

Damped Harmonic Oscillator Driven by Sinusoidal Driving Function: Special Cases

BEATING: drive undamped system ($\kappa_0=0$) near the natural frequency: $\omega \approx \omega_0$

Take initial conditions $y(0) = 0 = y'(0)$ (nothing happening at $t=0$)

The general formula reduces to

$$y = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t + \frac{B_0}{\omega_0^2 - \omega^2} \cos \omega t$$

$$y' = -c_1 \omega_0 \sin \omega_0 t + c_2 \omega_0 \cos \omega_0 t - \frac{B_0 \omega}{\omega_0^2 - \omega^2}$$

$$y(0) = c_1 + \frac{B_0}{\omega_0^2 - \omega^2} = 0 \rightarrow c_1 = -\frac{B_0}{\omega_0^2 - \omega^2}$$

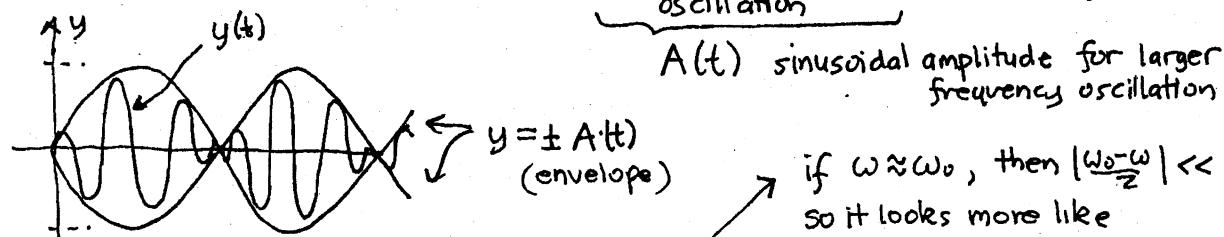
$$y'(0) = c_2 \omega_0 = 0 \rightarrow c_2 = 0$$

$$y = \frac{B_0}{\omega_0^2 - \omega^2} (\cos \omega_0 t + \cos \omega t) = \left[\frac{+2B_0}{\omega_0^2 - \omega^2} \sin \left(\frac{\omega_0 - \omega}{2} t \right) \right] \sin \left(\frac{\omega_0 + \omega}{2} t \right)$$

trig difference identity

smaller frequency, larger period of oscillation

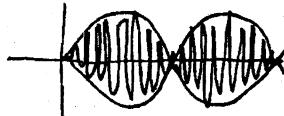
larger frequency, smaller period of oscillation



$$T = \frac{2\pi}{|\omega_0 - \omega|}$$

beating is the constructive/destructive interference of two sinusoidal signals/waves with nearly the same frequency and intensity (take 2 tuning forks for nearby musical notes)

if $\omega \approx \omega_0$, then $|\frac{\omega_0 - \omega}{2}| \ll \frac{\omega_0 + \omega}{2}$
so it looks more like



RESONANCE: if $\kappa_0=0$ (no damping) the above formulas are not valid for $\omega=\omega_0$ so driving the undamped system at its natural frequency must be handled separately.

$$(D^2 + \omega_0^2)y = B_0 \cos \omega_0 t \quad \leftarrow (D^2 + \omega_0^2)(B_0 \cos \omega_0 t) = 0 \quad \text{same roots } r = \pm i\omega_0$$

$$(D^2 + \omega_0^2)^2 y = 0 \quad y = (c_1 + c_2 t) \cos \omega_0 t + (c_3 + c_4 t) \sin \omega_0 t \quad \begin{matrix} \text{(multiplicity 2)} \\ \text{(need linear function coefficients)} \end{matrix}$$

$$(r^2 + \omega_0^2)^2 = 0 \rightarrow r = \pm i\omega_0 \quad = (c_1 \cos \omega_0 t + c_2 \sin \omega_0 t) + t(c_3 \cos \omega_0 t + c_4 \sin \omega_0 t)$$

$$y_h \quad (\text{fixed amplitude}) \quad y_p \quad (\text{growing amplitude})$$

$$\omega_0^2 [y_p = t(c_3 \cos \omega_0 t + c_4 \sin \omega_0 t)]$$

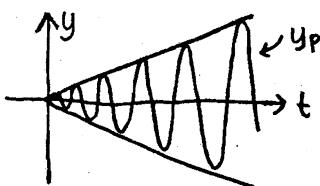
$$0 [Dy_p = t(-c_3 \omega_0 \sin \omega_0 t + c_4 \omega_0 \cos \omega_0 t) + (c_3 \cos \omega_0 t + c_4 \sin \omega_0 t)]$$

$$1 [D^2 y_p = t(-c_3 \omega_0^2 \cos \omega_0 t - c_4 \omega_0^2 \sin \omega_0 t) + 2(-c_3 \omega_0 \sin \omega_0 t + c_4 \omega_0 \cos \omega_0 t)]$$

$$D^2 y_p + \omega_0^2 y_p = t(0) + 2(-c_3 \omega_0 \sin \omega_0 t + c_4 \omega_0 \cos \omega_0 t) = B_0 \cos \omega_0 t$$

90° out of phase

$$\therefore -2c_3 \omega_0 = 0 \rightarrow c_3 = 0 \quad \left. \begin{matrix} 2c_4 \omega_0 = B_0 \rightarrow c_4 = B_0 / (2\omega_0) \end{matrix} \right\} y_p = \left(\frac{B_0 t}{2\omega_0} \right) \sin \omega_0 t = A(t) \cos(\omega_0 t - \frac{\pi}{2}) \quad [y_p \text{ in phase with } f(t)]$$



$$A(t) = \frac{B_0 t}{2\omega_0} \quad \text{linearly increasing amplitude}$$

oscillation grows until model breaks down
(no damping assumption no longer justified, etc)