_{,k} - \underbrace{C^i_{ki}}_{=0 \text{ in coord frame}}$$

7.1-7.2

4

$$\begin{aligned} \operatorname{div} \underline{X} &= X^0_{,i} + \Gamma^i_{ik} X^k \\ &= X^i_{,i} + \underbrace{(\ln |\det g|^{1/2})_{,k} X^k}_{\frac{(\det g)^{1/2} X^i_{,i}}{|\det g|^{1/2}}} - C^i_{ki} X^k \end{aligned}$$

$$\begin{aligned} \operatorname{div} \underline{X} &= \underbrace{\frac{(\det g)^{1/2} X^i_{,i}}{|\det g|^{1/2}}}_{\text{in coordinate frame}} - C^i_{ki} X^k \\ &= 0 \text{ in coord frame} \end{aligned}$$

$$\text{recall } N_{i_1 \dots i_n} = |\det g|^{1/2} \epsilon_{i_1 \dots i_n} \quad \begin{matrix} \text{volume} \\ n\text{-form} \end{matrix}$$

divergence only needs an  $n$ -form  
from metric

Chapter 11 : exterior derivative  
of  $(n-1)$  form —  
no metric required.

simpler to evaluate  
in coord system  
(especially on orthogonal one)

7.1-7.2

## Second derivatives

5

$$T^i_{j;kl} \equiv T^i_{j,k;l} \equiv [\nabla \nabla T]^i_{j;kl} = \underbrace{[\nabla \nabla T]}_{\substack{\rightarrow \\ \text{derivative indices} \\ \text{add on to the right}}}^i_{j;kl} = \underbrace{[\nabla_e \nabla_k T]}_{\substack{\leftarrow \\ \text{del indices} \\ \text{add on to left}}}^i_j$$

same abbreviation  
for partial derivatives,  
frame derivatives

$$T^i_{j;kl} \equiv T^i_{j,k;l} = \partial_e \partial_k T^i_j = e_e e_k T^i_j \quad (\text{frame})$$

functions!

$$\nabla f = f_{,i} w^i$$

$$\nabla \nabla f = f_{,ij} w^i \otimes w^j$$

$$f_{,ij} = (f_{,i}),_j - f_{,k} \Gamma^k_{ij} = f_{,ij} - f_{,k} \Gamma^k_{ij}$$

$$g^{ij} f_{,ij} = g^{ij} (f_{,ij} - f_{,k} \Gamma^k_{ij}) = f_{,ij} g^{ij} - f_{,k} \Gamma^k_{ij} g^{ij}$$

$$\begin{aligned} \vec{\nabla} \cdot \vec{\nabla} f &= \text{div grad } f \\ \vec{\nabla}^2 f &= \underset{\substack{\text{Cartesian} \\ \text{coords}}}{\delta^{ij} f_{,ij}} = \left( \frac{\partial}{\partial x_1} \right)^2 + \dots + \left( \frac{\partial}{\partial x_n} \right)^2 \end{aligned}$$

Laplacian

$$\vec{\nabla} f = f_{,i}^i e_i$$

$$\nabla \vec{\nabla} f = f_{,i}^i_{,j} e_i \otimes w^j$$

$f_{,i}^i$  matrix of components

$$\nabla^2 f = f_{,i}^i_{,i} = f_{,i}^i_{,i} = \text{Tr}(f_{,i}^i) \quad \text{Trace of matrix}$$

$$dwX = X^i_{,i} = |\det g|^{-1/2} (|\det g|^{1/2} X^i)_{,i} - C^i_{ik} X^k$$

$$\nabla^2 f = (g^{ik} f_{,k})_{,i} = \underbrace{(\det g)^{-1/2} (|\det g|^{1/2} g^{ik} f_{,k})_{,i}}_{\substack{\text{easy to evaluate}}} - C^i_{ik} f_{,k} \underset{\substack{\text{=0 coord} \\ \text{frame.}}}{}$$

7.1-7.2

6

 $\mathbb{R}^3$  cylindrical coords, spherical coords= orthogonal curvilinear coords  $\rightarrow$  "vector analysis"

$$g = (h_1)^2 dx^1 \otimes dx^1 + (h_2)^2 dx^2 \otimes dx^2 + (h_3)^2 dx^3 \otimes dx^3$$

$$= (h_1 dx^1) \otimes (h_1 dx^1) + (h_2 dx^2) \otimes (h_2 dx^2) + (h_3 dx^3) \otimes (h_3 dx^3)$$

$$= w^1 \otimes w^1 + w^2 \otimes w^2 + w^3 \otimes w^3$$

$$g^{-1} = \left(\frac{1}{h_1} \frac{\partial}{\partial x^1}\right) \otimes \left(\frac{1}{h_1} \frac{\partial}{\partial x^1}\right) + \left(\frac{1}{h_2} \frac{\partial}{\partial x^2}\right) \otimes \left(\frac{1}{h_2} \frac{\partial}{\partial x^2}\right) + \left(\frac{1}{h_3} \frac{\partial}{\partial x^3}\right) \otimes \left(\frac{1}{h_3} \frac{\partial}{\partial x^3}\right)$$

$$= e_1^1 \otimes e_1^1 + e_2^2 \otimes e_2^2 + e_3^3 \otimes e_3^3$$

$$\vec{\nabla} f = \left(\frac{1}{h_1} \frac{\partial f}{\partial x^1}\right) e_1^1 + \left(\frac{1}{h_2} \frac{\partial f}{\partial x^2}\right) e_2^2 + \left(\frac{1}{h_3} \frac{\partial f}{\partial x^3}\right) e_3^3 \quad [g^{ij} \partial_j f]$$

coord-expression oops!

$$\text{curl } X = \frac{1}{h_1 h_2 h_3} \epsilon^{ijk} \frac{\partial}{\partial x^j} (h_k X^k) \quad \begin{matrix} \downarrow \\ \text{no sum} \end{matrix} \quad \begin{matrix} \downarrow \\ e_i = \delta_{ij} \end{matrix}$$

orthonormal components of gradient.

$$w^k(x) \quad h_n x^k = \hat{x}^k, \quad x^k = \frac{\hat{x}^k}{h^k}$$

$$X_k = (h_k)^2 \hat{x}^k = h_k \hat{x}^k$$

$$\text{div } X = \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial x^1} (x^1 h_2 h_3) + \frac{\partial}{\partial x^2} (x^2 h_3 h_1) + \frac{\partial}{\partial x^3} (x^3 h_1 h_2) \right]$$

$$\leftarrow (\det g)^{-1/2} (\text{t} \det g^{1/2} X^k), k$$

$$\begin{matrix} h_1 h_2 h_3 & X^1 \\ h_2 h_3 & X^1 \\ h_2 h_3 & X^1 \end{matrix}$$

$$\begin{aligned} \det g &= g_{11} g_{22} g_{33} \\ &= h_1^2 h_2^2 h_3^2 \\ |\det g|^{1/2} &= h_1 h_2 h_3 \end{aligned}$$

$$= \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial x^1} (x^1 h_2 h_3) + \frac{\partial}{\partial x^2} (x^2 h_3 h_1) + \frac{\partial}{\partial x^3} (x^3 h_1 h_2) \right]$$

ON component of gradf.

$$\nabla^2 f = \text{div grad } f = \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial x^1} \left( \frac{h_2 h_3}{h_1} \frac{\partial f}{\partial x^1} \right) + \frac{\partial}{\partial x^2} \left( \frac{h_3 h_1}{h_2} \frac{\partial f}{\partial x^2} \right) + \frac{\partial}{\partial x^3} \left( \frac{h_1 h_2}{h_3} \frac{\partial f}{\partial x^3} \right) \right]$$

7.1-7.2

$$\begin{aligned} g &= dx \otimes dx + dy \otimes dy + dz \otimes dz \\ &= dp \otimes dp + p^2 d\phi \otimes d\phi + dz \otimes dz \quad h_1 = 1, h_2 = p, h_3 = 1 \\ &= dr \otimes dr + r^2 d\theta \otimes d\theta + r^2 \sin^2 \theta d\phi \otimes d\phi \quad h_1 = 1, h_2 = r, h_3 = r \sin \theta \end{aligned}$$

$$(\det g)^{1/2} = h_1 h_2 h_3 = p = r^2 \sin \theta$$

$$\nabla^2 f = \sum_{i=1}^3 (h_1 h_2 h_3)^{-1} \partial_i (h_1 h_2 h_3 h_i^{-2} \partial_i f)$$

$$= \underbrace{\frac{1}{p} \frac{\partial}{\partial p} \left( p \frac{\partial f}{\partial p} \right)}_{\frac{1}{p^2} \frac{\partial^2 f}{\partial \phi^2}} + \underbrace{\frac{1}{p} \frac{\partial}{\partial \phi} \left( p p^{-2} \frac{\partial f}{\partial \phi} \right)}_{\frac{\partial^2 f}{\partial \phi^2}} + \underbrace{\frac{1}{p} \frac{\partial}{\partial z} \left( p \frac{\partial f}{\partial z} \right)}_{\frac{\partial^2 f}{\partial z^2}}$$



$$= \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial r} \left( r^2 \sin \theta \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( r^2 \sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \phi} \left( r^2 \sin \theta \frac{\partial f}{\partial \phi} \right)$$

$$= \underbrace{\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial f}{\partial r} \right)}_{\frac{1}{r^2} \frac{\partial^2 f}{\partial r^2}} + \underbrace{\frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial f}{\partial \theta} \right)}_{\frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \theta^2}} + \underbrace{\frac{1}{r^2 \sin^2 \theta} \frac{\partial}{\partial \phi} \left( \frac{\partial f}{\partial \phi} \right)}_{\frac{\partial^2 f}{\partial \phi^2}}$$



$$\frac{\partial f}{\partial r} \equiv D_r f$$

$$= \dots = \frac{x \frac{\partial f}{\partial x} + y \frac{\partial f}{\partial y} + z \frac{\partial f}{\partial z}}{r}$$

$$= \hat{r} \cdot \vec{\nabla} f \quad \text{radial derivative}$$

$$\frac{1}{r^2} \left[ \underbrace{\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial f}{\partial \theta} \right)}_{\nabla^2 \text{ on unit sphere}} + \underbrace{\frac{1}{\sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}}_{\frac{\partial^2 f}{\partial \phi^2}} \right]$$

$\nabla^2$  on unit sphere

$$\equiv L^2 = L_1^2 + L_2^2 + L_3^2$$

square of angular momentum

$$L_3 = x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} = \frac{\partial}{\partial \phi}$$

$$\boxed{\nabla^2 = \underbrace{r^{-2} D_r (r^2 D_r)}_{\text{radial}} + \underbrace{r^{-2} L^2}_{\text{angular}}}$$

radial

angular

7.1-7.2

8

eigenfunctions

$$L_3 e^{im\phi} = \frac{\partial}{\partial \phi} e^{im\phi} = im e^{im\phi}$$

$$L_3^2 e^{im\phi} = -m^2 e^{im\phi}$$

$$Dr r^n = n r^{n-1}$$

$m$  integer or not  
continuous:

$$e^{im\pi/2} = e^{im(0)} = 1$$

(must be integer)  
 $\cos 2\pi m + i \sin 2\pi m$

$$\underbrace{r^{-2} Dr(r^2 Dr r^n)}_{= r^2(n r^{n+1})}, r = r^{-2} n(n+1) r^n$$

$$Dr(r^2 Dr r^n) = n(n+1) r^n \quad \text{eigenfunction}$$

Laplace's eqn

$$0 = \nabla^2 (r^n P_{em}(\theta) e^{im\phi}) \leftarrow \begin{cases} \text{sum of variables} \rightarrow \text{product} \\ \text{of eigenfunctions} \end{cases}$$

$$= [r^{-2} Dr(r^2 Dr) + r^{-2} L^2] r^n P_{em}(\theta) e^{im\phi}$$

$$= [r^{-2} n(n+1) + r^{-2} \underbrace{(-l(l+1))}_{= l(l+1)}] r^n P_{em}(\theta) e^{im\phi}$$

$$L^2 P_{em}(\theta) e^{im\phi} = \underbrace{\left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right]}_{= -m^2} P_{em}(\theta) e^{im\phi}$$

$$= [l(l+1) + m^2] P_{em}(\theta) e^{im\phi}$$

$$\underbrace{r^{-2} [n(n+1) - l(l+1)]}_{= 0} r^n P_{em}(\theta) e^{im\phi} Y_{em}(\theta, \phi)$$

$\leftarrow l = n, -(n+1)$

$$\underbrace{[-(n+1)][-(n+1)+1]}_{= n(n+1)} \leftarrow$$

gen soln:  $\sum_{n=0}^{\infty} \underbrace{(C_{nem} r^n + d_{nem} r^{n+1})}_{\text{radial dependence}} \underbrace{Y_{em}(\theta, \phi)}_{\text{angular dependence}}$

spherical harmonics