

osculating plane = vel-acc plane

$$\frac{ds}{dt} = |\vec{r}'(t)| = \text{speed}$$

$$ds = |\vec{r}'(t)| dt$$

$$s(t) = \int ds = \int |\vec{r}'(t)| dt$$

"invert" $t = t(s)$

$\vec{r}(t) \rightarrow \vec{r}(s)$ arclength parametrized

VERY SLOPPY
Valentine's Day

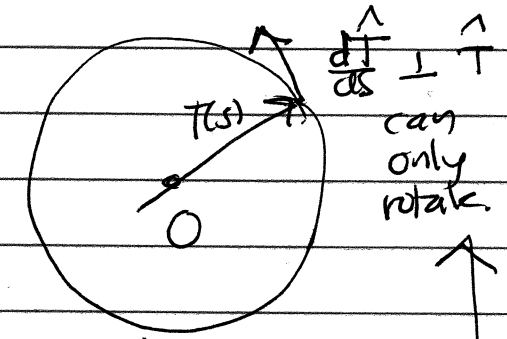
$$\frac{d\vec{r}(s)}{ds} = \frac{d\vec{r}/dt}{ds/dt} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \hat{T}(t)$$

unit speed parametrization

only geometry relevant - not how trace out curve.

$$\frac{d^2\vec{r}(s)}{ds^2} = \frac{d\hat{T}(s)}{ds} = \kappa(s)\hat{N}(s)$$

↑ direction
magnitude ≥ 0
"curvature"



$\hat{T}, \hat{N}, \hat{B}$
1 2 3 right handed ON basis.
 $\hat{B} = \hat{T} \times \hat{N}$
 $= \hat{T} \times \hat{N}$ etc.

$$\frac{d}{ds} (\hat{T} \cdot \hat{T} = 1)$$

$$\frac{d\hat{T}}{ds} \cdot \hat{T} + \hat{T} \cdot \frac{d\hat{T}}{ds} = 0$$

$$\hookrightarrow \hat{T} \cdot \frac{d\hat{T}}{ds} = 0$$

$$e'_a = e_b B^a_b(t) \leftarrow \text{rotation to new basis } (\hat{T}, \hat{N}, \hat{B}) = (e'_a)$$

$$e' = e B$$

$$e' = e B' = e B B^{-1} B'$$

$$= e' B^{-1} B'$$

antisymmetric (Lie algebra of rotation group)

antisymmetric

$$\left[\frac{d\hat{T}}{ds}, \frac{d\hat{N}}{ds}, \frac{d\hat{B}}{ds} \right] = [\hat{T} \hat{N} \hat{B}] \tilde{\omega}$$

antisymmetric matrix

$$= [\hat{T} \hat{N} \hat{B}] \begin{bmatrix} 0 & -\kappa & 0 \\ \kappa & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

A.3(2)

$$\frac{d\hat{N}}{ds} = -k\hat{T} + \tau\hat{B} \leftarrow (\text{must be } \perp \hat{B}!) \quad \text{"torsion"}$$

$$\begin{bmatrix} \frac{dT}{ds} \\ \frac{dN}{ds} \\ \frac{dB}{ds} \end{bmatrix} = (T N B) \begin{bmatrix} 0 & -k & 0 \\ k & 0 & -\tau \\ 0 & \tau & 0 \end{bmatrix}$$

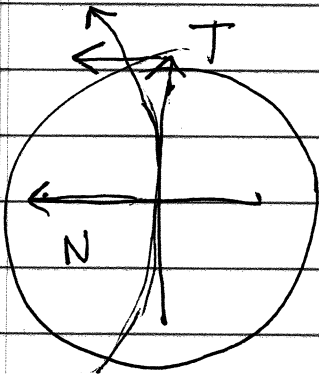
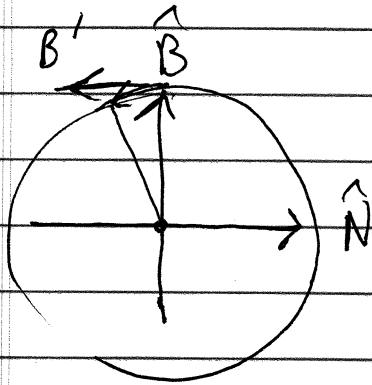
↓

$$\frac{dB}{ds} = -\tau\hat{N}$$

normal to osc plane rotates if $\tau \neq 0$

↔ nonplanar curve

$\tau = 0$, \hat{B} fixed motion takes place in fixed plane.



$$\frac{dT}{ds} = k\hat{N}$$

←

A.3 | 3

circle:

$$\vec{r} = a \langle \cos t, \sin t \rangle$$

$$= a (\cos t \hat{i} + \sin t \hat{j})$$

$$\vec{r}' = a \langle -\sin t, \cos t \rangle$$

$$+ \vec{0}$$

$$|\vec{r}'| = a = \frac{ds}{dt} \rightarrow s = \int a dt = at + c \rightarrow 0$$

↑ center

$$t = \frac{s}{a}$$

$$\frac{dt}{ds} = \frac{1}{a}$$

$$\frac{d\theta}{ds} = \frac{1}{a} = k$$

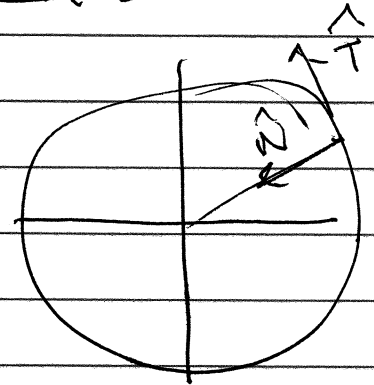
$$\vec{r} \in a \langle \cos \frac{s}{a}, \sin \frac{s}{a} \rangle$$

~~$$= a \langle \cos$$~~

$$\frac{d\vec{r}}{ds} = a \langle -\sin \frac{s}{a}, \cos \frac{s}{a} \rangle = \hat{T}$$

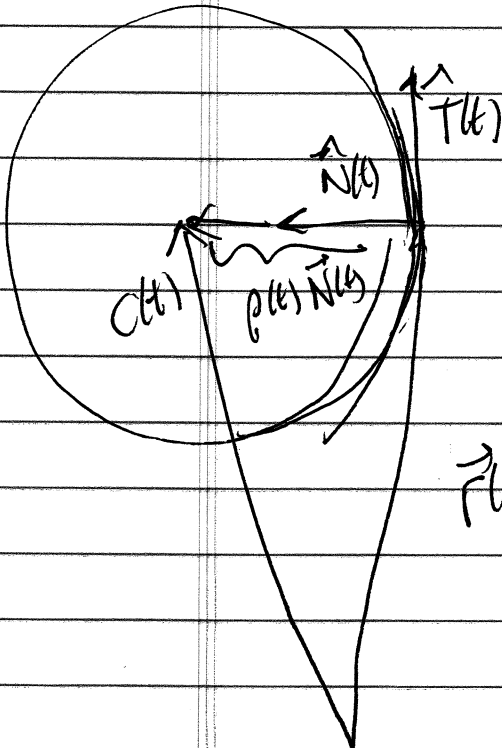
$$\frac{d^2\vec{r}}{ds^2} = \frac{d\hat{T}}{ds} = \frac{1}{a} \langle -\cos \frac{s}{a}, -\sin \frac{s}{a} \rangle$$

$$\underbrace{\frac{1}{a}}_k \langle \underbrace{-\cos \frac{s}{a}}_{\hat{N}_x}, \underbrace{-\sin \frac{s}{a}}_{\hat{N}_y} \rangle = \hat{N}$$



$$k = \frac{1}{a} \text{ for circle.} = \text{curvature}$$

$k(s) \equiv 1/\rho(s) \rightarrow \rho(s)$ radius of curvature for equivalent circle



$$\vec{r} = \vec{0} + a (\cos t \hat{i} + \sin t \hat{j})$$

↓

$$\vec{r}(t, \theta) = C(t) + \rho(t) (\cos \theta (-\hat{N}) + \sin \theta \hat{T})$$

∥

$$\vec{r}(t) + \rho(t) \hat{N}(t) \quad \text{center} \quad \theta = 0$$

$$\vec{r}(t, 0) = \vec{r}(t) \text{ pt of tangency.}$$

osc circle at $\vec{r}(t)$

circle of best fit

A.31

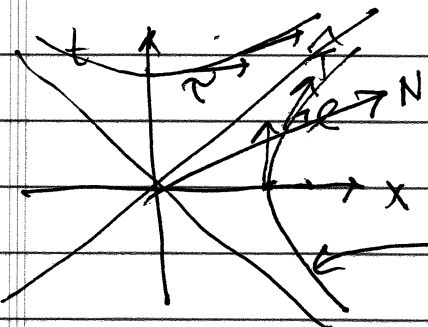
4. Everything we did can be repeated for any inner product \rightarrow spacetime

$$G = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \text{ or submatrix } n=2,3,4 \text{ dimension.}$$

n=2 Lorentz plane.

$\pm s^2 = -t^2 + x^2 > 0 \rightarrow \mathcal{L}^2$ proper distances

$< 0 \rightarrow -\tau^2$ proper time τ .



pseudo-circles centered at origin

timelike curve tangent "timelike"

$$\vec{r} = l \begin{pmatrix} \sinh \alpha \\ \cosh \alpha \end{pmatrix} \quad \vec{r}(0) = \langle 0, l \rangle$$

$t \quad x$

$$\vec{r}' = l \langle \cosh \alpha, \sinh \alpha \rangle$$

$$|\vec{r}'|^2 = l^2 (-\cosh^2 \alpha + \sinh^2 \alpha) = -l^2 \quad |r'| = l = \frac{dr}{d\alpha}$$

$$\hat{r} = \left\langle \cosh \frac{\alpha}{l}, \sinh \frac{\alpha}{l} \right\rangle$$

$$dr = l d\alpha$$

$$\tau = l\alpha$$

$$\frac{d\hat{r}}{d\tau} = \frac{1}{l} \left\langle \sinh \frac{\alpha}{l}, \cosh \frac{\alpha}{l} \right\rangle$$

$$\alpha = \frac{\tau}{l}$$

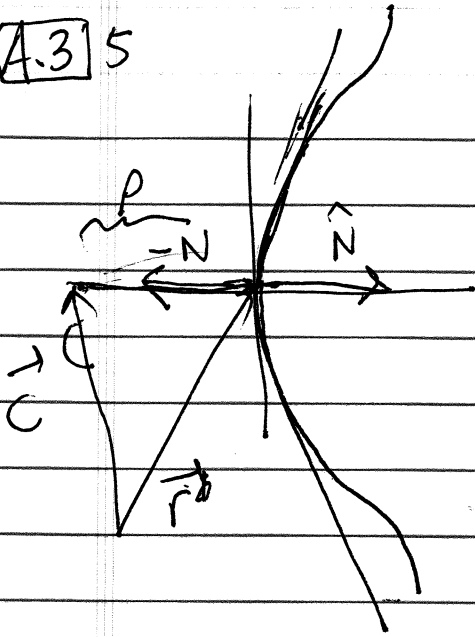
$(-s^2 + c^2) = 1$ spacelike unit vector

$$K = \frac{1}{l} \quad \hat{N}$$

pseudoradius = $1/K$. but center at origin is distance l along $-\hat{N}$.

$$\vec{r} = \vec{0} + l (\sinh \alpha \hat{j} + \cosh \alpha \hat{i})$$

A.3.5



$$\vec{r}(t) = \vec{C}(t) + \rho(t) \hat{N}(t)$$

$$\vec{r} = \vec{C} + \rho (\sinh \beta \hat{T} + \cosh \beta \hat{N}) \quad \text{pseudo curve}$$

$$\vec{r}(t, \beta) = \vec{C}(t) + \rho(t) (\sinh \beta \hat{T} + \cosh \beta \hat{N})$$

$$\begin{aligned} \vec{r}(t, 0) &= \vec{C}(t) + \rho(-\hat{N}(t)) + \rho(t) \hat{N}(t) \\ &= \vec{r}(t) \end{aligned}$$